

IFS NO. 2010051/ 72903 A 15/02/2023 1 (115)



Cabinets e-RTU2020-2S and e-RTU2020-4S

Installation and operating guide



4PR-F14-D

Ensto Novexia SAS 210 rue Léon Jouhaux BP 10446 69656 Villefranche-sur-Saône Cedex, France





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General

- Before unpacking

- > Verify that the product in its packaging has not been damaged during transport.
- > Verify that the product is suitable for the intended installation.

- Before installation

> Carefully read this guide before installing or using this product.

> While carrying out the installation, ensure that the equipment remains clean throughout the operation.

- After installation

- > If you are installing this product for someone else, leave the guide for the end user.
- > Clean the work area after installation.

Legal notices

- The product may only be installed by a competent person with adequate training in installation practices and with adequate knowledge of proper safety and installation practices for electrical equipment. If local regulations have requirements relating to this training or adequate knowledge in terms of the installation of electrical equipment, the aforementioned requirements must be complied with by this person.

- Ensto Novexia declines all liability for any property damage or personal injury caused by poor installation, mishandling, or failure to comply with safety recommendations.

WARNING

For the operation of this system in complete safety, it is essential that installers, users and technicians follow the procedures and precautions described in this guide. Non-compliance with these instructions may cause damage to the products and/or serious or even fatal injury.





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1 PRESENTATION

- 1.1. Product purpose
- 1.2. General characteristics
- 1.3. Mechanical specifications
 - 1.4. List of equipment required for installation (not supplied by Ensto Novexia)

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1.1 PRODUCT PURPOSE

The e-RTU2020-2S & e-RTU2020-4S versions combine all the functions required to manage a MV sub-station in a compact unit. Combining the equipment with MV circuit breakers makes the electrical network more reliable.

1.2 GENERAL CHARACTERISTICS

1.2.1 General

The product enables instrumentation and control of 2 (e-RTU2020-2S) or 4 (e-RTU2020-4S) motorised circuit breakers. In addition, it is equipped with functions for remote communication, acquisition of analogue values, fault detection and automated system.

The parameters below can be viewed and/or programmed either on the local panel on the front of the e-RTU2020 cabinet, or on a PC. For additional details, see § 4.2.

• <u>Remote communication with the control station (Scada):</u>

By default, the cabinet incorporates the standard protocols for communication with control stations (IEC 104/101, DNP3 IP/serial, MODBUS RTU/IP, etc.)

With its 3 Ethernet ports and 2 UARTs, the e-RTU2020 enables all modern communication media (IP or serial) to be used with the control station – SCADA – (XG modem, ADSL or fibre optic routers, IP radio, digital radio, etc.)

It enables several media to be used simultaneously (communication redundancy)

• Control of MV circuit breakers:

In remote or local mode, it is possible to independently operate 1 to 4 motorised MV circuit breakers. In addition, the operation of circuit breakers can be controlled by automated systems (ASF or APSS). The position of circuit breakers is accessible locally via the user (UI) and PC interfaces.







• Acquisition of analogue values:

The cabinets measure the following MV network values:

- o Measurement of instantaneous currents for all channels
- o Calculation of current averaged for all channels over X minutes (configurable value)
- $\circ\,$ Saving of maximum instantaneous current for all channels
- $\circ~$ Measurement of instantaneous MV voltage
- o Calculation of MV voltage averaged over X minutes (configurable value)
- o Cyclic measurement recording in a file (configurable measurements and frequency)

The product measures the following information in real time:

- LV supply voltage
- \circ Voltage and current relating to the 12 V internal and 12 V radio power supply
- Voltage and current of the 48 V voltage source
- o Internal temperature of the cabinet
- o External temperature (PT100) for external T° or transformer measurement
- Measurement originating from a 4-20 mA or 0-10 V external sensor for measuring the water level, SF6 pressure, etc.

• Visualisation of the cabinet status and information relating to the MV network:

The following information is displayed on the front panel of the product or on the PC:

- Position of the MV switch
- Switch status (neutralised manual mode or unlocked)
- Number of operations per channel
- $\,\circ\,$ Cabinet 12V, 48V voltage and supply voltage out of range
- o Battery fault
- o Internal fault
- o Local or remote modes
- o Automated system (ASF & APSS) status
- Date and time

• Detection of MV faults:

Overcurrent on 2 to 4 channels: single-phase fault, double faults, poly-phase faults, in accordance with specification **"HN 45-S-50" of February 2011**

Directional on 2 to 4 channels: red single-phase fault, green single-phase fault, poly-phase fault in

accordance with specification "HN 45-S-51" of February 2011

Fault counters: Polyphase / double & single-pole

Fault indication on the user interface depending on the type of detection (see §4.2)





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<u>Automated systems:</u>

Auto-Sectionalising Function (ASF) equating to opening the MV switch in the event of a downstream fault during the source unit resetting cycles.

Automatic Power Supply Switching (APSS) allowing a voltage source that has become inactive to be swapped for an active voltage source

• Recording of Dated Events (RDE):

All the cabinet events (opening, fault detection, etc.) can be consulted or downloaded in .csv format using the PC interface (DRME).

The .csv files can be directly exported into excel

• Power supplies:

AC voltage 230 V \pm 15 % (originating from the MV 20 kV network) or 172.5 V \pm 15 % (originating from the MV 15 kV network) Sealed lead battery 12 V 38 Ah (autonomous supply).

Possible compatibility with other network voltages (on request)





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1.2.2 Overview of the product:

The e-RTU2020 cabinet is divided into several sub-assemblies accessible at different access levels





- 1. Cabinet metal enclosure
- 2. Space reserved for communication equipment (XG modem, Radio, IP router, etc.)
- 3. Card rack containing the LV transformer, the power supplies, the CPU and the modem card.
- 4. User interface (UI)
- 5. Line and fault current acquisition modules
- 6. Wiring board (contains the current acquisition modules, external inputs/outputs and the residual MV voltage measuring unit)
- 7. 12 V battery (autonomous supply)
- 8. Connection space for alternative power supply
- 9. Radio interface: Radio antenna connection area
- 10. Connection area for the electrical control interface connectors (1 to 4 channels)
- 11. Lower door
- 12. Upper door





1.2.3 Description of the card rack:

The rack comprises 6 functional units highlighted in the diagram below:





- 1- Product power supply transformer.
- 2- 48 V voltage module: Provides the power needed for motorised operation of the circuit breakers
- 3- 12 V voltage module: Charges the battery and provides the cabinet's internal and external power supply.
 The module also has automatic protection for the battery and loads (internal and external).
- 4- CPU2020 module: Supervises all equipment.
- 5- Motherboard: positioned on the back panel, provides the interface for the equipment's internal and external connections (cards, cables, etc.).
- 6- User interface: Allows the user to exchange information with the product (display and/or adjustment of certain cabinet parameters).







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1.2.4 Description of the user interface (UI):

The user interface is available in the cabinet at access level 1. It allows the user to configure and/or display certain equipment parameters.



- 1. **Display/navigation button module:** Display and/or configuration of product information.
- 2. Remote control button: Selects local or remote mode.
- 3. Equipment test button: Lights up all of the lights to check their proper operation.
- 4. ASF button: Turns the automated systems (ASF) on/off.
- 5. Command validation button: Use in parallel with the open/close & ASF buttons
- 6. Open button: Controls opening of the selected channel
- 7. Close button: Controls closing of the selected channel
- 8. Channel selection buttons: Selects the channel to be controlled
- 9. APSS button: Turns the automated systems (ASF & APSS) on/off.
- 10. Source button: Selects the automatic switching direction (APSS)
- 11. Local indicator light: Local mode active if lit
- 12. MV fault indicator lights: Image of green and red MV fault single remote signals
- 13. **Position indicator lights:** Position (open, closed or invalid) of the circuit breaker connected to the channel
- 14. **Neutralisation light**: The flashing light indicates neutralisation of the circuit breaker connected to the channel
- 15. Cabinet status indicator lights

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- Equipment on standby: flashing green indicates normal operation of the cabinet
- Equipment fault: Lit up red indicates a fault. Refer to the following LEDs
- No 48 V DC: indicates a lack of 48 V voltage
- No 12 V DC: indicates a lack of 12 V voltage
- No AC voltage: indicates a lack of AC power supply voltage
- External load outage: Indicates that the power supplies for external loads are cut off
- Battery fault: Indicates a battery fault
- Internal fault (connect the PC to analyse the fault)
- 16. 12 V power supply indicator light: Lit if the cabinet is supplied with power
- 17. Communication indicator lights: Indicates the traffic present on the communication device.
- 18. ETHERNET Configuration Port: Provides access to the PC interface.

Address 192.168.10.1 (static)

19. ETHERNET Extension Port: Allows external equipment or a second IP communication medium to be connected.

Address 220.220.0.1 (modifiable)

20. **ETHERNET Communication Port (on the back of the CPU):** Allows an IP communication medium to be connected. The Ethernet cable is offset towards the area reserved for communication media (see §1.2.2).

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Address 192.168.0.1 (modifiable)

- 21. Reset button: Peripheral reset, SPI fault reset, charger fault reset
- 22. I/O connector: Temperature measurement (PT100), 4-20 mA / 0-10 V sensor, user inputs and outputs (dry contacts)

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Wiring:

PT100 (red)		
PT100 (white) / 0 V		
Common 0 V		
Common 0 V		
Common 0 V		
Common 0 V		
Common 0 V		
Common 0 V		
NC (Isolation)		
RELAY1 (CONTACT1)		
RELAY2 (CONTACT1)		
RELAY3 (CONTACT1)		

PT100 (red) 4-20 mA / 0-10 V analogue input Digital input 1 Digital input 2 Digital input 3 Digital input 4 Digital input 5 +12 V NC (Isolation) RELAY1 (CONTACT2) RELAY2 (CONTACT2) RELAY3 (CONTACT2)

The user Input and Output Labels are fully configurable by means of software





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1.2.5 Description of the wiring board

The wiring board supports the current acquisition modules. It allows the circuit breakers to be operated, the residual MV voltage to be measured, the MV presence to be provided and external inputs/outputs to be controlled (urgent fault, switching in progress, etc.).

The MV voltage sensors must be connected directly to it and the current sensors to the related current acquisition module (channels A to D).



NB.: Channels C & D are only present for type 4S.

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1.2.6 Access levels:

The cabinet has three access levels defined as follows:

Level 0: On: The cabinet is closed and the user interface is visible but inaccessible. The upper part of the cabinet is padlocked (not supplied by Novexia).







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Level 1: Operation: access for operating personnel. Only the user interface (UI) is accessible. The upper part is locked using two seals.

At this level, it is possible to operate the circuit breakers locally, view the status of the cabinet and connect the configuration PC.



Level 2: Maintenance:

To open the cabinet, release the

upper door by raising it then slide

it into the upper section.

access for maintenance technicians (complete accessibility).

At this level, it is possible to work on each element of the cabinet (electronic circuit boards, battery, cables, etc.) to carry out maintenance or troubleshooting operations.

To release the lower door, pull the lower door towards you. It is possible to remove this door for improved access to the battery and to facilitate wiring



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1.3 MECHANICAL SPECIFICATIONS

1.3.1 Characteristics:

Dimensions	$H \times W \times D$	650 mm × 310 mm × 330 mm
Dimensions with door open	$H \times W \times D$	650 mm × 310 mm × 600 mm
Weight		38 kg
Enclosure		Galvanised steel
materials		
1 mm-		
thick galvanised sheet		
Protection rating		IP2XC for access level 0 and IP2X for access
		level 1
Mechanical impacts		IK10
Mechanical vibration	In accordance with NF	(10Hz to 500Hz 2g or 0.15mm peak-to-peak)
	EN 60068-2-6	
Resistance to saline mist	NF EN 60068-2-11	Exposure 178 h
Earthquake resistance	NF 60255-21-3	Class 2
Operating temperature		-15°C to +55°C
Storage temperature		-25°C to +70°C

The mounting plate has four holes with a diameter of 12 mm, spaced at 250 mm × 630 mm, allowing it to be mounted.

1.3.2 Rating plate:

An easy to read external plate allows the cabinet to be identified.

It contains the following details (e.g. cabinet e-RTU2020-4S + 4 detectors)

- Ensto product code
- The product's date of manufacture Year Week
- Serial number
- Compliant with HN 64-S-44 Version F dated March 2012
- Type of equipment: e-RTU2020
- Commercial name: e-RTU2020-2S or e-RTU2020-4S





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1.3.3 Identification of electronic circuit boards:

Each electronic circuit board is identified by a serial number and its type. The information for each board (serial number and type) appear on a plate inside the lower door.

Example:

2009725 CABINET e-RTU2020 Underground: e-RTU2020-4S No. 00106					
Board Name	Novexia code	Serial no.	Board Name	Novexia code	Serial no.
CPU2020 board PR236 V1.0 PR241 V1.0	2009612-14		Wiring board PR167 V1.3	2005412-14	
Converter board	2004995-08		current acquisition PR149 V1.2	2005158-08	
Charger card PR142 V1.2	2004993-08		current acquisition PR149 V1.2	2005158-08	
Motherboard	2005023-08		current acquisition PR149 V1.2	2005158-08	
4 channel display board: PR144 V1.2	2005009-04		current acquisition PR149 V1.2	2005158-08	
Novexia at	iter-sales s	ervice: +	33 (0)6 16 66 46 4	3 / +33 (0)6 0	8 93 26
31					

1.4 LIST OF EQUIPMENT REQUIRED FOR INSTALLATION (SUPPLIED DEPENDING ON ORDER)

1.4.1 Battery:

The batteries used in operation meet the following criteria:

- Stationary lead, sealed type with valve according to NF EN 60696-21 and 22
- Maximum dimensions: 195mm x 160mm x 170mm
- Initial capacity: 38 Ah
- Connection via type M5 insulated threaded ring terminals

Note: The cable connecting the battery to the equipment and the retaining strap are included in the product's bag of accessories.







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If there is no LV voltage, the battery enables power to be supplied to the cabinet. In addition, the battery provides the power required to motorise the circuit breakers during an operation.



Only batteries approved by ENSTO Novexia can be used.

1.4.2 Current sensors and connecting cable:

The 500/1 ratio sensors take instantaneous measurements of the three MV line currents to detect faults and to acquire the analogue values.



Only current coils and connecting cables approved by Ensto Novexia may be used.

The current coils used have the characteristics listed below:

- Compliant with standard NF EN 60044-1
- Power: 1.5 VA
- Precision class: 3
- Rated load: 1.5 Ohm
- Primary rated current: 500 A
- Secondary rated current: 1 A
- Rated transformation ratio: 500/1
- Rated usable frequency: 50 Hz to 500 Hz
- Rated thermal short-circuit current: 12500 A for 1 sec
- Secondary dielectric strength: 4 kV 50 Hz 1 minute in common mode 5 kV 1.2/50 μs in common and differential mode

Connecting cable specifications:

- Copper cross section: $\geq 1.5 \text{ mm}^2$
- Number of conductors: 4
- Cable type: U-1000 R 02V
- Length: 2, 5, 10 or 15 m
- Connector type: MATE N LOCK 2

1.4.3 Capacitive voltage sensors and connecting cable (if directional detection):

The transducers measure the individual MV voltages to detect directional faults and the presence of voltage.



Only PPACS connectors and connecting cables approved by Ensto Novexia may be used.



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The PPACS installed comply with specification HN 52-S-63.

Connecting cable specifications:

- Number of conductors: 4
- Length: 7 or 12 m
- Connector type: HARTING (Han Q5/0)

Calibration of the voltage acquisition module allows for the acknowledgement of head capacitors with capacities of between 0.7 pF and 3.3 pF for MV voltages of between 15 kV and 20 kV. The sampling method is described in §3.2.

The e-RTU2020 cabinet has the option of being connected to the secondary windings of MV/100 V voltage transformers.



To do this, you need to use suitable wire cutters to cut away the 3 standard resistors at the bottom right of the wiring board. Therefore, the calibration method is identical to that described above and presented in §3.2.

Take care not to damage the electronic circuit board when performing this operation. For increased safety and convenience, it may be necessary to remove the electronic circuit board to perform this operation.

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1.4.4 Radio antenna and holder (only useful for the RADIO version):

Install a compliant communications antenna.



1.4.5 Cabinet mounting element:

The equipment is attached using 4 type M10 screws for good mechanical adhesion to the wall (not supplied by Novexia).

1.4.6 PC:

A PC is needed to commission the cabinet.

The PC used must use an OS no earlier than Windows 7, an Ethernet connection and a standard web browser (Microsoft Edge, Mozilla FireFox, Google Chrome, etc.).

1.4.7 Ethernet Cable:

An RJ45 straight Ethernet cable (standard, commercially available cable) is required to connect the PC to the cabinet (not supplied with the cabinet).

1.4.8 Tools:

Only standard tools are required to install the product:

- Flat screwdriver for the screw connectors
- Philips (cross-head) screwdriver for positioning the Harting connector
- Flat spanners (13) to secure the cabinet to its rail

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2 INSTALLATION

- 2.1. Unpacking and handling instructions
- 2.2. Installation operations
- 2.3. External connections
- 2.4. Earthing instructions





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2.1 UNPACKING AND HANDLING INSTRUCTIONS

On receipt of the cabinet, check that the equipment matches the product requested. An identification label is fixed to the outside of the packaging.

Check the contents of the package against the order

- Cabinet

- Bag of accessories containing
 - Battery strap
 - Battery cable
 - Replacement fuses: 12 V internal (Radio) and 48 V
 - Installation and operating guide
 - Battery installation guide

It is preferable to assign two people to the product installation task.

allation task.



No specific tools are needed to open the packaging.

Store the cabinet indoors at a temperature between -25°C and +70°C

2.2 INSTALLATION OPERATIONS

Four steps are needed to attach the cabinet to the rail:

Step 1: Drill four holes in the wall in accordance with the mounting distances.



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Step 2: Place the wall plugs in the holes in the wall.

- **Step 3:** Position the cabinet so that the holes in the wall are facing the mounting holes.
- Step 4: Attach the cabinet using four type M10 screws.



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2.3 EXTERNAL CONNECTIONS

2.3.1 Identification of grommets and connectors:

The purpose of these assembly drawings is to facilitate connection of the external elements to the product (battery, current sensor, communications, etc.).



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- 1- Radio antenna interface (for Radio versions)
- 2- Current sensor channel A connecting cable grommet
- 3- Current sensor channel B connecting cable grommet
- 4- Current sensor channel C connecting cable grommet
- 5- Current sensor channel D connecting cable grommet
- 6-230 V power supply cable grommet
- 7- Communication cable grommet
- 8- Voltage sensor connecting cable grommet
- 9- Grommets for external single remote signalling, switching in progress, reserved connections, etc.





Note: For the e-RTU2020-2S version only two "HARTING" type connectors and two current acquisition modules are installed on the product.

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2.3.2 Connections:

To facilitate the connection of external elements, refer to § 2.3 "Identification of grommets and connectors".

a) Cabinet power supply

The cabinet being at access level 2, remove the power supply fuse.

Then insert the power supply connection cable into the dedicated grommet.

To complete this operation, connect the cable to the **power supply connector** (neutral on the left & phase on the right).

Place the fuse back in its housing without closing the fuse holder



U1000 R2V Power supply cable

b) Transmission via communication (IP router, RADIO – GSM/GPRS – external RTU, etc.)

Note: The data cable and the radio power supply cable are pre-connected in the factory depending on the type of communication base required. 1- Pull out the metal communication drawer.

2- Attach the communication system to the base.



3- Connect the equipment **power supply** cable to the connector provided.

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4- The data cable (serial protocols) is already connected to the 25-pin connector on the motherboard. If this cable is not suitable for your communication equipment, you can modify it in line with the following diagram.

>>>>> 9-pin female DATA cable or 9-pin male DATA cable depending on the circumstances.





For an IP base, the Ethernet cable is pre-connected to the Ethernet Communication port (Eth0) on the CPU2020 board.

5- Connect the radio or the XG modem to the antenna connector

6- Put the drawer back in place.

To complete mounting, connect the radio antenna interface to the communications antenna.

c) Current sensors (coils):

The installation method for current sensors is similar for all channels (A to D).

Insert the coil connection cable through the specific grommet for the channel. Fasten the green connector on the current acquisition module to the end of the coil connection cable while clearly respecting the position of the blue wire (on the right)



Connect the connector to the current board. Tighten the grommet



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Position the three current coils on the MV feed (400A socket) with the green side of each coil on the circuit breaker side.

This is absolutely vital to achieve proper delivery of the single-pole current.

 When replacing a box on the work place it is mandatory to put tors version 2012 and new connecting cables
 Image: Connecting cables

 Green side
 Red side

 Blue thread
 Référence du poste

Connect all the sensor Earth connections (blue wire fitted with a ring terminal) to the unit Earthing point. The Earth braid of the MV cable shield must pass inside the coils

Connect the three coil connectors to those on the connecting cable





The connection of live coils can be dangerous, consequently <u>it is absolutely essential</u> that the coil connecting cables are connected to the cabinet before they are connected to the coils.

Once this wiring has been created, it is possible to remove this live connector, specifically in order to conduct fault seeding tests using the standard tool

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(DED)

d) Voltage sensors (capacitive divider if directional detection):

The voltage sensors must only be installed if the cabinet is configured for directional fault detection (DFD).

Connect the three PPACSs to the 400 A sockets.

Connect the Earth connection (green/yellow wire fitted with a ring terminal) to the unit Earthing point





Insert the PPACS connecting cable through the grommet designed for this purpose. Screw the green connector on the wiring board onto the end of the



PPACS connecting cable, making sure you respect the position of the blue wire.

Connect the connector to the wiring board (bottom right).

Tighten the grommet



blue wire on the right

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Connect the PPACS connector to that on the connecting cable.



e) External signalling connector (on the wiring board):

It combines external remote signalling (reserved connection) and the "switching in progress" floating potential contact.

The reserved connection labels can be fully customised by software.

Identification of the pins of the external connector:



Pin no.	Function
1	Reserve 1
2	Reserve 2
3	Lock switching / Reserve 5
4	0 V
5	NC
6	Switching in progress + contact
7	Switching in progress - contact
8	Reserve 3
9	Reserve 4
10	0 V
11	Common indicator light (+)
12	Red indicator light (-)
13	Common indicator light (+)
14	Green light (-)

The dry contact inputs must be wired between the input for the desired signal (e.g. Water level on Reserve 3) and a 0 V input (representation of external contact wiring above).

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External indicator light wiring

Dual-colour light (Green/Red):



Single-colour light (Red):



f) Electrical control of circuit breakers:

The method for connecting electrical control "HARTING" connectors is identical for all channels. Each channel is positioned in production.



Trunnion

Pin no.	Function
1	0 V (- 48 V)
2	Close command
3	Open command
4	Open position
5	Closed position
6	+ 48 V
7	Neutralised control
o	MV power supply circuit breaker
0	presence/absence
9	Use reserved
10	Use reserved





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De-rompage of connectors and header Han-10 A (contact pin side view)

	command binding	
Command male connector	Channel A Channel B Channel C Channel D	
ITI female header		

Once the electrical control interface connector is attached to the cabinet, lock it.



g) MV voltage selection:



The MV voltage can only be selected by programming using the PC software (see §4.2)

2.4 EARTHING INSTRUCTIONS

Loosen the earth M8 stud bolt nut.

Remove the two washers (flat and locking).

Place the **ring terminal connected to the equipment Earth** on the bolt.



Place the two washers on the bolt and secure it all in place using the nut.

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3 COMMISSIONING

- 3.1. Points to be checked before commissioning
- 3.2. List of commissioning operations
- 3.3. Operational tests

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3.1 POINTS TO BE CHECKED BEFORE COMMISSIONING

3.1.1 Visual inspection

Check the product by means of a simple visual inspection (cabinet and user interface with no impact).

Check the battery charge status in accordance with the supplier's options.

3.1.2 Setting up the configuration PC

The equipment is configured during this phase. To do this, it is necessary to use a computer with an Ethernet connection and a standard web browser (Microsoft Edge, Mozilla FireFox, Google Chrome, etc.).

First, it is necessary to establish the connection between the equipment and the embedded software.

<u>Note</u>: The PC used must have at least Windows 7, an Ethernet connection and a standard web browser (Microsoft Edge, Mozilla FireFox, Google Chrome, etc.).

Changing an IP address on a PC

The connection to new e-RTU2020 cabinets is established via an Ethernet port and uses the IP protocol.

For this to work, it is therefore essential to provide the configuration PC with an IP address which matches that of the cabinet.

The cabinet configuration IP address is common to all of our products and is as follows:

- IP address: 192.168.10.1
- Subnet mask: 255.255.255.0

The configuration PC address must be:

- IP address: from 192.168.10.2 (or up to 192.168.10.254)
- Subnet mask: 255.255.255.0





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This operation only needs to be performed once on the same PC to connect to all the cabinets.

Note: The CPU2020 board includes a DHCP server (disabled by default). Refer to guide 72868 – System configuration guide for cabinet e-RTU 2020

It is essential to have administrator rights in order to change the IP addresses of a PC.

Note: Following configuration, if this PC needs to be connected to one or more different networks, it is necessary to change its IP address in order to bring it into line with the network addressing principles (static IP, DHCP).

The method for changing the PC IP addresses in different PC operating environments is detailed below



Change your network settings

Æ

Change adapter options

View network adapters and change connection settings.



Sharing options

Windows 10

For the networks you connect to, decide what you want to share.



Network troubleshooter

Diagnose and fix network problems.

View your network properties

Select "Network and sharing centre"

Right-click the network icon in the

Select "Open Network and Sharing

menu bar to the right.

centre"

Windows Firewall

Network and Sharing Center

Network reset

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Control Panel Home

Change adapter settings

Change advanced sharing settings

Media streaming options

Ethernet 7 Rés 📢 Disable ASI Status Diagnose 🐶 Bridge Connections Create Shortcut 🔛 Delete Rename Properties (2) Ethernet 7 Properties X Networking Authentication Sharing Connect using: ASIX AX88179 USB 3.0 to Gigabit Ethemet Adapter #3 Configure ... This connection uses the following items: 🗹 🌄 Client pour les réseaux Microsoft 🗹 🔄 Partage de fichiers et imprimantes Réseaux Microsoft Npcap Packet Driver (NPCAP) 🗹 👰 Nord VPN Light Weight Firewall 🗹 🖳 Planificateur de paquets QoS (1)Protocole Internet version 4 (TCP/IPv4) Protocole de multiplexage de carte réseau Microsoft < > Uninstall Install... Properties <u>(2</u>) Description Protocole TCP/IP (Transmission Control Protocol/Internet Protocol). Protocole de réseau étendu par défaut permettant la communication entre différents réseaux interconnectés. OK Cancel

In the panel on the left-hand side, select "Change adapter settings"

 Select and right-click the icon to view the network connection pop-up menu that will be used.

2 Select "Properties"

 Select
 "Internet Protocol (TCP/IP)" or
 "Internet Protocol version 4
 (TCP/IPv4)" (without deselecting the check box)

2 Select "Properties"

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×



rotocole Internet vers	ion 4 (TCP/IP)	v4) Properti	es	
General				
You can get IP setting this capability. Otherw for the appropriate IP	s assigned aut ise, you need settings. ress automatic	omatically if to ask your r ally	your netw network ac	ork <mark>suppor</mark> Iministrato
) 💿 Use the following	IP address: -			
IP address:		192 . 16	58.10.	8 2
Subnet mask:		255 . 25	55.255.	0 3
Default gateway:				
Obtain DNS serve	er address auto	omatically		
	DNS server ad	aresses:		
Preferred DNS serve	er:		1. 13	<u></u>
Alternate DNS serve	er:			8
Validate settings	upon exit			Advanced.
		4	OK	Car
Ethernet 7 Properties				×
Networking Authentication	Sharing			
Connect using:	-51			
ASIX AX88179 USE	3 3.0 to Gigabit E	themet Adapte	er #3	
This connection uses the f	ollowing items	Conti	gure	
Client pour les rés Partage de fichier Partage de fichier NordVPN LightW Planificateur de p Protocole Interne	eeaux Microsoft rs et imprimantes river (NPCAP) eight Firewall aquets QoS t version 4 (TCP/ iplexage de carte	Réseaux Micro (IPv4) e réseau Micro:	soft	
<			>	
Install	Uninstall	Prope	erties	
Description				
Protocole TCP/IP (Tran Protocol). Protocole de communication entre dif	smission Control réseau étendu pa férents réseaux ir	Protocol/Interr ar défaut perme nterconnectés	net ettant la	
communication entre dif	férents réseaux ir	nterconnectés		

Select "Use the following IP address"

Enter:

- 2 the IP address
- 3 the subnet mask
- 4 Press "OK" to confirm

Select "Close".

The change of IP address has now taken effect.

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3.2 LIST OF COMMISSIONING OPERATIONS

3.2.1 Product power supply:

Connect the battery cable to the battery (in the bag of accessories).



Check that the battery cable is correctly fitted (red cable to + and black cable to -)

Insert the battery into its housing and connect it to the equipment (see § 2.3).

Position the retaining strap in place (by passing it through the rectangles at the bottom).

Close the fuse holder.

The equipment is now live

Close the lower door and apply the second locking seal.



3.2.2 Configuration by PC

Now connect your PC to the cabinet's Ethernet Configuration port.

Open the Internet browser and enter https://192.168.10.1 in the address bar

As the certificate is self-signed, a warning message may appear. Agree to continue.

You are then taken to the home page for the embedded software.





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User :	Administrator	~
Decoword :	Administrator	
Password.	Maintenance	
	Visualization	
Cancel		

3 user accounts are created by default:

- Administrator: -Access to all tabs. Default password: root_ensto
- Maintenance: -Access to all tabs associated with operation of the MV network Default password: maintenance_ensto
- Visualization Access limited to visualization, downloading and actions available on the local UI. Default password: ensto

The passwords for Administrator and Maintenance users must be changed when the user first logs in.

Additional accounts can be added (Refer to guide 72868 – System configuration guide for cabinet e-RTU2020)

All of the configuration settings are detailed in § 4.2, but the following settings at least must be configured

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- Communication and Protocols Menu
 - Configure the communication devices
 - IP:



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• Serial:

日 米 三		You are logged in as Administrator 🕞
ENSTO	Communication a	nd Protocols
e-RTU2020	Uart (COM	
A Return	Uart 1	
Ethernet		×
Uart (COM)	Baudrate 9600	×
Main Communication	Number of bits 8	• •
Secondary	Stop bit (s) 1	~
Communication	RTS management No Delay pre RTS (ms) 100 Delay post RTS (ms) 50 PTS polarity Nam	
	COM settings direct Dialing buffer (ATD)	protocol (null modem) V
	Uart 2	
	COM	2 ×
	Baudrate 9600	~
	Parity Even	v
	Stop bit (s) 1	<u> </u>
		•
	RTS management No Delay pre RTS (ms) 0 Delay post RTS (ms) 0 RTS polarity Norm	al V
	Save	

- > Configure primary/secondary communication (see Protocol Notice)
- Fault detection menu
 - Program the type of fault detection



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- Overcurrent ("Amperimetric"):
- > Program the current thresholds for single-phase and polyphase faults

11 # E		You are logged in as Administrator 🕞
ENSTO	Fault D	etection
e-RTU2020	Amperemetric	Fault Detection
Return Fault detection Amperemetric Fault Detection Directional Fault Detection	Earth current channel A (A) Earth current channel B (A) Earth current channel D (A) Earth current channel D (A) Time taken into account earth fault current (ms) Phase current Channel A (A) Phase current Channel B (A) Phase current Channel D (A) Phase current Channel D (A) IDouble Channel A (A) IDouble Channel B (A) IDouble Channel C (A)	40 40 40 40 40 40 40 40 40 40 40 40 40 4
	Time for taking into account phase and double fault (ms) SPI activation time (ms) Minimum SPI signaling time (s) Reset detector by UV presence Detector reset by MV presence(PPACS) Reset detector by current presence Reset detector by time delay SPI maximum time signaling (s)	80 250 3 Yes No Vo No Yes Vas Vas
	Detector reset by MV presence(PPACS) Reset detector by current presence Reset detector by time delay SPI maximum time signaling (s)	No V No V Yes V 7200 200

- Directional
- > Program the current thresholds for single-phase and polyphase faults

UI 💥 🚾		You are logged in as Administrator
ENSTO	Fault De	etection
e-RTU2020	Directional Fa	ault Detection
Return Fault detection	Phase current Channel A (A) Phase current Channel B (A)	500
Amperemetric Fault Detection	Phase current Channel C (A) Phase current Channel D (A)	500
Directional Fault Detection	Time for taking into account phase fault (ms) IDouble Channel A (A) IDouble Channel B (A) IDouble Channel C (A) IDouble Channel D (A) Time for taking into account double fault (ms)	80 250 260 250 250 80
	Earth current peak threshold (Acr) Earth voltage peak threshold (Vcr) Earth voltage confirmation threshold (Veff) Presetting 1 Presetting 2	30 4000 1700 Preset the parameters with the Jeu 1 Preset the parameters with the Jeu 2
	Time of taking into account MV presence (ms) SPI presence time (s) Max time SPI (s)	5000
(Sa	ave

Standard homopolar sensitivity presets are available (Press the Preset1 and Preset2 buttons)





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> Calibrate the PPACSs (to do this, there must be MV) in the local control tab



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- Automation menu (if necessary)
 - o ASF

H # 💶		You are logged in as Administrator
ENSTO	Auton	nation
e-RTU2020	A	SF
ASF	Active function Voltage monitored during opening	No V None V
ASPP	Validated Automation channel A Opening during Fault direction	No
	Validated Automation channel B Opening during Fault direction	No Y Fault 2 Y Red Y
	Validated Automation channel C Opening during Fault direction	No Y Fault 2 Y Red Y
	Validated Automation channel D Opening during Fault direction	No Fault 2 Red
	Minimum time between 2 faults (ms) ASF Standby Timeout (s) Opening delay on ASF (ms) Opening supervision delay on ASF (s)	1500 40 3000 10
	Si	ave

- > Enable or disable the use of ASF automation (Function active/inactive)
 - o APSS

LI 💥 💶		You are logged in as Administrator 🕞
ENSTO	Autor	nation
e-RTU2020	As	;PP
숙 Return	Active function	No
ASF	Source 1 configuration	Channel A
ASPP	+	None 🗸
'	+	None 🗸
	Source 2 configuration	Channel B
	+	None 🗸
	+	None 🗸
	Type of automation	Full V
	Number of attempts	3 🗸
	Automatic return to main source	No 🗸
	Cancel time permut. on active Src voltage return (T3s) (ms)	3000
	Time out permutation (T3mn) (s)	180
	Switchover delay (s)	45
	Cell opening monitoring delay on ASPP (s)	10
	Cell closing monitoring delay on ASPP (s)	10
	Time between 2 attempts (ms)	150
	Si	ave
	-	

Enable or disable the use of APSS automation (Function active/inactive)



In order to function, the automated systems must be turned on either locally via the local panel or remotely.

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• System menu

M # 💶			You are logged in as A	Administrator \longrightarrow
ENSTO	Sys	stem		
e-RTU2020	Sy	stem		
\land Return	Date / Hour		2000-01-02 / 01:32:18 🚱	
System	Version		e-RTU2020 PR236 V1.9	
Password	Ur	odate		
Users	Choisir un fichier Aucun fichier n'a été sélectionné		Update	
Add user	0			
Firewall	Conti Download the configuration file	guration	Developed	
			Download Send and report	
OpenVPN	Choisir un fichier Aucun fichier n'a ete selectionne		Send and repose	
IPSec	Re	boot		
DHCP	R	eboot		
SSH				
Web server	Rest	oration		
Encryption Keys and	Restore the previous configur	ation (excluding systemation)	em settings)	
Ocrtificates	Restore fa	ictory settings		
	Se	ttings		
	Session timeout (s)	6000		
	Maximum number of login attempts	3		
	Lockout time for too many failed login attempts (s)	180		
	Save and ta	ke into account		

Set the ITI cabinet's time either manually or using the time on your PC (click on the cogwheel alongside the time)

On completion of configuration, there should no longer be any faults and the green equipment standby LED on the local panel should flash.

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3.3 OPERATIONAL TESTS

A description of the user interface is available in § 1.2.

Via the local panel, check that the following information is displayed:

12 V POWER SUPPLY indicator	STEADY ON	
light		
EQUIPMENT IN STANDBY	FLASHING	
indicator light		
EQUIPMENT FAULT indicator light	OFF	
Fault indicator lights	OFF	
LOCAL indicator light	STEADY ON	
POSITION indicator lights	STEADY ON GREEN OR RED	
	(if a circuit breaker is connected)	
NEUTRALISATION indicator lights	OFF OR FLASHING	
	(depends on the status of the circuit	
	breaker neutralisation switch)	
TEXT display	> Measurements	
	> Counters	
	> Configuration	
	> Maintenance	



Press the EQUIPMENT TEST button and check that all the indicator lights come on and that the display is off.

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The following commissioning operations may be carried out via:

- User interface: Display module / navigation button.
- Web user interface: Local Command Tab

The cabinet must be in local position

a. Battery test:

The equipment integrates a battery test to confirm the condition of the battery.

Maintenance \rightarrow Battery test \rightarrow Press the "OK" button

20 seconds later the screen displays the message: **"Battery test OK" or "Battery test failed"**. If the procedure has failed, refer to §5.2 (corrective maintenance) to identify the cause of the problem.

b. Fault detector test:

Maintenance \rightarrow Detector tests \rightarrow Press the "OK" button

Flashing fault lights implies the detector is functioning correctly. If the procedure has failed, refer to §5.2 (corrective maintenance) to identify the cause of the problem.

Note: To check all the fault detection features, use the NOVEXIA fault simulator (internal cat. No. IFS NX2000401).

c. Calibration procedure: (if voltage sensors present and directional)

As the switch is connected to the live network, you can only initiate the calibration of voltage sensors via the <u>Web User interface</u> (local Command tab).

After 10 seconds the calibration status (OK or Fail) can be seen in the fault tab. If the procedure has failed, refer to §5.2 (corrective maintenance) to identify the cause of the problem.





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d. Communication test

Perform communication tests with the control station and check that information is correctly returned to the remote control centre.

The "Reception", "Transmission", and "Online" LEDs must flicker during communication (serial protocols).

e. Circuit breaker control test

Check the proper operation of the electrical control of the MV circuit breakers. To do this, for each channel, perform an open/close cycle (via the local panel, select the channel then press the command validation and the open or close buttons at the same time) and check the correspondence between the position of the circuit breaker and the position indicator lights on the user interface.

Note: To perform this check, it is possible to use a circuit breaker simulator.

f. Testing the neutralisation switch for MV circuit breakers

For each channel, set the neutralisation switch on the MV circuit breaker to ON. Check that the corresponding "Neutralised" LED for the channel flashes. Check that the electrical control is neutralised (manual mode): No possibility of performing an open/close cycle



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4 OPERATION

- 4.1. Functions
- 4.2 Commands, tests, configurations
- 4.3. Method for using the PC interface
- 4.4 Upgrades with new functions







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4.1 FUNCTIONS

The cabinet contains, with reduced space requirements, all of the functions required to remotely control underground circuit breakers. In addition, it can detect line faults, for example, a branch fallen on the line.

The product purpose is to make the MV network more reliable in order to reduce power outages for the end user (industrial users, residents, etc.).

Several variants are available to meet all communications needs.

Viewing and configuration are possible by PC by means of the HTML pages embedded in the equipment.

Certain settings can be viewed on the local panel.

4.1.1 Power supply unit function

The power supply unit comprises:

a. 100 VA primary isolation transformer

Primary: 230 V (U ± 15 %) Secondary: 0 V – 27 V

Dielectric strength: primary/screen: 10 kV 50 Hz – 1 mm, 20 kV with 1.2 / 50 μs shock wave secondary/screen: 10 kV 50 Hz – 1 mm, 20 kV with 1.2 / 50 μs shock wave primary/secondary: 10 kV 50 Hz – 1 mm, 20 kV with 1.2 / 50 μs shock wave

b. Battery charger

The charger is voltage-regulated and temperature-compensated with a current limit of 3.5 A. The charge curve is specific to each type of battery, batteries must be replaced with batteries of the same type and the same make. The energy workshop can provide 15 A for 50ms and 5 A for 7s for controlling the circuit breaker motor.

- 12 V DC power source: the energy supply unit provides regulated DC voltage with temperature compensation of 13.8 V, 3.6 A at 20°C. The protection of external loads is assured by a 5 x 20 mm fuse, rating 4 A.

- 48 V DC power source: A 12 V / 48 V converter provides 48 V, 7 A regulated voltage (it can withstand a current impact of 15 A for 50 ms).

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Management of the 12 V power supply required by the cabinet.

- Fuse F1 (4 A) protects the charger.
- An F2 fuse with 6.3 A rating protects the motor power supply.
- In standby or during operating cycles, the voltage is 12 V +30%, -10% depending on consumption and the ambient temperature.
- Residual ripple less than 1% from 50 Hz to 3 kHz
- 0 V connected to the protective Earth

Battery protection against deep discharge

Subsequent to a lack of AC voltage for 16 hours , the loads powered by the battery are cut off (the cabinet is no longer supplied).

The power supply is restarted by:

- Return of the AC voltage supply
- Pressing the "RAZ" (Reset) button, which restarts a 16-hour charging cycle.

In the event of excessive power consumption by your communication equipment (Current > 2 A for more than 3 min) the 12 V power supply circuit is disconnected. Restore the power supply by pressing the reset button, which initialises the cabinet.

Monitoring of the AC voltage. The loss of AC voltage (U < 30 %) is signalled by

- Remote signalling: "no AC voltage"
- A red indicator light appears on the front panel of the local module panel

Periodic battery test:

A battery testing system is incorporated into the battery charger. The battery capacity is systematically tested every 24 hours.

Values measured: battery voltage: $12 V \pm 2 \% \pm 0.1 V$ or converter voltage: $48 V \pm 2 \% \pm 0.4 V$ (depending on the model)

A current of 6 A is delivered in a resistive load for a period of 2 sec. The battery voltage is measured before, during and after testing. This enables us to calculate the voltage drop at these terminals. Exceeding the voltage drop threshold indicates that the battery's characteristics are no longer able to guarantee normal operation of the control cabinet (battery at the end of its life or insufficient charge).





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This information is signalled by the flashing red indicator lights (battery fault and Equipment Failure) on the front panel and via remote signalling.

The battery voltage varies according to the ambient temperature; the permissible voltage drop threshold is offset by the temperature measurement.

It should be noted that the test can also be initiated manually via the display menu. This test takes about 2s. If a battery fault is detected, the battery fault remote signal is activated. The battery fault and the red equipment failure indicator lights switch on and remain lit until total removal of the power supplies.

c. Battery

Lead battery: 12 V / 38 Ah.

The battery (not supplied with the cabinet) has a recommended working life of seven years. Replace the battery if a battery fault is reported by the cabinet.

NB.: In the case of prolonged s	torage, the battery must be	
recharged every 3 months.		
Charging voltage	Temperature	
12 V		
13.9 V	15°	
13.8 V	20°	
13.7 V	25°	
Note that you can recharg	e the battery using the	

Note that you can recharge the battery using the instrumentation and control unit by connecting it to mains power





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4.1.2 Switch command function

The switch can be operated remotely or locally via the cabinet's UI.

For local operation, ensure that the cabinet is in local operation ("local" indicator light on) otherwise press the "REMOTE CONTROL/LOCAL" button



To close a channel, first select the channel to close, then press the "CLOSE" and "COMMAND VALIDATION" buttons at the same time. After closure, the red position indicator lights up

To open a channel, first select the channel to open, then press the "OPEN" and "COMMAND VALIDATION" buttons at the same time. After opening, the green position indicator light comes on

<u>Note</u>: If a circuit breaker is neutralised by the neutralisation switch on the circuit breaker, the corresponding indicator light ① flashes yellow and all local or remotely controlled operations are prevented.

4.1.3 Fault detection function

For each channel, the device consists of:

- 3 current measuring coils installed on the phases with a ratio of 500 A/1 A and 3 kV insulation between the windings and earth

- 3 isolation transformers with 2 kV coils, which protect our electronic system from voltage surges.







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Electronic assembly comprising the modules for:

- phase current measurement
- detection of exceeding thresholds
- monitoring of AC voltage
- fault display
- remote signalling of faults

There are 2 types of fault current detector

Overcurrent detector (with an impedance-earthed neutral)

This enables single-phase faults, double earth faults and polyphase faults to be detected.

Any excess phase current or phase-earth above the current threshold lasting longer than 300 ms (±10 ms) is signalled by:

- display on the front panel of the cabinet
 - o a flashing red light indicating a phase fault.
 - $\circ \quad$ flashing red and green lights indicating a polyphase fault
- remote signalling of "fault occurrence"



Deletion of logs is performed by the return of AC voltage or after 2 hours signalling. However, the information is retained for at least 3s after the fault has disappeared.

The different fault and time delay thresholds can be modified via the PC (see §4.2)

Directional sensor (compensated neutral)

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This enables the detection of green or red single-phase faults, double earth faults and polyphase faults.

- display on the front panel of the cabinet
 - o a flashing green light indicating a green single-phase fault.
 - o a flashing red light indicating a red single-phase fault.
 - o flashing green and red lights indicating polyphase or double faults

How this detection works is described in HN 45-S-51

The different fault and time delay thresholds can be modified via the PC (see §4.3)





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4.1.4 ASF function

Automation analyses and stores the occurrence of permanent faults detected by the fault detector and controls the automatic opening of the switch if the threshold for the number of faults is reached. A fault is considered permanent when, in the power supply substation (or source substation), the upstream circuit breaker performs an ineffective slow recloser cycle.

The automation considers a fault downstream of the circuit breaker to be permanent when N number of network faults (N programmable from 1 to 7) are detected. The faults taken into consideration are Phase-Earth or Phase-Phase faults > T1. Faults < T1 are not considered.

E.g.:

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The circuit breaker cycle takes place as shown in the diagram. The order to open the circuit breaker is sent 3 sec (T3) after the second occurrence of a current fault only if the line is switched off.

If the voltage has not disappeared, the opening command is not transmitted.

If no other fault is detected during a time of T2 seconds after the occurrence of the first fault, the automated system returns to the initial mode (T2 programmable from 30 sec to 240 sec).







- T1: Time to trigger fault detection (page "fault detector setting programming")
- o T2: Timeout to return to the initial state
- T3: Time delay before opening command
- T4: Minimum time between two faults
- N: Number of faults before opening

Automated systems (ASF & APSS) can be turned on/off either remotely or locally via the cabinet local user interface (UI).



To activate the ASF function, press the "ASF" and "COMMAND VALIDATION" buttons at the same time. After activation, the green "ASF on" indicator light is illuminated

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To deactivate the ASF function, press the "ASF" and "COMMAND VALIDATION" buttons at the same time. After deactivation, the yellow "ASF off" indicator light is illuminated



The ITI cabinet's ASF function is only active if it has been previously configured by the PC software (see §4.3.12) If the function has not been activated, the 2 ASF function lights (on, off) are not lit up



The direct action of activation/deactivation using the "ASF" button can be configured (see § 4.3.20 Administrator Parameters)

4.1.5 APSS function

The APSS automated system continuously analyses the network's status and switches between 2 sources when the following switching conditions are fulfilled:

- At least one circuit breaker for the active source is closed. The closed circuit breakers are not neutralised.
- The circuit breakers for the back-up source are open.
- There is no voltage at all the closed circuit breakers for the active source.
- There is voltage at at least one non-neutralised circuit breaker for the back-up source.
- The 48 V DC voltage is correct, guaranteeing the complete switching of sources.
- There is no external locking order.
- The switching direction is authorised.
- No default MV locking order originating from MV fault detectors for the active source in the case of complete automation.
- Locking conditions for the APSS function

Overcurrent

Locked switching in the presence of at least one single-pole or polyphase fault affecting the active source.

Directional

Locked switching in the presence of at least one green or polyphase fault affecting the active source.





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The APSS automated system is configured using the PC. It defines

- Definition of the switching pair Src1 and Src2: 1 to 3 channels per source •
- Type of automated system: Complete (MV fault monitoring) or Simplified
- Switching direction: Src1 -> Src2 ; Src1 <-> Src2 ; Src1 <- Src2
- Time delay to switching (Tr): 1, 5, 25, 45s •
- Number of authorised attempts: 1 to 4 •

Automated systems (ASF & APSS) can be activated and deactivated either remotely or locally via the local user interface (UI) on the cabinet.

PASA	
En Service Hors Service	EQUIPEMENT EN VEILLE EQUIPEMENT EN DEFAUT
Src1 < Src2 SOURCE Src1 ⇔ Src2 Src1 > Src2	ABSENCE 48 V/C ABSENCE 12 V/CC ABSENCE 12 V/CC ABSENCE U V/CC COUPURE CHARGE EXTERNE DEFAUT BATTERIE
CONDITIONS NON REMPLIES	DEFAUT INTERNE
	VALIDATION DRDRE

Display of the switching direction

To activate the PASA function, press the "APSS" and "COMMAND VALIDATION" buttons at the same time. After activation, the green "APSS ON" indicator is illuminated

To deactivate the PASA function, press the "APSS" and "COMMAND VALIDATION" buttons at the same time. After deactivation, the yellow "APSS OFF" indicator is illuminated.



The ASPP function of e-RTU2020 cabinet the is only active if it has been configured beforehand by the PC software (see §4.3.12) If the function has not been activated, the 2 PASA function lights (on, off) are not lit up

The direct action of activation/deactivation using the "PASA" button can be configured (see § 4.3.20 Administrator Parameters)

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4.2 COMMANDS, TESTS, CONFIGURATIONS

The product has UI and PC interfaces for configuring it and visualizing information on the cabinet and the network. This paragraph informs the technician of the method for using the product interfaces.

Method for using the user interface (UI):

The user interface has buttons, indicator lights and a display.

The use of buttons and the visualization of LEDs is intuitive. The memo (below) is available for taking charge of the *display/navigation button* module.

Memo for using the display/navigation button module

In the initial state in local mode, the screen displays the following tabs:

- > Measure > Counters
- > Configuration
- > Maintenance



Position the arrow opposite a tab and press the OK button to access it. To leave the tab, press the LEFT button. The arrow is moved using the UP and DOWN buttons.

It is possible to scroll through the information contained in the tabs using the UP and DOWN buttons.

The "Configuration" and "Maintenance" menus allow certain cabinet settings to be visualized.





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4.3 METHOD FOR USING THE PC INTERFACE



User :	Administrator	~
Decoverd	Administrator	
Password.	Maintenance	
	Visualization	
	Cancel	

3 user accounts are created by default:

- Administrator: Access to all tabs. Default password: root_ensto
- Maintenance:

Access to all tabs associated with operation of the MV network Default password: maintenance_ensto

Visualization

Access limited to visualization, downloading and actions available on the local UI. Default password: ensto

The passwords for Administrator and Maintenance users must be changed when the user first logs in.

Additional accounts can be added (*Refer to guide 72868 – System configuration guide for cabinet e-RTU2020*)



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4.3.1 Available tabs depending on the user level

User Level	Visualization	Maintenance	Administrator
Accessible tabs	CONSTOR CONSTOR CONSTOR Counters Counters Inputs / Outputs Events Local order Downloading IP analyzer IP traces Serial traces	 IIII IIII ENSTED ENSTED ENSTED Equipment Fault Measurements and Counters Inputs / Outputs Events Local order Downloading IP analyzer IP traces Serial traces Communication and Protocols Automation Fault Detection Delays and Alarms Cyclic Measurement Recording Telemetry I/O Label TSS Fault Grouping Maintenance System 	 Imit Imit Imit Imit Imit Imit Imit Imit Fauit Reasurements and Counters Inputs / Outputs Inputs / Out
			System

The Maintenance and Administrator user levels allow settings to be changed, by entering the value via the computer keyboard or via the drop-down menu.

Data is incorporated by the equipment when the **Save** button is pressed on the corresponding page.

Save

Once all the settings have been changed, they are applied by the cabinet when the **Apply changes** button is pressed:

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4.3.2 Visualization Tab



Settings	Possibilities	Definitions
Equipment fault	Lit up red Off	Fault affecting one of the cabinet's elements. An explanation of the fault will be provided in the Fault tab
Equipment in standby	Lit up green Off	Equipment operating normally. Additional information on the equipment fault
No LV supply voltage	Lit up red Off	No power supply if the voltage is below 170 V (for a 230 V power supply)
Local	Lit up red Off	Display of product operating mode (Local / Remote)
Switch position (by channel)	Lit up green Lit up red Off Lit up red+green	Switch open Switch closed Switch not present Switch fault
Instantaneous current (by channel)	o to 999	Instantaneous value of three averaged line currents
Fault detection (by channel)	Lit up red Lit up green Lit up green+red Off	Line fault detection depending on the type of detection selected (§4.3.13 Fault detection tab) and the type of visualization selected (§4.3.20 Administrator Settings tab)
Channel lockout information – padlock – (by channel)	Lit up yellow Off	Status of the lockout switch for the MV cell

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Automated system status (ASF)	Lit up green	On
	Lit up yellow	Off
	Off	Disabled
Automated system status (APSS)	Lit up green	On
	Lit up yellow	Off
	Off	Disabled
Switching in progress	Lit up red	Switching source in progress
	Off	
Switching direction	Lit up green	Defining the authorised switching direction
	Off	
External locking	Lit up red	Automated system locked by presence of external
	Off	contact (see §2.3.2.e)
Conditions not fulfilled	Lit up red	Automation locked as the result of a lack of
	Off	switching conditions

By moving the mouse over the channel, the channel details appear:

CHAN	NEL A	Instantaneous current	o to 999	Instantaneous value of three averaged line
linst	0.0 A	Average current	o to 999	Averaged instantaneous current
avg	0.0 A	Maximum current	o to 999	Maximum instantaneous current
max	0.0 A	Switching operation counters	o to 9999	Number of switching operations switching operations
Manoe num 1	uvers ber:	Phase/earth fault (in amperometric detection mode only)	o to 9999	Number of faults between phase and earth
Earth	fault:	Fault between phases	o to 9999	Number of faults between phases
0	fa	Red fault (in directional detection mode only)	o to 9999	Number of red faults
Phase 1	Tault:	Green fault (in directional detection mode only)	o to 9999	Number of green faults



button opens the Measurements and Counters tab (see §4.3.4)

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4.3.3 Fault Tab

и ж 💶		You are	logged in as Administrator
ENSTO		Visualization	
e-RTU2020		Fault	
Equipment Fault Measurements and Counters Inputs / Outputs Events Local order Downloading IP tester IP analyzer IP analyzer IP traces Serial traces Communication and Protocols Automation Fault Detection Delays and Alarms	 U Alim Fault subst. U Alim Fault Charger(12V) Fault Charger(COM) Fault Battery Fault Display fault Convertor fuse Fault DC/DC Convert. Fault Measure board Fault 12V motor fuse Fault SF6 low pressure CPU Fault IO board Fault Reserve IO board 1 Reserve IO board 2 Voltage board2 Fault Voltage board2 Fault APSS open fault APSS def carditione 	 ASF open Fault Ch C ASF open Fault Ch D ASF open Fault Ch E ASF open Fault Ch F ASF open Fault Ch G ASF open Fault Ch H CD Fault Channel A CD Fault Channel B CD Fault Channel C CD Fault Channel C CD Fault Channel F CD Fault Channel F CD Fault Channel H DD board fault Ch B DD board fault Ch D DD board fault Ch C 	
Telemetry	ASF open Fault Ch A	◯ DD board fault Ch H	
I/O Label	O ASF Open Fault Ch B		
TSS Fault Grouping		Remote fault reporting	
Maintenance	C Equipment fault	Card Fault	
Administrator Settings	O Internal fault	O Urgent fault	
System	O Non Urgent Fault		

Settings	Possibilities	Definitions
Prolonged lack of LV supply voltage (AC voltage)	Lit up red Off	No power supply for 16 h (configurable value)
Charger Fault (12 V voltage)	Lit up red Off	12 V voltage fault or no 12 V voltage
Charger fault (COM)	Lit up red Off	Charger card communication fault
Battery fault	Lit up red Off	Battery anomaly if the voltage at its terminals is less than 10.5 V or its capacity is zero or the battery test has failed
Display fault	Lit up red Off	Display board communication fault
Converter fuse fault	Lit up red Off	48 V fuse fault as the result of 48 V over- consumption
Converter fault	Lit up red Off	Output voltage fault or no output voltage from the DC/DC converter
Measurement board fault (overhead only)	Lit up red Off	Measurement board communication fault
Motor fuse fault (overhead only)	Lit up red Off	Motor fuse fault as the result of 12 V motor over- consumption
SF6 pressure drop fault (overhead only)	Lit up red Off	Information originating from the SF6 pressure sensor contact (Auguste)
CPU fault	Lit up red Off	CPU board electronic fault
IO board fault	Lit up red	IO 16 board communication fault

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	Off	
Reserves card 1 fault	Lit up red	Reserves information originating from the fault
	Off	detector card wire 1 communication fault
Reserves card 2 fault	Lit up red	Reserves information originating from the fault
	Off	detector card wire 2 communication fault
VT 1 fault (PPACS)	Lit up red	Communication fault or fault affecting
(directional only)	Off	initialisation of the voltage acquisition electronics
		originating from the PPACS fault detector card
		wire 1
VT 2 fault (PPACS)	Lit up red	Communication fault or fault affecting
(directional only)	Off	initialisation of the voltage acquisition electronics
		originating from the PPACS fault detector card
		wire 2
Prolonged max. radio current	Lit up red	Over-consumption of external 12 V current (by
	Off	default > 2 A for 3 min – Adjustable)
APSS active source open fault	Lit up red	Fault affecting opening of the active source during
	Off	APSS switching
APSS backup source close fault	Lit up red	Fault affecting closing of the backup source during
	Off	APSS switching
APSS conditions definition	Lit up red	Automation locked as the result of a lack of
	Off	switching conditions
ASF opening fault	Lit up red	Channel opening fault as the result of ASF
(by channel)	Off	automation
TCD fault	Lit up red	Switch O/C management system communication
(by channel)	Off	fault
DD fault	Lit up red	Fault detection card communication fault or
(by channel)	Off	internal fault

Faults can also be viewed directly on the display.

Maintenance/Equipment fault menu





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4.3.4 Measurements and Counters Tab

🛯 米 💶 You are logged in as Administrator **ENSTO** Visualization e-RTU2020 **Measurements and Counters** Equipment LV voltage 224.0 V MV voltage 19.5 kV 224.0 V Average MV voltage (10 min) 13.4 V Voltage 48V Average LV voltage (10 min) Fault 19.5 kV 12V voltage 48.2 V Measurements and Current 12V 0.0 A Current 48V 0.0 A Counters **CPU** temperature 41 °C Analog input 0-10V / 4-20mA 0 % Inputs / Outputs xx °C PT100 temperature Events Local order CHANNEL A CHANNEL B Downloading Linst Phase 1 Linst Phase 1 0.0 A 0.0 A IP tester l inst Phase 2 I inst Phase 2 0.0 A 0.0 A IP analyzer l inst Phase 3 0.0 A l inst Phase 3 0.0 A 0.0 A 0.0 A l inst avg l inst avg **IP traces** l avg (10 min) 0.0 A l avg (10 min) 0.0 A Serial traces I max 0.0 A I max 0.0 A Communication and Protocols MV presence (Switch) No MV presence (Switch) No MV presence (PPACS) No MV presence (PPACS) No Initialized Sensors (PPACS) Initialized Sensors (PPACS) Automation No No Number of Maneuvers Number of Maneuvers Fault Detection 1 1 ASF Openings Number 0 ASF Openings Number 0 Delays and Alarms Number of Earth Faults 0 Number of Earth Faults 0 Cyclic Measurement Number of Phase Faults Number of Phase Faults 1 0 Recording Telemetry CHANNEL C CHANNEL D I/O Label TSS Fault Grouping l inst Phase 1 0.0 A l inst Phase 1 0.0 A Maintenance l inst Phase 2 0.0 A l inst Phase 2 0.0 A l inst Phase 3 0.0 A I inst Phase 3 0.0 A Administrator Settings l inst avg 0.0 A l inst avg 0.0 A l avg (10 min) l avg (10 min) System 0.0 A 0.0 A 0.0 A 0.0 A I max I max MV presence (Switch) MV presence (Switch) No No MV presence (PPACS) MV presence (PPACS) No No Initialized Sensors (PPACS) Initialized Sensors (PPACS) No No Number of Maneuvers 0 Number of Maneuvers 0 ASF Openings Number 0 ASF Openings Number 0 Number of Earth Faults 0 Number of Earth Faults 0

Settings	Possibilities	Definitions
LV voltage	o to 999.9	LV voltage value in V
Average LV voltage	o to 999.9	Averaged LV voltage value in V
MV voltage	o to 99.9	Value of the MV voltage in kV originating from the
		LV
Average MV voltage	o to 99.9	Averaged MV voltage value in kV
12 V voltage	o to 99.9	Instantaneous value of the internal 12 V voltage in
		V
12 V current	o to 9.9	Instantaneous current supplied to external
		elements (radio, etc.) in A
48 V voltage	o to 99.9	Instantaneous value of the 48 V source in V
48 V current	o to 9.9	Instantaneous current supplied to the switch
CPU temperature	± 99.9°	Internal temperature of the cabinet in degrees
PT100 temperature	± 999.9°	Temperature originating from the PT100
		temperature sensor in degrees (see §1.2.4)

0

Number of Phase Faults

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Number of Phase Faults

7



0





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Analogue input 0-10 V / 4-20 mA	0 to 100%	Measurement as a % originating from the
		analogue sensor (see §1.2.4)
Instantaneous current Phase 1	o to 999	Instantaneous line current value for phase 1
(by channel)		
Instantaneous current Phase 2	o to 999	Instantaneous line current value for phase 2
(by channel)		
Instantaneous current Phase 3	o to 999	Instantaneous line current value for phase 3
(by channel)		
Average instantaneous current	o to 999	Instantaneous value of three averaged line
(by channel)		currents
Average current (10mn)	o to 999	Averaged instantaneous current
(by channel)		
Maximum current	o to 999	Maximum instantaneous current
(by channel)		
MV available (DC)	Yes	MV availability information originating from the
(by channel)	No	switch connector (see §2.3.2.f)
MV available (PPACS)	Yes	MV availability information originating from the
(by channel)	No	PPACS separable connector (see §2.3.2.d)
Initialized sensor (PPACS)	Yes	PPACS sensor initialised (see §4.3.13 Fault
(by channel)	No	detection menu – directional)
Switching operation counters	o to 9999	Number of switching operations
(by channel)		(1 switching operation = 1 opening + 1 closing)
ASF opening counters	o to 9999	Number of openings triggered by ASF automation
(by channel)		
Phase/earth fault (by channel)	o to 9999	Number of faults between phase and earth
(in amperometric detection mode only)		
Fault between phases (by channel)	o to 9999	Number of faults between phases
(in amperometric detection mode only)		
Red fault (by channel)	o to 9999	Number of red faults
(in directional detection mode only)		
Green fault (by channel)	o to 9999	Number of green faults
(in directional detection mode only)		, , , , , , , , , , , , , , , , , , ,
Poly fault (by channel)	o to 9999	Number of faults between phases (polyphase)
(in directional detection mode only)		

Measurements can also be viewed directly on the display.

Measurements and Counters menus





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4.3.5 Inputs / Outputs Tab

		You a	re logged in as Administrator
ENSTO		Visualization	
e-RTU2020		Reserves	
Equipment	Libelle reserve 1 : → >-	Libelle reserve 2 : >	
Fault	Libelle reserve 3 : >	Libelle reserve 4 :>-	
Measurements and Counters	Libelle reserve 5 : → ►	Libelle reserve 6 : Y-	
Inputs / Outputs		Digital inputs	
Events	Libelle digital input 1 : >	Libelle digital input 2 :	
Local order	Libelle digital input 3 :	Libelle digital input 4 : -• •-	
Downloading	,		
IP tester		Digital outputs	
IP analyzer	Libelle digital output 1 :>-	Libelle digital output 2 : 🍾	
IP traces	Libelle digital output 3 : ->-		
Serial traces			
Communication and Protocols			
Automation			
Fault Detection			
Delays and Alarms			
Cyclic Measurement Recording			
Telemetry			
I/O Label			
TSS Fault Grouping			
Maintenance			
Administrator Settings			
System			

Settings	Possibilities	Definitions
Reserves 1 to 6	Contact open or closed	Status of the reserves contact (see §2.3.2.e)
Digital inputs 1 to 5	Contact open or closed	Status of the dry contact at digital inputs (see §1.2.4)
Digital outputs 1 to 5	Contact open or closed	Status of the dry contact at digital output relays (see §1.2.4)

The labels are fully customisable (see §4.2.17 I/O labels)





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4.3.6 Events tab

See §5.1.3

4.3.7 Local Command Tab



This tab enables the actions that can be performed with the local UI to be performed locally.

This offers the option of performing opening and closing commands for a switch, following a maintenance operation on the latter, in complete safety and outside the substation.

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Buttons	Actions	Local UI	
Reset counters	Resets the switching operation counters	Configuration/Reset Counters	
LV Voltage Calibration	Calibration of the LV voltage (correction of the LV/ELV transformer ratio, if necessary)		
Detector test	Runs a test of the detectors present (The fault LEDs flash)	Maintenance / Detector Test	
Change APSS source	Changing the permitted switching direction SOURCE button		
Cyclic measurement file	to start cyclic measurement recording (see		
initialize	§4.3.16)		
Calibration	Calibration of PPACSs (see §3.2.2. Directional)		
(directional only)			
Battery Test	Initiation of the battery test procedure	Maintenance / Battery test	
	Result in the Fault tab (see §4.3.3)		
Activate/Deactivate the APSS	Turns the APSS function off	APSS button (on/off)	
Activate/Deactivate ASF	Turns the ASF function off	ASF button (on/off)	
Opening / Closing	Switch opening or closing command	Switch Control Buttons	
(by channel)	(instantaneous current recalled for increased	CHANNEL / COMMAND VALIDATION / OPENING	
	safety)	/ CLOSING	
Open/close digital outputs	Digital output command relayed.		
·	Position in the Inputs / Outputs tab (see §4.3.5)		

4.3.8 Downloading Tab

日 米 💶		You are logged in as Administrator 🕞		
ENSTO	Visual	Visualization		
e-RTU2020	Down	Downloading		
Equipment Fault	Maneuver counter file	Download Download		
Measurements and Counters	Box description file	Download		
Inputs / Outputs	EEMD file	Download		
Events	Cyclic measurements file	Download		
Local order	Average measurements file	Download		
Downloading				
IP tester				
IP analyzer				

This tab allows files generated by the cabinet to be downloaded in .csv format, for direct export into excel type spreadsheets

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4.3.9 IP Analyzer Tab

See §5.1.1

4.3.10 IP Traces Tab

See §5.1.2

4.3.11 Communication and Protocols Tab

4.3.11.1 Ethernet tab

LI 💥 💶		You are logged in as Administrator	
ENSTO	Communication and Protocols		
e-RTU2020	Ethernet		
Return Ethernet Uart (COM) Main Communication	Ethernet IP address eth0 (COM) 192168.0.1 Ethernet mask eth0 (COM) 255255255 Ethernet eth2 IP address (EXTENSION) 220220.0.1 Ethernet mask eth2 (EXTENSION) 255255255	5.0	
Secondary Communication	IP routing Destination IP IP G 0.0.0.0 [192.168.0.254 Save	Gateway Interface ↔	

This tab enables definition of the IP addresses (V4) for the 2 Eth0 (COM) communication ports located on the back of the CPU2020 board (remote Ethernet connection in the communication area) and Eth2 (EXTENSION) on the front of the CPU2020 board.

Remember: the address of the Eth1 (CONFIGURATION) port is static (192.168.10.1)

IP routing can be adapted to all the routing options for IP networks. The default address is recorded as 0.0.0.0

Settings	Possibilities	Definitions
Ethernet IP address etho (COM)	Xxx.Xxx.Xxx.Xxx	IP address(V4) that is assigned to the COM port of the
		e-RTU2020 cabinet
Ethernet mask etho (COM)	Xxx.Xxx.Xxx.Xxx	Subnet mask that is assigned to the COM port of the
		e-RTU2020 cabinet
Ethernet IP address etho (COM)	Xxx.Xxx.Xxx.Xxx	IP address (V4) that is assigned to the EXTENSION
		port of the e-RTU2020 cabinet

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Ethernet mask etho (COM)	Xxx.Xxx.Xxx.Xxx	Subnet mask that is assigned to the EXTENSION port of the e-RTU2020 cabinet
IP routing – Destination IP	Xxx.Xxx.Xxx.Xxx	Destination address using the "IP Gateway" gateway on the "Interface" Ethernet port
IP routing - Gateway IP	Xxx.Xxx.Xxx.Xxx	IP address of the gateway used by the routing function
IP routing - Interface	Etho or Eth2	Ethernet port used by the routing function (etho COM or eth2 EXTENSION)



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4.3.11.2 UART(COM) Tab

LI 💥 💶		You are logged in as Administrator
ENSTO	Communication	n and Protocols
e-RTU2020	Uart	(COM)
li Return	Ua	art 1
Ethernet	COM	COM1 V
Uart (COM)	Baudrate	9600
Main Communication	Pany Number of bits	8 Veni
Secondary	Stop bit (s)	1 ~
Communication	RTS management Delay pre RTS (ms) Delay post RTS (ms)	No ▼ 100 50
	COM settings Dialing buffer (ATD)	Infraction direct protocol (null modem) V ATD00000000
	Ua	art 2
	COM	COM2 V
	Baudrate	9600 🗸
	Pany Number of bits	8 V
	Stop bit (s)	<u>1</u>
	RTS management Delay pre RTS (ms) Delay post RTS (ms)	No ▼ 0
	RTS polarity	Inormal Variation Variatio Variation Variation Variation Variation Variation Variation

This tab enables configuration of the 2 serial communication ports UART 1 (COM1) and UART 2 (COM2)

Management of the RTS signal with pre-activation and post-activation delays provides a means to interface with transparent digital radios

Settings (UART 1 and UART 2)	Possibilities	Definitions
Baud rate	110 to 3686400 baud	
Parity	Even	
	Odd	
	None	
Data bits	7 or 8	
Stop bit	1 Or 2	
RTS management	Yes	
	No	
Delay pre RTS	o to 500 ms	
Delay post RTS	o to 500 ms	
RTS polarity	Normal	
	Inverted	
COM settings	Direct protocol (null modem)	Null modem or digital radio
(UART 1 only)	AT command modem	Modem using AT commands (GSM type). DTR
		used for command / line mode
Dialling buffer (ATD)	ATD <telephone number=""></telephone>	
(UART 1 and AT command modem only)		







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4.3.11.3 Primary Communication Tab and Secondary Communication Tab

See specific protocol notices

4.3.12 Automation Tab

4.3.12.1 ASF Tab

How the ASF function works is described in §4.1.4

M # 💶		You are logged in as Administrator
ENSTO	Autor	nation
e-RTU2020	A	SF
ASF	Active function Voltage monitored during opening	No v
ASPP	Validated Automation channel A Opening during Fault direction	No Fault 2 Red
	Validated Automation channel B Opening during Fault direction	No Fault 2 Red
	Validated Automation channel C Opening during Fault direction	No ▼ Fault 2 ▼ Red ▼
	Validated Automation channel D Opening during Fault direction	No ▼ Fault 2 ▼ Red ▼
	Minimum time between 2 faults (ms) ASF Standby Timeout (s) Opening delay on ASF (ms) Opening supervision delay on ASF (s)	1500 40 3000 10
	S	ave

Settings	Possibilities	Definitions
Function enabled	Yes	Activation or deactivation of the ASF function
	No	
Voltage monitored during opening	None	This setting involves opening only if the voltage selected is not
	Cabinet power supply (LV)	present
	MV (DRS)	Voltage sensors see §2.3.2
	MV (PPACS)	
ASF configuration	Valid	Invalid disables the function on the specified channel
(by channel)	Invalid	
Opening during	Slow 1 to 7	Opening of the switch after the 1st and 7th fault
(by channel)		
Fault configuration (by channel)	Red	Defines the type of fault triggering opening
(in directional only)	Green	
Minimum time between 2 faults	100 to 5000 ms	Time between 2 faults in order for the fault to be counted
ASF Standby Timeout	15 to 240s	Return to the initial automation state after the timeout
ASF opening time delay	o to 5000 ms	Opening time delay in relation to the time when the ASF
		conditions are met
Opening supervision delay on ASF	1 to 50s	Opening delay as the result of ASF automation.
		The expiry of this period without a return to the "open"
		position, creates an "ASF opening on" fault

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4.3.12.2 APSS Tab

		You are logged in as Administrator 🕞
ENSTO	Autor	nation
e-RTU2020	AS	;PP
A Return	Active function	No V
ASF	Source 1 configuration	Channel A 🗸
ASPP	+	None 🗸
	+	None 🗸
	Source 2 configuration	Channel B 🗸
	+	None 🗸 🗸 🗸
	+	None
	Type of automation	Full 🗸
	Number of attempts	3 🗸
	Automatic return to main source	No 🗸
	Cancel time permut. on active Src voltage return (13s) (ms)	3000
	Time out permutation (T3mn) (s)	180
	Switchover delay (s)	45
	Cell opening monitoring delay on ASPP (s)	10
	Cell closing monitoring delay on ASPP (s)	10
_	Time between 2 attempts (ms)	
	Si	ave

Settings	Possibilities	Definitions
Function active	Yes	Activate or deactivate the APSS function
	No	
Configuration sources 1	None	Choice of channels associated with source 1
(Active sources)	Channel A	
	Channel B	
	Channel C	
	Channel D	
Configuration sources 2	None	Choice of channels associated with source 2
(Backup sources)	Channel A	
	Channel B	
	Channel C	
	Channel D	
Type of automation	Simplified	If complete, take account of locking for MV faults
	complete	
Number of switching attempts	1 to 3	Number of switching attempts in the event of a failure
Automatic return to primary source	Yes	Automatic return to Source 1 upon the return of voltage to it
	No	
Time to abandon return to active source	1 to 10 sec	Cancel switching in progress if active Source voltage is present during this time
upon voltage return		
Delay on switching	1 to 60 sec	Delay on switching
Monitoring time for cell opening on	1 to 50 sec	Opening time for active source subsequent to APSS automated system.
APSS	_	The expiry of this period without a return to the "open" position, creates an
		"APSS open" fault
Monitoring time for cell closing on	1 to 50 sec	Closing time for active source subsequent to APSS automated system.
APSS	_	The expiry of this period without a return to the "closed" position, creates an
		"APSS closed" fault
Time between 2 attempts	0 to 1000 ms	Time delay between 2 switching attempts

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4.3.13 Fault Detection Tab

The list of types of fault detections managed by the electronics installed in the equipment is available in the "Fault Detection" tab.

It relates directly to the type of neutral point treatment used.

U # 🎞	You are logged in as Administrator
ENSTO	Fault Detection
e-RTU2020	Fault detection
🔄 Return	Neutral regime type Amperemetric
Fault detection	Save
Amperemetric Fault Detection	
Directional Fault Detection	

Contact Ensto novexia for more information.

4.3.13.1 Overcurrent Fault Detection Tab

U # 🏊		You are logged in as Administrator 🕞
ENSTO	Fault D	etection
e-RTU2020	Amperemetric	Fault Detection
Call Amperemetric Fault	Earth current channel A (A) Earth current channel B (A) Earth current channel C (A) Earth current channel D (A)	40 40 40 40
Directional Fault Detection	Time taken into account earth fault current (ms) Phase current Channel A (A) Phase current Channel B (A) Phase current Channel D (A)	80 450 450 450 450
	IDouble Channel D (A) IDouble Channel B (A) IDouble Channel D (A) IDouble Channel D (A) IDouble Channel D (A)	1200 1200 1200 1200 1200 1200 00
	SPI activation time (ms) Minimum SPI signaling time (s) Reset detector by LV presence Detector reset by MV presence(switch) Detector reset by MV presence(PPACS) Reset detector by current presence	250 3 Yes No No No No No Yes No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No No N
	Reset detector by time delay SPI maximum time signaling (s)	Yes v 7200

Settings	Possibilities	Definitions
Homopolar current	20 A to 240 A	Detection of an earth fault if the residual current is above the
(by channel)		threshold for an interval longer than the time for triggering
		detection of the homopolar current
Homopolar fault trigger time	30 to 30000 ms	Minimum earth fault time
Phase current	250 A to 1600 A	Detection of a phase fault if at least one of the two line
(by channel)		currents is above the configured threshold

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Double current (by channel)	250 A to 1200 A	Detection of a phase fault if the residual current is above the threshold for an interval longer than the time for triggering detection of the phase fault
Phase and double fault trigger time	30 to 3000 ms	Minimum phase fault time
SPI activation time	30 to 10000 ms	Minimum fault time for validating the related SPI
Minimum SPI signalling time	o to 6os	Minimum time for maintaining the fault SPI
Reset detector if LV available	No	Allows the fault detector to be reset if LV voltage is available
	Yes	
Reset detector if line current available	No	Allows the fault detector to be reset if line current is available
	Yes	(>5 A)
Reset detector by time delay	No	Allows the fault detector to be reset at the end of the
	Yes	"Maximum SPI signalling time" timeout
Maximum SPI signalling time	1s to 10,800s (3 h)	

4.3.13.2 Directional Fault Detection Tab

Directional detection in accordance with HN 45 S 51 (EDF)

	You are logged in as Administrator	ج
ENSTO	Fault Detection	
e-RTU2020	Directional Fault Detection	
🚓 Return		
Fault detection	Phase current Channel A (A) 500	_
Amperemetric Fault	Phase current Channel B (A) 500	_
Detection	Phase current Channel D (A) 500	
Directional Fault	Time for taking into account phase fault (ms)	
Detection	IDouble Channel A (A) 250 IDouble Channel B (A) 250 IDouble Channel C (A) 250 IDouble Channel C (A) 250 IDouble Channel D (A) 250 Time for taking into account double fault (ms) 80 Earth current peak threshold (Acr) 30 Earth voltage peak threshold (Vcr) 4000	
	Earth voltage confirmation threshold (Veff) 1700	_
	Presetting 2 Preset the parameters with the Jeu 1 Preset the parameters with the Jeu 2	
	Time of taking into account MV presence (ms)	
	SPI presence time (s) 10	
	Max time SPI (s) 7200	
	Save	

Settings	Possibilities	Definitions
Phase current (by channel)	100 A to 1000 A	Detection of a phase fault if at least one of the two line currents is above the configured threshold.
Double current (by channel)	250 A to 1000 A	Detection of a double fault if the residual current is above the configured threshold
Homopolar peak threshold (APK)	10 to 100 APK	green or red fault Refer to specification HN 54-S51 for the operating principle
Homopolar voltage peak threshold (VPK)	2,000 to 10,000 VPK	green or red fault Refer to specification HN 54-S51 for the operating principle
Homopolar voltage confirmation threshold (Vrms)	1,000 to 6,000 Vrms	green or red fault Refer to specification HN 54-S51 for the operating principle
Homopolar detection sensitivity pre-selection	Preset 1 Preset 2	green or red fault Refer to specification HN 54-S51 for the operating principle

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MV availability trigger time	100 to 10000 ms	Refer to specification HN 54-S51 for the operating principle
SPI availability trigger time o to 70s Delay bef		Delay before SPI activation
Max SPI time	1s to 10,800s (3 h)	Remote signalling duration if no MV

4.3.14 Delays and Alarms Tab

4.3.14.1 TS Delay Tab

This tab allows a delay to be defined between the physical appearance of a status and the positioning of the related TS (information recorded by protocol)

14 米 💶		You are logged in as Administrator \square
ENSTO	Delays ar	nd Alarms
e-RTU2020	TS	delay
Image: Constraint of the second s	ASF ES / HS (ms) APSS ES / HS (ms) Position Channel A (ms) Position Channel C (ms) Position Channel D (ms) Position Channel D (ms) Absence Ubt (ms) Persistent Ubt absence (ms) Local (ms) Battery fault (ms) Card fault (ms) Urgent fault (ms) Urgent fault (ms) Non-urgent fault (ms) Blocked Channel A (ms) Blocked Channel B (ms) Blocked Channel C (ms) Blocked Channel C (ms) MV presence Channel B (ms) MV presence Channel B (ms) MV presence Channel B (ms) MV presence Channel B (ms)	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 </th
	MV presence Channel D (ms)	

4.3.14.2 TS Alarm Tab

This tab allows the TSs generating a call (use of a line) to be configured.

This configuration is only used when a modem is used with a non-permanent connection (GSM type – AT command see §4.3.11.2)





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4.3.15 Cyclic measurement recording tab

This tab allows cyclic measurement recording in a .csv format file, for direct export into an Excel type spreadsheet, to be configured.

The file size is 100k, enabling more than 10,000 measurements to be recorded

Should the capacity be exceeded, the file is saved by after-sales service and a new one is created.

日本 🕄 🚾		You are logged in as Administrator \square
ENSTO	Cyclic Measurement Recording	
e-RTU2020	General	
🚓 Return	activated No.	
General	Recording frequency (s) 60	
Definition of recorded tm	Save	
Settings	Possibilities	Definitions

Settings	Possibilities	Definitions
Enabled	No	Activation of cyclic measurement recording
	Yes	
Recording frequency	1 to 1005	

Cyclic Measurement Recording ISTO RTI 12020 Definition of recorded tm Return U BT 12V voltage 12V current 48V voltage * * Definition of recorded tm 48V current ž HTA Voltage CPU temperature External temperature sensor (PT100) * * Analog input Value Instantaneous current phase1 Channel A ž Instantaneous current phase2 Channel A Instantaneous current phase3 Channel A * * Instantaneous current Channel A ž Instantaneous current phase1 Channel B Instantaneous current phase2 Channel B Instantaneous current phase3 Channel B * * No Instantaneous current Channel B Instantaneous current phase1 Channel C ž No Instantaneous current phase2 Channel C Instantaneous current phase3 Channel C Ne * * Instantaneous current Channel C Instantaneous current phase1 Channel D ž No Instantaneous current phase2 Channel D No * * Instantaneous current phase3 Channel D Instantaneous current Channel D Average current Channel A No ž Average current Channel B Average current Channel C No * * Average current Channel D Average current time ž No Maximum current Channel A Maximum current Channel B No * * Maximum current Channel C Maximum current Channel D ž No Voltage Average Time Voltage Average No ~ ~ HTA Voltage Average No × Save Ensto Novexia SAS

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4.3.16 Analog Input Tab

4.3.16.1 Time averages tab

This tab allows the voltage (LV and MV) and average current information to be defined by channel The time averages are synchronised at a fixed time taking account of the averaging duration. For example: for a programmed 10-min period, an average value is calculated at Xh10mn, Xh20mn, Xh30mn, etc.

U # 🏊	You are logged in as Administrator
ENSTO	Telemetry
e-RTU2020	Time averages
Return	Averaging time U (s) 600 Average duration I (s) 600
Dead Bands - Sampling	Save
Dead Bands - Thresholds and Variations	

4.3.16.2 Dead Bands Tab (Sampling / Threshold and variation)

These tabs allow the conditions for updating AIs available for communication (see protocol notices) to be defined

14 米 💶	You are logged in as Administrator
ENSTO	Telemetry
e-RTU2020	Dead Bands - Sampling
ta Return	TM refresh frequency (s) 3
Time averages	Save
Dead Bands - Sampling	
Dead Bands - Thresholds and Variations	

Settings	Possibilities	Definitions
Recording frequency	1 to 105	AI refresh frequency and "Thresholds and variations"
		management





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ENSTO	Telemetry					
e-RTU2020	Dead	Bands - Thresho	Ids and Variatio	ons		
\land Return		Coefficient	Rate variation	Mini variation	Low threshold	High threshold
Time averages	Voltage bt (V)	1	20	20	0	400
	MV voltage (V)	1	20	1000	0	40000
Dead Bands - Sampling	Voltage 12V (V)	1	20	1	0	16
Dead Bands -	Voltage 48V (V)	1	20	5	0	56
Thresholds and	Current 12V (A)	1	20	1	0	10
Variations	Current 48V (A)	1	20	1	0	10
	CPU temperature (°C)	1	20	20	0	100
	PT100 temperature (°C)	1	20	20	0	100
	Instantaneous current channel A (A)	1	20	5	0	700
	Instantaneous current channel B (A)	1	20	5	0	700
	Instantaneous current channel C (A)	1	20	5	0	700
	Instantaneous current channel D (A)	1	20	5	0	700
	Instantaneous current ph1 vA (A)	1	20	5	0	700
	Instantaneous current ph2 vA (A)	1	20	5	0	700
	Instantaneous current ph3 vA (A)	1	20	5	0	700
	Instantaneous current ph1 vB (A)	1	20	5	0	700
	Instantaneous current ph2 vB (A)	1	20	5	0	700
	Instantaneous current ph3 vB (A)	1	20	5	0	700
	Instantaneous current ph1 vC (A)	1	20	5	0	700
	Instantaneous current ph2 vC (A)	1	20	5	0	700
	Instantaneous current ph3 vC (A)	1	20	5	0	700
	Instantaneous current ph1 vD (A)	1	20	5	0	700
	Instantaneous current ph2 vD (A)	1	20	5	0	700
	Instantaneous current ph3 vD (A)	1	20	5	0	700
	Maximum current channel A (A)	1	20	5	0	700
	Maximum current channel B (A)	1	20	5	0	700
	Maximum current channel C (A)	1	20	5	0	700
	Maximum current channel D (A)	1	20	5	0	700
	Average current channel A (A)	1	20	5	0	700
	Average current channel B (A)	1	20	5	0	700
	Average current channel C (A)	1	20	5	0	700
	Average current channel D (A)	1	20	5	0	700
	Current average duration (s)	1	20	20	0	3600
	Average voltage bt (V)	1	20	20	0	400
	Average MV voltage (V)	1	20	1000	0	40000
	Average voltage duration (s)	1	20	20	0	3600
	Analog input (%)	1	20	20	0	100
		Save	E. C.			

Settings	Possibilities	Definitions
Variation rate	0 to 100%	Variation rate of a measurement for spontaneous
(for each item)		transmission of a AI
Mini variation	Measurement range and	Minimum variation of the measurement for
(for each item)	unit	transmission.
Low threshold	Measurement range and	
(for each item)	unit	Minimum and Maximum permitted measurements (AI
High threshold	Measurement range and	invalid outside these ranges)
(for each item)	unit	





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4.3.17 I/O Label Tab

4.3.17.1 Reserves Tab

This tab enables you to customise the Reserved connection inputs (see §2.3.2.e)

M # 🎞	You are logged in as Administrator
ENSTO	I/O Label
e-RTU2020	Box language: English
🔄 Return	Reserves
Reserves	Reserve 1 Libelle reserve 1
Digital inputs	Reserve 2 Libelle reserve 2
Digital outputs	Reserve 3 Libelle reserve 3
Channel Label	Reserve 4
Channel Laber	
	Save

Example:

Reserve 5: "Locking switching" if the APSS function is used Reserve 3: "Water level"

4.3.17.2 Digital Inputs and Digital Output Tab

This tab allows the digital inputs and outputs to be customised (see §1.2.4)

🗾 🖬 💥 🗖			You are logged in as Administrator \longrightarrow
ENS1	Ο	I/O Label	
e-RTU2020		Box language: English	
숙 Return		Digital inputs	
Reserves Digital input Digital outpu Channel Lab	s ts	Digital Input 1 Digital Input 2 Digital Input 2 Digital Input 3 Digital Input 4 Digital Input 4 Digital Input 5	
		Save	
U # I			You are logged in as Administrator \square
ENS	Ю	I/O Label	
e-RTU2020)	Box language: English	
🗠 Return		Digital outputs	
Reserves Digital input Digital outpu	ts	Digital Output 1 Digital Output 2 Digital Output 2 Digital Output 3	
Channel Lat	pel	Save	
		T 1 00 (0) (7) 050 (0)	





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4.3.18 SPI Fault Grouping Tab

The SPI fault groupings are SPIs allowing an SPI to be linked to various pieces of equipment fault information.

The e-RTU2020 cabinet offers 3 manufacturer SPI groupings (fixed) and 2 user SPI groupings (configurable)

Manufacturer SPI

- Equipment fault
 This fault is created for all equipment faults.
 Information relating to the equipment fault indicator light on the front.
- Board fault Fault relating to the electronics.
- Internal fault
 Equivalent to a board fault + faults relating to automation
 Information relating to the internal fault indicator light on the front
 (Display type = Type 1 see §4.3.20).

User SPI:

- Urgent fault
- Non-urgent fault

4.3.18.1 Manufacturer SPI

Board fault	Internal fault	Equipment fault
CPU board fault	Board fault	Internal fault
Display board fault	ASF opening fault (by channel)	Battery fault
Charger card fault (COM)	APSS active source opening fault	No AC voltage
DC electronic fault (by channel)	APSS backup source closing fault	Prolonged lack of AC voltage
Reserves electronic fault	APSS condition not met fault	Charger fault (12V)
(board 1 and 2)		
Fault detector board fault		Converter fuse fault
(by channel)		
Converter board fault		Prolonged over-consumption
		of external 12 V (max. radio
		current)
Measurement board fault		SF6 pressure drop
(overhead only)		(Overhead only)
16 I/O board fault		
PPACS (VT) voltage electronic fault		
(Underground: board 1 and 2,		

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Overhead: voltage board)			
Motor control fuse fault		▼	
(overhead only)			

4.3.18.2 User SPI

14 米 💶		You are logged in as Administrator \longrightarrow
ENSTO	TSS Fault	Grouping
e-RTU2020	Definition SF	Pl urgent fault
A Return Definition SPI urgent fault SPS non-urgent fault definition	Power Voltage fault Prolonged Power Voltage fault Charger fault (12V) Charger fault (2OM) Battery fault Motor fuse fault Converter fault Converter fault Converter fuse fault Prolonged Imax radio SF6 fault Display fault Electronic command fault Channel A Electronic command fault Channel D Fault reserves card 1 Detector fault Channel D Fault reserves card 1 Detector fault Channel B Detector fault Channel B Detector fault Channel B Detector fault Channel B Detector fault Channel A Detector fault Channel C Detector fault Channel B Detector fault Channel C Detector fault Channel C Detector fault Channel B Detector fault Channel C Detector fault Channel C Detector fault Channel B Detector fault Channel C Detector fault Channel B Detector fault Channel B Detector fault Channel B Detector fault Channel C Detector fault Channel C Detector fault Channel B Detector fault Channel C Detector fault Channel B Detector fault Channel A CPU board fault Open fault ASF Channel A Open fault ASF Channel A Open fault ASF Channel B Open fault ASF Channel C Detelle reserve 3 Libelle reserve 3 Libelle reserve 5 Libelle reserve 5 Libelle reserve 6 Libelle digital input 4 Libelle digital input 4	N0 × N0 ×
	Sa	ave

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4.3.19 Maintenance Tab

4.3.19.1 General Configuration Tab

14 米 💶		You are logged in as Administrator 🕞
ENSTO	Mainte	enance
e-RTU2020	General co	onfiguration
A Return	Box language	English
General configuration	HMI standby	Yes V
Anti Rebound Inputs	Time before standby (s)	180
	Date change registration (EEMD)	Yes 🗸
Charger Card	Box Reference	200XXXX
	Box serial number	200XXXX
	Box designation	e-RTU2020
	Time synchronization (Protocols)	Local
	Si	ave

Settings	Possibilities	Definitions
Cabinet language	English	
	English	
	Spanish	
UI standby	No	Local UI indicator lights off in <u>remote</u> mode at the end
	Yes	of "Time before standby".
		Only the "Equipment in standby" or "equipment fault"
		indicator lights are on.
Time before standby	10 to 600s	
Date recorded maintenance events (DRME)	No	Registration of a date event when the day is changed
	Yes	
Cabinet Reference		ensto cabinet code
Cabinet serial number		To be entered for after-sales service contacts
Cabinet description		Free field for cabinet name
		Default name: e-RTU2020
Time synchronisation (Protocols)	Local	Time adjustment by protocol if required by SCADA
	UTC-12 to UTC+14	

4.3.19.2 Anti Rebound Tab

This tab allows you to configure the anti-rebound times for Reserve inputs (see §2.3.2.e) and digital inputs (see §1.2.4)

These inputs can be connected to various sensors by the user, it is sometimes necessary to adjust the input's sensitivity.

Example: anti-rebound of 1 sec for a door contact to prevent unintentional status changes due to vibrations (a truck passing nearby) or atmospheric factors (wind).





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You are logged in as Administrator

ENSTO	Maintenance	
e-RTU2020	Anti Rebound Inputs	
A Return	Libelle reserve 1 (ms) 0	
General configuration	Libelle reserve 2 (ms)	
Anti Rebound Inputs	Libelle reserve 3 (ms) 0	
Charger Card	Libelle reserve 5 (ms) 0	
	Libelle reserve 6 (ms) 0	
	Libelle digital input 2 (ms) 100	
	Libelle digital input 3 (ms) 100	
	Libelle digital input 4 (ms)	
	Libelle digital input 5 (ms) 100	
	Save	

Settings	Possibilities	Definitions
Anti rebound	0 to 1000 ms	
(for each item)		

4.3.19.3 Charger card tab

This tab enables you to configure allows the power supply settings (Charger card)

U 💥 💶	You are logged in as Administrator \rightarrow
ENSTO	Maintenance
e-RTU2020	Charger Card
ta Return	LV / ELV transformer ratio 230V / 26V transformer
General configuration	Coefficient for LV calibration (%) 100
Anti Rebound Inputs	MV network voltage (V) 20000
Charger Card	Imax Radio (mA)
	Time Before Radio Outage (mn) 3
	Save

Settings	Possibilities	Definitions
LV / ELV transformer ratio	230 V / 26 V transformer 58 V / 26 V transformer 135 V / 26 V transformer 101 V / 26 V transformer 270 V / 26 V transformer	Definition of the transformation ratio value for the cabinet's LV/ELV transformer
Coefficient for LV calibration	1 to 200%	Correction of the LV measurement error. The coefficient is calculated automatically by a simple measurement of the voltage at the cabinet's input. See §4.2.7
MV network voltage	5,000 to 30,000 V	MV network voltage for calculating the MV voltage analog input with the LV measurement
Prolonged lack of LV time	1 to 48 h	Time before outage
Imax Radio	200 to 4000 mA	Defines the maximum current consumed by the
Time Before Radio Outage	1 to 1000 mn	communication device (radio) when transmitting. In the event that this threshold is exceeded during the "Time Before Radio outage", the device power supply is cut off

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4.3.20 Administrator Settings Tab (Administrator user only)

4.3.20.1 General Configuration Tab

This tab defines and allows the cabinet's specific features and options to be configured These settings are factory-set on the basis of the cabinet's configuration and the customer's requirements

14 米 💶			You are logged in as Administrator \longrightarrow
ENSTO	Administra	tor Settings	
e-RTU2020	General co	nfiguration	
A Return	Box Type	Underground	~
General configuration	Display type	Type 1 (internal fault)	~
Daily reboot	Up and downstream U Leds (Type 2 disp.)	No	~
	Fault visualization (Earth / phase)	Type 2 (Green/Red)	~
Command umers	Automation selection method	BP ASF/ASPP	~
Absence SF6	Coefficient for voltage calibration Measuring unit Ph1 (%)	100	
	Coefficient for voltage calibration Measuring unit Ph2 (%)	100	
	Coefficient for voltage calibration Measuring unit Ph3 (%)	100	
	Outdoor SF6 indicator	No	*
	S	ave	

Settings	Possibilities	Definitions
Cabinet type	Underground Overhead (Auguste)	Determines the type of cabinet based on its operation
	Overhead (Other)	operation
Display type	Type 1 (internal fault)	Definition of the Display board installed in the
	Type 2	cabinet.
		Type 2 display for overhead only
Upstream and downstream voltage	Yes	Upstream voltage/downstream voltage availability
LEDs (Type 2 disp.)	No	LED management options with Type 2 display only
Fault Visualization (Earth/phase)	Type 1 (Red/Red+Green)	Red light for an Earth fault (homopolar)
		Red+green lights for a Phase fault (polyphase)
	Type 2 (Green/Red)	Green light for an Earth fault (homopolar)
		Red light for a Phase fault (polyphase)
Automation selection method	ASF/APSS button	Automation enabled by pressing the button
	ASF/APSS + COMMAND VALIDATION	Automation enabled by pressing the button and the
	bottom	

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4.3.20.2 Daily Reboot Tab

This tab allows daily Reboots (restarts) of the cabinet to be enabled and configured.

LI 💥 💶		You are logged in as Administrator
ENSTO	Administra	tor Settings
e-RTU2020	Daily	reboot
the Return	Daily reboot CPU	Inactive
General configuration	Hour	0
Daily reboot	Minute	
Command timers	Daily reboot Peripherals Hour	0
Absence SF6	Minute	0
	Sa	ave
Settings	Possibilities	Definitions
Daily reheat CPU	Inactivo	Daily raboat of the CPU

Settings	Possibilities	Demilitions
Daily reboot CPU	Inactive	Daily reboot of the CPU
	active	Equivalent to a reboot command (see System
		configuration guide)
Daily reboot Peripherals	Inactive	Daily reboot of peripherals (display boards, charger,
	active	fault detection, communication device, etc.)

4.3.20.3 Command time delay tab

This tab allows the commands to be set

LI 💥 💶	You are logged in as Administrator 🕞
ENSTO	Administrator Settings
e-RTU2020	Command timers
🔄 Return	command pulse duration (ms) 10000
General configuration	command monitoring time (ms) 10000
Daily reboot	time no complementarity Channel A (ms) 10000
Command timers	time no complementarity Channel G (ms) 10000
Absence SF6	time no complementarity Channel D (ms) 10000
	Save

Settings	Possibilities	Definitions
Command pulse duration	10 to 10000 ms	Period during which the control voltage is applied at the opening and closing command output
Command monitoring time	10 to 10000 ms	Period during which the return of the position for signalling transmission to SCADA is expected (at the end of the period, the position is transmitted)

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No complementarity time (By channel)	10 to 10000 ms	Time during which no complementarity information is permitted (This corresponds to the max. time for physically executing the switching operation)	

4.3.21 System Tab

This tab allows the firmware to be updated, the configuration to be loaded (PC -> cabinet) or downloaded (Cabinet ->PC), the time to be set for the cabinet and the entire system to be configured (Users, Firewall, VPN tunnel, etc.)

See System configuration guide

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5 MAINTENANCE

- 5.1. Preventive
- 5.2. Corrective

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5.1 **PREVENTIVE**

The e-RTU2020 cabinet allows the connections and data transmitted via IP communication devices to be analysed by means of the configuration PC.

5.1.1 IP analyzer

The "IP Analyzer" tab allows the connections to the 3 IP ports of the e-RTU2020 cabinet to be identified and quantified.

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5.1.2 IP traces

The "IP traces" tab allows the protocol frames of IP-based protocols (IEC 104, DNP3 IP) to be displayed.

Filters provide assistance for decoding frames on the basis of protocols. Exchanges logged may be saved in a .txt file for analysis.

日 米 💶					You are	e logged in as A	Administrato	\rightarrow
ENSTO			Vis	ualizatio	n			
e-RTU2020				IP traces				
Equipment		[
Fault	Interface : eth0 v Port	: 2404	Refresh (ms	s) : 2000	Automatic sc	croll		
Measurements and Counters	Decoding : ● No O IEC Display IEC 104 : ✔ I-	C 104 O DNP3 Frame 🔽 U-Fra	ame 🔽 S-Frame					
Inputs / Outputs	Start				Clear	Sa	ave	
Events	Date Timestamp	IP source	Destination IP	Source Port	Destination Port	Length	Content	
Local order								
Downloading								
IP tester								
IP analyzer								
IP traces								

See protocol notices for more information on decoding.

5.1.3 Visualization of Dated Recorded Maintenance Events (DRME):

The cabinet stores a stack of a minimum of 10,000 dated events (1MB file), which can be viewed via the "Dated Recorded Maintenance Event (DRME)" HTML page.

Should the capacity be exceeded, the file is saved by after-sales service and a new one is created.

It is impossible to delete an event.

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					ت ^م
ENSTO			Vi	sualization	
e-RTU2020				Events	
Equipment	2000/01/02	00:47:13.68	322	Restart Runtime	
Fault	2000/01/02	01:19:45.10	322	Restart Runtime	
Measurements and	2000/01/02	02:42:15.68	242	Start equipment	
Counters	2000/01/02	02:42:15.94	340	End digital output 1 (Libelle digital output 1)	
Inputs / Outputs	2000/01/02	02:42:15.94	341	End digital output 2 (Libelle digital output 2)	
Events	2000/01/02	02:42:15.94	342	End digital output 3 (Libelle digital output 3)	
Local order	2000/01/02	02:42:15.94	16	AC power supply ON	
Downloading	2000/01/02	02:42:29.69	7	Remote Mode	
IP tester	2000/01/02	02:42:30.49	6	Local Mode	
IP analyzer	2000/01/02	02:42:44.0	51	Selected channel A for manoeuvring	
IP traces	2000/01/02	02:42:45.16	67	Request of manual closing channel A	
Serial traces	2000/01/02	02:42:49.74	99	Switch Closing channel A	
Communication and Protocols	2000/01/02	02:42:55.79	7	Remote Mode	
Automation	2000/01/02	02:42:56.55	6	Local Mode	
Fault Detection	2000/01/02	02:43:40.4	7	Remote Mode	
Delays and Alarms	2000/01/02	02:43:40.68	6	Local Mode	
Cyclic Measurement	2000/01/02	02:43:41.37	52	Selected channel B for manoeuvring	
Recording	2000/01/02	02:43:42.58	68	Request of manual closing channel B	
Telemetry	2000/01/02	02:43:47.26	100	Switch Closing channel B	
I/O Label	2000/01/02	02:43:47.43	51	Selected channel A for manoeuvring	
TSS Fault Grouping	2000/01/02	02:43:51.5	243	Display test	-
	\				

The DRMEs are events relating to the operation of the network and the cabinet

It is possible to save the events file (.csv) with the aid of the **"Download"** button.

A list of DRMEs and their numbers appears below.

code	Label
1	No voltage >2h
2	Charger card fault
3	Prolonged lack of voltage
4	Blacklisted number
5	drme stack full
6	Local
7	Remote
8	12 V fault (start)
9	12 V fault (end)
10	DC voltage fault (start)
11	DC voltage fault (end)
12	Battery fault (start)
13	Battery fault (end)
14	Autonomous supply backup (start)
15	Autonomous supply backup (end)
16	LV available
17	No LV

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18	Red fault channel A	
19	Red fault channel B	
20	Red fault channel C	
21	Red fault channel D	
22	Red fault channel E	
23	Red fault channel F	
24	Red fault channel G	
25	Red fault channel H	
26	Green fault channel A	
27	Green fault channel B	
28	Green fault channel C	
29	Green fault channel D	
30	Green fault channel E	
31	Green fault channel F	
32	Green fault channel G	
33	Green fault channel H	
418	Earth fault channel A	
419	Earth fault channel B	
420	Earth fault channel C	
421	Earth fault channel D	
422	Earth fault channel E	
423	Earth fault channel F	
424	Earth fault channel G	
425	Earth fault channel H	
34	Phase fault channel A	
35	Phase fault channel B	
36	Phase fault channel C	
37	Phase fault channel D	
38	Phase fault channel E	
39	Phase fault channel F	
40	Phase fault channel G	
41	Phase fault channel H	
42	Permanent transmission	
43	Selection of channel A for operation	
44	Selection of channel B for operation	
45	Selection of channel C for operation	
46	Selection of channel D for operation	
47	Selection of channel E for operation	
48	Selection of channel F for operation	
49	Selection of channel G for operation	
50	Selection of channel H for operation	
51	Manual opening request channel A	

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		÷.,
52	Manual opening request channel B	
53	Manual opening request channel C	
54	Manual opening request channel D	
55	Manual opening request channel E	
56	Manual opening request channel F	
57	Manual opening request channel G	
58	Manual opening request channel H	
59	Manual closing request channel A	
60	Manual closing request channel B	
61	Manual closing request channel C	
62	Manual closing request channel D	
63	Manual closing request channel E	
64	Manual closing request channel F	
65	Manual closing request channel G	
66	Manual closing request channel H	
67	Remote controlled opening request channel A	
68	Remote controlled opening request channel B	
69	Remote controlled opening request channel C	l
70	Remote controlled opening request channel D	
71	Remote controlled opening request channel E	
72	Remote controlled opening request channel F	
73	Remote controlled opening request channel G	
74	Remote controlled opening request channel H	
75	Remote controlled closing request channel A	l
76	Remote controlled closing request channel B	l
77	Remote controlled closing request channel C	l
78	Remote controlled closing request channel D	
79	Remote controlled closing request channel E	l
80	Remote controlled closing request channel F	l
81	Remote controlled closing request channel G	
82	Remote controlled closing request channel H	
83	Channel A opening	
84	Channel B opening	
85	Channel C opening	l
86	Channel D opening	l
87	Channel E opening	
88	Channel F opening	
89	Channel G opening	l
90	Channel H opening	l
91	Channel A closing	l
92	Channel B closing	l
93	Channel C closing	I

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94	Channel D closing
95	Channel E closing
96	Channel F closing
97	Channel G closing
98	Channel H closing
99	Blocked channel A (start)
100	Blocked channel B (start)
101	Blocked channel C (start)
102	Blocked channel D (start)
103	Blocked channel E (start)
104	Blocked channel F (start)
105	Blocked channel G (start)
106	Blocked channel H (start)
107	Blocked channel A (end)
108	Blocked channel B (end)
109	Blocked channel C (end)
110	Blocked channel D (end)
111	Blocked channel E (end)
112	Blocked channel F (end)
113	Blocked channel G (end)
114	Blocked channel H (end)
115	Start signalling closing heartbeat channel A
116	Start signalling closing heartbeat channel B
117	Start signalling closing heartbeat channel C
118	Start signalling closing heartbeat channel D
119	Start signalling closing heartbeat channel E
120	Start signalling closing heartbeat channel F
121	Start signalling closing heartbeat channel G
122	Start signalling closing heartbeat channel H
123	Start signalling opening heartbeat channel A
124	Start signalling opening heartbeat channel B
125	Start signalling opening heartbeat channel C
126	Start signalling opening heartbeat channel D
127	Start signalling opening heartbeat channel E
128	Start signalling opening heartbeat channel F
129	Start signalling opening heartbeat channel G
130	Start signalling opening heartbeat channel H
131	End signalling closing heartbeat channel A
132	End signalling closing heartbeat channel B
133	End signalling closing heartbeat channel C
134	End signalling closing heartbeat channel D
135	End signalling closing heartbeat channel E

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126	End signalling closing boartboat channel E	
130	End signalling closing heartbeat channel G	
138	End signalling closing heartbeat channel H	-
130	End signalling opening heartheat channel A	-
140	End signalling opening heartbeat channel R	-
1/1	End signalling opening heartbeat channel C	-
142	End signalling opening heartbeat channel D	-
1/13	End signalling opening heartbeat channel F	-
143	End signalling opening heartbeat channel E	-
145	End signalling opening heartbeat channel G	-
146	End signalling opening heartbeat channel H	-
140	ASE configuration channel A	-
147	ASE configuration channel B	4
149	ASE configuration channel C	4
150	ASE configuration channel D	4
151	ASE configuration channel E	-
152	ASE configuration channel E	-
153	ASE configuration channel G	-
154	ASE configuration channel H	-
155	ASE configuration channel A green fault	-
156	ASE configuration channel B green fault	-
157	ASE configuration channel C green fault	-
158	ASE configuration channel D green fault	-
159	ASE configuration channel E green fault	-
160	ASF configuration channel F green fault	-
161	ASF configuration channel G green fault	-
162	ASF configuration channel H green fault	-
163	ASF configuration channel A red fault	-
164	ASF configuration channel B red fault	-
165	ASF configuration channel C red fault	-
166	ASF configuration channel D red fault	-
167	ASF configuration channel E red fault	-
168	ASF configuration channel F red fault	-
169	ASF configuration channel G red fault	1
170	ASF configuration channel H red fault	1
171	ASF function activation	1
172	ASF function deactivation	1
173	ASF turned on locally	1
174	ASF turned off locally	1
175	ASF turned on by remote control	1
176	ASF turned off by remote control	1
177	ASF opening request channel A	
		-

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178	ASF opening request channel B
179	ASF opening request channel C
180	ASF opening request channel D
181	ASF opening request channel E
182	ASF opening request channel F
183	ASF opening request channel G
184	ASF opening request channel H
185	ASF opening fault channel A
186	ASF opening fault channel B
187	ASF opening fault channel C
188	ASF opening fault channel D
189	ASF opening fault channel E
190	ASF opening fault channel F
191	ASF opening fault channel G
192	ASF opening fault channel H
193	Simplified APSS configuration
194	Complete APSS configuration
195	Change to APSS source 1
196	Change to APSS source 2
197	APSS direction: Src1 -> Src2
198	APSS direction: Src1 <-> Src2
199	APSS direction: Src2 -> Src1
200	APSS function activation
201	APSS function deactivation
202	APSS turned on locally
203	APSS turned off locally
204	APSS turned on by remote control
205	APSS turned off by remote control
206	No voltage APSS source 1
207	Voltage available APSS source 1
208	No voltage APSS source 2
209	Voltage available APSS source 2
210	APSS switching (start)
211	APSS switching (end)
212	Locking APSS switching (start)
213	Locking APSS switching (end)
214	APSS switching cancelled
215	APSS opening request channel A
216	APSS opening request channel B
217	APSS opening request channel C
218	APSS opening request channel D
219	APSS opening request channel E

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220	APSS opening request channel F
221	APSS opening request channel G
222	APSS opening request channel H
223	APSS closing request channel A
224	APSS closing request channel B
225	APSS closing request channel C
226	APSS closing request channel D
227	APSS closing request channel E
228	APSS closing request channel F
229	APSS closing request channel G
230	APSS closing request channel H
231	APSS active source opening fault
232	APSS backup source closing fault
233	Equipment reset
234	Equipment start-up
235	Display test
236	Urgent external fault (start)
237	Urgent external fault (end)
238	Non-urgent external fault (start)
239	Non-urgent external fault (end)
240	MV available (functional unit info) channel A
241	MV available (functional unit info) channel B
242	MV available (functional unit info) channel C
243	MV available (functional unit info) channel D
244	MV available (functional unit info) channel E
245	MV available (functional unit info) channel F
246	MV available (functional unit info) channel G
247	MV available (functional unit info) channel H
248	No MV (functional unit info) channel A
249	No MV (functional unit info) channel B
250	No MV (functional unit info) channel C
251	No MV (functional unit info) channel D
252	No MV (functional unit info) channel E
253	No MV (functional unit info) channel F
254	No MV (functional unit info) channel G
255	No MV (functional unit info) channel H
256	MV available (voltage sensor info) channel A
257	MV available (voltage sensor info) channel B
258	MV available (voltage sensor info) channel C
259	MV available (voltage sensor info) channel D
260	MV available (voltage sensor info) channel E
261	MV available (voltage sensor info) channel F

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262	MV available (voltage sensor info) channel G	
263	MV available (voltage sensor info) channel H	
264	No MV (voltage sensor info) channel A	
265	No MV (voltage sensor info) channel B	
266	No MV (voltage sensor info) channel C	
267	No MV (voltage sensor info) channel D	
268	No MV (voltage sensor info) channel E	1
269	No MV (voltage sensor info) channel F	1
270	No MV (voltage sensor info) channel G	
271	No MV (voltage sensor info) channel H	
272	DC electronic fault channel A	
273	DC electronic fault channel B	
274	DC electronic fault channel C	1
275	DC electronic fault channel D	
276	DC electronic fault channel E	
277	DC electronic fault channel F	
278	DC electronic fault channel G	
279	DC electronic fault channel H	
280	Electronic wiring board fault 1	
281	Electronic wiring board fault 2	
282	Detector board fault channel A	
283	Detector board fault channel B	
284	Detector board fault channel C	
285	Detector board fault channel D	
286	Detector board fault channel E	
287	Detector board fault channel F	
288	Detector board fault channel G	
289	Detector board fault channel H	
290	16 IO module fault	
300	48 V fuse fault	
301	Detector voltage fault	
302	Detector voltage fault	
303	Display board fault	
304	Converter board fault	
305	Measurement board fault	
306	CPU board fault	4
307	SPI start reserve 1	
308	SPI start reserve 2	4
309	SPI start reserve 3	4
310	SPI start reserve 4	-
311	SPI start reserve 5	
312	SPI start reserve 6	

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313	SPL end reserve 1	
314	SPL end reserve 2	
315	SPL end reserve 3	
316	SPI end reserve 4	
317	SPI end reserve 5	
318	SPI end reserve 6	
319	Detector voltage initialisation	
320	Detector voltage initialisation failure	
321	2 detectors voltage initialisation	
322	2 detectors voltage initialisation failure	
323	Restart Runtime	
324	Date and time programming	
325	Date event	
326	SCA function activation	
327	SCA function deactivation	
328	Digital input 1 start	
329	Digital input 2 start	
330	Digital input 3 start	
331	Digital input 4 start	
332	Digital input 5 start	
333	Digital input 1 end	
334	Digital input 2 end	
335	Digital input 3 end	
336	Digital input 4 end	
337	Digital input 5 end	
338	Digital output 1 start	
339	Digital output 2 start	
340	Digital output 3 start	
341	Digital output 1 end	
342	Digital output 2 end	
343	Digital output 3 end	
344	SF6 drop start	
345	SF6 drop end	
346	Equipment fault	
347	SPI heartbeat (start)	
348	SPI heartbeat (start)	
349	SPI heartbeat (start)	
350	SPI heartbeat (start)	
351	SPI heartbeat (start)	
352	SPI heartbeat (start)	
353	SPI heartbeat (start)	
354	SPI heartbeat (start)	

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355	SPI heartbeat (start)	
356	SPI heartbeat (start)	
357	SPI heartbeat (start)	
358	SPI heartbeat (start)	
359	SPI heartbeat (start)	
360	SPI heartbeat (start)	
361	SPI heartbeat (start)	
362	SPI heartbeat (start)	
363	SPI heartbeat (start)	
364	SPI heartbeat (start)	
365	SPI heartbeat (start)	
366	SPI heartbeat (start)	
367	SPI heartbeat (start)	
368	SPI heartbeat (start)	
369	SPI heartbeat (start)	
370	SPI heartbeat (start)	
371	SPI heartbeat (start)	
372	SPI heartbeat (start)	
373	SPI heartbeat (start)	
374	SPI heartbeat (start)	
375	SPI heartbeat (start)	
376	SPI heartbeat (start)	
377	SPI heartbeat (start)	
378	SPI heartbeat (start)	
379	SPI heartbeat (end)	
380	SPI heartbeat (end)	
381	SPI heartbeat (end)	
382	SPI heartbeat (end)	
383	SPI heartbeat (end)	
384	SPI heartbeat (end)	
385	SPI heartbeat (end)	
386	SPI heartbeat (end)	
387	SPI heartbeat (end)	
388	SPI heartbeat (end)	
389	SPI heartbeat (end)	
390	SPI heartbeat (end)	
391	SPI heartbeat (end)	
392	SPI heartbeat (end)	
393	SPI heartbeat (end)	
394	SPI heartbeat (end)	
395	SPI heartbeat (end)	
396	SPI heartbeat (end)	

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397	SPI heartbeat (end)
398	SPI heartbeat (end)
399	SPI heartbeat (end)
400	SPI heartbeat (end)
401	SPI heartbeat (end)
402	SPI heartbeat (end)
403	SPI heartbeat (end)
404	SPI heartbeat (end)
405	SPI heartbeat (end)
406	SPI heartbeat (end)
407	SPI heartbeat (end)
408	SPI heartbeat (end)
409	SPI heartbeat (end)
410	SPI heartbeat (end)
411	Initialisation of measurement recording file
412	DC closing Digital output 1
413	DC closing Digital output 2
414	DC closing Digital output 3
415	DC opening Digital output 1
416	DC opening Digital output 2
417	DC opening Digital output 3
418	Local closing command Digital output 1
419	Local closing command Digital output 2
420	Local closing command Digital output 3
421	Local opening command Digital output 1
422	Local opening command Digital output 2
423	Local opening command Digital output 3
424	Max. no. of login attempts admin mode
425	Reset bus
426	XML file initialisation fault
427	Motor fuse fault

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5.1.4 Fault display

Faults associated with the equipment or operation are displayed on the local panel.

In the event of a fault:

- The "Equipment in standby" LED stops flashing
- o The "Equipment fault" LED lights up red
- o The corresponding fault LED lights up red

The faults displayed by the LEDs are as follows

No.	Labels	Fault LED
9	Start Irregularity on electrical control power supply	No 48 V DC + internal fault
334	48 V fuse fault	No 48 V DC
18	No voltage	No AC voltage
7	Start Irregularity on 12 V DC	No 12 V DC
15	Start Autonomous Source Backup	External load outage
13	Start Irregularity Autonomous Source	Battery fault
1	Charger irregularity	Internal fault
315 to	Wiring board fault (tcd channel x)	Internal fault
322		
323 to	Wiring board x fault (external inputs)	Internal fault
324		
325 to	Sensor board fault channel x	Internal fault
332		
333	Eeprom parameters fault	Internal fault
334	48 V motor fuse fault	Internal fault
335	Voltage acquisition board 1 fault	Internal fault
336	Voltage acquisition board 2 fault	Internal fault
337	Display board fault	Internal fault

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338	Converter board fault	Internal fault	
347	Modem 1 fault	Internal fault	
348	Modem 2 fault	Internal fault	
349	CPU board fault	Internal fault	
357	Initialisation failure voltage board 1	Internal fault	
359	Initialisation failure voltage board 2	Internal fault	
369	Eeprom mac CPU fault	Internal fault	
370	Framework CPU fault	Internal fault	
371	Modem interface CPU fault	Internal fault	
372	Temperature sensor CPU fault	Internal fault	
373	Time stamper CPU fault	Internal fault	

5.1.5 CPU2020 firmware update:

Enables the new version of the CPU program to be downloaded

See System configuration guide

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5.2 **CORRECTIVE**

Location of protective fuses

Converter board (optional)

Should the equipment malfunction (to identify the problem see §5.1), it may be necessary to replace a cabinet component (electronic circuit board, battery, cable, etc.).

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To do this

- \circ $\,$ Open the cabinet's lower door $\,$
- o Disconnect the battery cable
- o Open the fuse holder
- Ensure that the equipment is not live (all LEDs off)
- Remove the faulty component
- Contact Ensto Novexia's After-sales Service

Accessing the converter/charger boards

Before undertaking any work, disconnect power to the cabinet (LV supply + battery).

Loosen (4 screws) and disconnect the local panel board to access the Charger and Converter boards

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You must remove the locking clips to remove the charger and converter boards.



Removing the converter/charger boards

Remove the clips holding the top and bottom of the board



Never use tools (screwdriver, spanner, etc.) that could damage the circuit boards

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Remove the board



Inserting converter/charger boards

Position the board and slide it onto the rack rails. connectors are connected



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Ensure that the male/female



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Reposition the locking clips at the top and bottom of the board and reconnect the cable.







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6 TECHNICAL SUPPORT

The company operates an after-sales service to assist with equipment installation and troubleshooting.

After-sales contact details:

ENSTO VILLEFRANCHE → +33 (0)474 656 160

ENSTO BAGNERES DE BIGORRE \rightarrow +33 (0)562 914 510

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7 END OF PRODUCT LIFE

ITI cabinets are covered by European Directive 2002/96/CE, which requires the use of professional processing facilities for waste electrical and electronic equipment (WEEE) to dispose of the cabinet and its components, as well as the reprocessing of the used battery in an appropriate collection facility.

If a local service provider is not available, the products may be returned to the manufacturer after consultation with them; make sure you have the technical components for the sub-assemblies and/or the products to recycle and contact the Ensto Novexia technical support team.



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Notes



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Service Après-Ventes / After-Sales Service

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