

ELECTRIC MOTORS UNIVERSAL PROTECTION DEVICE

UBZ-302



OPERATING MANUAL

Quality control system on the production complies with requirements ISO 9001:2008

Review the Operating manual before using the unit.
Store the unit in the operating environment for 2 hours before switching to the mains.
Do not use abrasives or organic compounds for cleaning (spirit, gasoline, solvents, etc.).



NEVER ATTEMPT TO REMOVE AND REPAIR THE UNIT.
Some of the unit components may be live.
NEVER ATTEMPT TO OPERATE THE UNIT WITH THE MECHANICAL DAMAGE OF THE HOUSING.
DO NOT LET WATER INTO THE UNIT.1

This unit is safe for use in case of compliance with operating rules.

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1 DESCRIPTION AND DESIGN

1.1 PURPOSE

1.1.1 General Information

UBZ-302 Universal Electric Motor Protection Device (UBZ) is designed for continuous monitoring of the circuit voltage parameters, the **RMS** values of phase/line currents of three-phase 380 V, 50 Hz electric equipment, and the electric motor insulation resistance values.

UBZ is designed for protection of asynchronous induction motors ranging from 2.5 kW to 30 kW that use integrated current transformers, including in circuits with insulated neutral.

UBZ provides for electric motor protection in case of:

- poor quality supply voltage (unacceptable voltage surges, phase loss, incorrect phase sequence and phase coincidence, phase/line voltage imbalance);
- mechanical overloads (symmetrical phase/line current overload);
- exceeding the negative sequence current threshold;
- phase current imbalance without overload, induced by the insulation fault inside the motor and/or the lead cable (the current imbalance factor is compared to the voltage imbalance factor using negative sequence);
- loss of motor torque ("dry stroke" for pumps) – protection based on the minimal starting and/or operating current;
- delayed motor start or rotor locking;
- abnormally low insulation level between the fixed coil and frame (testing before motor startup);
- ground fault of the stator coil during operation - protection against ground leakage current;
- motor thermal overload;
- coil overheating (measuring the coil temperature with integrated temperature sensors, or the body temperature with external temperature sensors).

For each protection type, automatic reclosing (ARC) can be enabled or disabled.

The device provides for electric equipment protection by means of controlling a magnetic starter (contactor) coil.

The device detects the presence of load currents when the load relay is open (when the load relay is open and the functional relay is in the star-delta mode). In this case the unit indicates fault of an external motor start contactor until the unit is totally de-energized.

UBZ provides for electric motor control through the following interfaces:

- two analogue inputs – “0-20 mA” and “0-10 V”;
- remote control channels (RS-232 and RS-485 interfaces);
- buttons on the front panel of the UBZ.

Communication

- control and parameter transfer via the RS-485 interface using the MODBUS protocol;
- control and parameter transfer via the RS-232 interface.

NOTE: simultaneous use of RS-485 and RS-232 is not allowed.

To use UBZ with a PC, you can use the “UBZ Control Panel” software, available from the website of NOVATEC-ELECTRO (http://www.novatek-electro.com/programmnoe_obespechenie.html).

The UBZ-302 Control Panel software is designed for monitoring the status of UBZ-302 devices and retrieving data from them via the RS-232 or RS-485 interface. The application allows saving (loading) various UBZ settings, collecting data and saving it for further analysis. Saved data can be viewed on a diagram for parameter comparison.

The software’s graphic user interface allows viewing the current status of various UBZ parameters in real-time. The flexible interface design allows any degree of customization.

1.1.2 Changes in the UBZ Specifications and Operation Depending on the Software Version.

Version 13 updates:

- additional parameters included in the consumed and displayed parameters list: load consumed gross, active and reactive power;
- added motor protection against phase (phases) loss with current control;
- added registers (read-only) containing values of the load consumed active power (nominal units) for each phase;
- added capability for remote start and stop of the motor via the RS-232/RS485 interface.

Version 15 updates:

- corrected error arising when measuring currents over 650A;
- when working with external transformers with rated current over 100A, current values (measured and calculated) are transferred via RS-232/RS485 in amperes.

Version 18 updates:

- when the motor is on (power voltage is supplied to motor), while the insulation resistance is not defined, the “--” code is displayed (when the motor insulation measurement circuit is connected).

Version 20 updates:

- added the option to control the motor using the analogue inputs “0 – 20 mA” and “0 – 10 V”;
- increased the reliability of data transfer through the MODBUS interface;
- added fault detection of EEPROM destruction;

- changed the algorithm for leaving the menu.

1.1.3 Limitations of UBZ Application and Correct Choice of Parameters

1.1.3.1 Using Internal Current Transformers.

When using internal current transformers, UBZ cannot be used to protect motors with wattage over 30 kW.

When measuring motor currents of 63A to 300A, the measurement error does not exceed 5%, while at currents over 320A, the current transformer core becomes saturated, and the measurement error increases rapidly. Regardless of the actual current value, the current measured by UBZ will not exceed 400A. Setting up certain programmable parameters (maximum current protection, delayed start and rotor locking, thermal overload) without regard to the saturation of current transformers will make protection tripping impossible.

For example, at $ind = 50$ (rated current), $i = P = 0$ (independent delay current protection), $i = S = 9$ (overcurrent protection tripping ratio), the overcurrent protection should trip at 450A. Due to the transformer saturation, the measured value of current will not exceed 380-400A, even in case of a short circuit in the coil and currents of over 1000A, and, therefore, UBZ will not de-energize the motor. In this case ($ind = 50$), the user should set the overcurrent tripping ratio at a value not exceeding 6.

1.1.3.2 Using External Current Transformers.

The rated current of external standard current transformers must be equal or higher than the rated current of the motor.

1.1.4 List of Abbreviations

ARC – automatic reclosing of the output contacts (autoreclosing)

MS – magnetic starter

PC – personal computer

CT – current transformer

MMSP – mode with minimal number of setting parameters

Itt – rated current of CT (specified when external CT are used. For example, if CT is type T-0.66 300/5, then Itt is 300 A)

In – rated current of motor. Usually, the current value shown on the motor plate, but a different current value may be set subject to specific operating conditions.

1.2 TECHNICAL SPECIFICATIONS

1.2.1 Main Technical Specifications

An overview is provided in Table 1.1.

The main technical specifications are provided in Table 1.2.

The parameters of the integrated relay output terminals are shown in Table 1.3.

Table 1.1 - General Information

Item	Unit	Value
Purpose of device	-	Control and distribution equipment. Asynchronous motor protection control.
Assembly (mounting) type	-	mounted on standard 35 mm DIN bar
Protection degree: - device - terminal block	-	IP40 IP20
Climate zone category	-	N3.1 (moderate, indoors)
Operating temperature range	°C	- 35 to +55
Storage temperature	°C	- 45 to +70
Pollution degree	-	III
Overvoltage category	-	III
Diameter of adapters on terminals	mm ²	0.5-2
Maximum torque of terminal screws	N*M	0.4

Table 1.2 – Main Technical Specifications

Rated supply voltage: three-phase	400 V, 50 Hz
Mains frequency, Hz	48-62
Rated currents range (when using integrated current transformers), A	5-63
Voltage hysteresis, (phase/line), V	10/17
Thermal hysteresis, % of accumulated heat at shutdown	33
Current tripping threshold detection accuracy, % of rated current, ≤	2
Voltage tripping threshold detection accuracy, V, at least	3
Voltage based phase imbalance detection accuracy, V, at least	3
Minimum operational voltage: - single-phase voltage power supply, with connected neutral wire, V, at least - three-phase power supply voltage, V, no more than	180 450

Main outputs - load relay – two groups of changeover contacts for motor starter control - 8A, 250V at $\cos \varphi=1$; - functional relay – one group of changeover contacts - 16 A, 250 V at $\cos \varphi=1$ (relay function assigned by the user)	
Analog inputs - two analog inputs for temperature sensors (type Pt100, Ni100, Ni120) - analog input for sensor with 0-10 V output - analog input for sensor with 4 mA (0mA) – 20 mA output - three analog inputs for standard CT with 5A output (type T-0.66 or similar) - input for differential current transformer (zero sequence transformer)	
Temperature sensor resolution, °C	1
Power consumption (under load), VA, no more than	5,0
Weight, kg, no more than	0,5
Dimensions (figure 1.1) - nine S type modules Mounting – on a standard 35 mm DIN bar Mounting position – any	

Table 1.3 – Characteristics of output terminals of integrated relays

Relay	Operation mode	Max. current at U~250 V	N of tripping x 1000	Max. commutated power	Max. additional alternating voltage	Max. current at Uconst=30 V (N of tripping)
functional relay	$\cos \varphi = 0.4$ $\cos \varphi = 1.0$	5 A 16 A	100	4,000 VA	440/300 V	3 A
load relay	$\cos \varphi = 0.4$ $\cos \varphi = 1.0$	2 A 8 A	100 100	1,000 VA	460 V	3 A (50,000)

UBZ-302 complies with requirements:

IEC 60947-1:2004, IDT; IEC 60947-6-2:1992, IDT; CISPR 11:2004, IDT; IEC 61000-4-2:2001, IDT

UBZ-302 conforms to the requirements:

Hazardous substances in excess of maximum allowable concentration – absent.

1.2.2 Measured and calculated parameters output to the display device*, their measurement limits and tolerances are provided in Table 1.4.

NOTE: - Display devices include:

- two three-digit seven-segment indicators on the front panel of UBZ;
- PC connected via one of the UBZ interfaces (MODBUS, RS-232).

Table 1.4 – Measured and Calculated Parameters

Measurement Functions	Range	Accuracy	Mnemonics	Address	Units of measurement used for data transfer
Currents					1/10 A*****
Phase currents RMS values, A	0.5-630	2%	<i>iF1</i> , <i>iF2</i> , <i>iF3</i>	100,101, 102	
Zero sequence current RMS value, A	0.3-5,0	2%	<i>iF0</i>	103	
Each phase average current value at the time specified in tSi			<i>iS1</i> , <i>iS2</i> , <i>iS3</i>	104,105, 106	
Maximum average current value for each phase obtained since the last power on. All average values can be reset using the (RES/MEM/SEL) button at the time of max average current value output for any phase (the new value assigned will be the real-time average current value for corresponding phase).	<3 ltt > 3 ltt	2% 10%	<i>in1</i> , <i>in2</i> , <i>in3</i>	107,108, 109	

Motor starting current (phase average)	<3 ltt	2%	<i>iPU</i>	110	1/10 A*****
Overcurrent (phase average)	> 3 ltt	10%		112	
Start time, sec Start time is time from the moment when all three phase currents exceed 1.2In and up to the moment when the three currents drop below 1.2In. Maximum phase current achieved during this period is the maximum starting current.	0.1-600		<i>iPE</i> <i>tPU</i>	111	
Negative sequence current (current imbalance), A.	0.2-200	5%	<i>ioP</i>	113	
Voltage					
Phase voltages RMS values (defined by connecting zero wire to the UBZ device), V	100-300	3 V	<i>UF 1,</i> <i>UF2,</i> <i>UF3</i>	114,115 116	V
Line voltage RMS values, V	100-475	5 V	<i>UL 1,</i> <i>UL2,</i> <i>UL3</i>	117,118 119	
Positive-sequence voltage, V	100-300	3 V	<i>UPP</i>	120	
Negative-sequence voltage, V	3 -300	3 V	<i>UP</i>	121	
Zero-sequence voltage (vector sum of three phase voltages, divided by three), (defined when zero wire is connected to the UBZ device), V.	3-100	3 V	<i>UnP</i>	122	
Miscellaneous					
Sensor 1 temperature (sensor type assigned according to Table 1.5), °C *	-40 to 100	1°C	<i>td 1</i>	123	5,000 – sensor not on
Sensor 2 temperature (sensor type assigned according to Table 1.5), °C *	-40 to 220	1°C	<i>td2</i>	124	1,000±10– sensor short-circuited 2,000±10– sensor fault
Current value at (4-20) mA input, mA	0-25	2%	<i>in i</i>	125	1/100 mA
Voltage value at 0-10 V analog input	0-10 V	2%	<i>inU</i>	126	1/10 V
Equipment operation time counter, days	0-999		<i>Str</i>	127	
Mains frequency, Hz	45-65	1%	<i>FFF</i>	128	1/10 Hz
Operation time before overload de-energizing (indicates time left before protection triggers thermal overload de-energizing), seconds	0-600	1 s	<i>tOP</i>	129	seconds
Time before ARC delay termination, seconds**	0-900	1 s	<i>tAP</i>	130	seconds
Wait time after overload de-energizing (indicates wait time before system restart is permitted after being locked by thermal protection), seconds ***	0-900	1 s	<i>tEP</i>	131	seconds
Motor insulation resistance, MOhm ****	0-19.9	10%	<i>r id</i>	132	'00 kOhm
Motor thermal balance Read-only parameter via RS-232 or RS-485 interface	1,100 thousand corresponds to 100% of accumulated heat at which the motor is de-energized if heat overload tripping is on (p. 1.2.5.7)			133, 134	
Gross power, kVA*****	0-5,000	5%	<i>POt</i>	135, 136	'0 W
Active power, kW*****	0-5,000	5%	<i>POA</i>	137, 138	
Reactive power, kVAR*****	0-5,000	5%	<i>POJ</i>	139, 140	'0 W
Phase A voltage/current angle cos*1000 Read-only parameter via RS-232 or RS-485 interface	0-1,000	5%		141, 142	
Phase B voltage/current angle cos*1000 Read-only parameter via RS-232 or RS-485 interface	0-1,000	5%		143,144	
Phase C voltage/current angle cos*1000 Read-only parameter via RS-232 or RS-485 interface	0-1,000	5%		145,146	

Table 1.4, continued

* If the temperature value exceeds the specified limit, the value indicator displays an error code as per Table 2.8.
 ** If automatic reclosing is forbidden, “noL” is displayed on the indicator.
 *** If the time before thermal overload safety de-energizing or the wait time before system start permit (ttP) has not been defined (over 900 sec), “---” code is displayed. If protection operation is forbidden, “noL” is displayed.
 **** If the motor insulation resistance exceeds 20 MOhm, the value indicator displays code “ 1_ ” (numerical “one” with a point in the higher digit).
 When the motor is on (power voltage supplied to the motor), the insulation resistance is not defined, and “---” code is displayed (when the motor insulation measurement circuitry is connected).
 ***** If the power consumed by the load exceeds 999 kW (kVA, kVAr), then the MW (MVA, MVAR) value is displayed on screen with a “n”-shaped point in the middle digit. For example, if the display shows “3n4”, it means 3.4 MW (MVA, MVAR).
 ***** Note. In software version 15, when using external transformers with rated current over 100A, the current values (measured and calculated), except for the zero sequence current (ground fault), are transferred in A, via the RS-232/RS485 interface.

1.2.3 Programmable parameters and their variability ranges are provided in Table 1.5.

Table 1.5 - Programmable parameters

Set and read parameters	Mnemonics	Min.	Max.	Factory setting	Operation	Address
Transformers						
CT in use	tPt	0	1	0	0-using integrated CT 1-using external CT	150
CT rated current, A	tnt	20	800	100	For external CT	151
Miscellaneous						
Motor rated current, A	ind	0	630	0	0-current value not set: UBZ will not activate load relay (p.2.3.7).	152
Average current measurement time, seconds	t5i	10	600	60	Time during which the average current value is measured (parameters iS1, iS2, iS3 from Table 1.4)	153
Overcurrent protection						
Overcurrent protection type	i = P	0	5	0	0-protection with independent time delay Protection types with dependent time delay: 1-SIT; 2-VIT (LTI); 3-EIT; 4-UIT; 5-RI	154
Overcurrent protection tripping setting value, ratio	i = 5	0.8	9.0	4.0	Assign the ratio to the motor rated current (active at i = P = 0).	155
Overcurrent protection tripping delay, seconds	i = t	0.3	600	10.0		156
Protection permission	i = r	0	2	2	0-protection forbidden 1- protection allowed, no ARC after tripping 2- protection allowed, ARC after tripping allowed	157
Order of overcurrent protection tripping relative to thermal overload protection	i = n	0	1	1	0-protection activated independent of thermal overload protection 1-in absence of thermal overload, overcurrent is indicated, but the overload relay is not tripped	158
Protection against ground faults (zero sequence current iF0)						
Current fault tripping setting, A	i_5	0.3	5.0	0.5	If the parameter is included in the MSM list, the default values are: 0,5 at In≤50 A; 1.0 at In>50 A	159
Protection tripping delay, seconds	i_t	0.3	2.0	1.0		160
Protection permission	i_r	0	2	2	0-protection forbidden	161

Set and read parameters	Mnemonics	Min.	Max.	Factory setting	Operation	Address
					1- protection allowed, no ARC after tripping 2- protection allowed, ARC after tripping allowed	
Negative sequence current protection						
Tripping setting, %	<i>i05</i>	5	20	10	Percents of rated current	162
Protection tripping delay, seconds	<i>i0t</i>	0.3	10.0	5.0		163
Protection permission	<i>i0r</i>	0	2	2	0-protection forbidden 1- protection allowed, no ARC after tripping 2- protection allowed, ARC after tripping allowed	164
Analysis of causes for negative sequence current protection tripping						
Negative sequence current ratio divided by negative sequence voltage ratio	<i>i05</i>	2	4	2		165
Analysis permission	<i>i0r</i>	0	1	1	0- analysis off 1- analysis on	166
Thermal overload (motor thermal model)						
Protection permission	<i>dt r</i>	0	2	2	0-protection forbidden 1- protection allowed, no ARC after tripping 2- protection allowed, ARC after tripping allowed	167
Double overcurrent overload protection tripping time, seconds	<i>dt t</i>	10	120	60		168
Time increase ratio with a stopped motor	<i>dt P</i>	1.0	4.0	1.0	Compensating for the increased cooling time with a stopped motor	169
Undercurrent phase protection						
Tripping setting, %	<i>i₅</i>	11	90	20	Minimum operating current tripping threshold, % of rated current	170
Protection tripping delay, seconds	<i>i₅ t</i>	1	100	5		171
Protection permission	<i>i₅ r</i>	0	2	2	0-protection forbidden 1- protection allowed, no ARC after tripping 2- protection allowed, ARC after tripping allowed	172
Delayed start, rotor blocking						
Tripping setting, ratio	<i>PP5</i>	1.5	7.0	5.0	Ratio relative to rated current	173
Delayed start protection tripping delay, seconds	<i>PPt</i>	1	600	10	Motor start time	174
Rotor blocking protection tripping delay, seconds	<i>Pbt</i>	0,3	300	1,0		175
Protection permission	<i>PPr</i>	0	2	1	0-protection forbidden 1- protection allowed, no ARC after tripping 2- protection allowed, ARC after tripping allowed	176
Voltage protection						
Minimum line voltage, V	<i>U₅</i>	270	415	320		177
Minimum voltage protec-	<i>U₅ t</i>	5	30	10		178

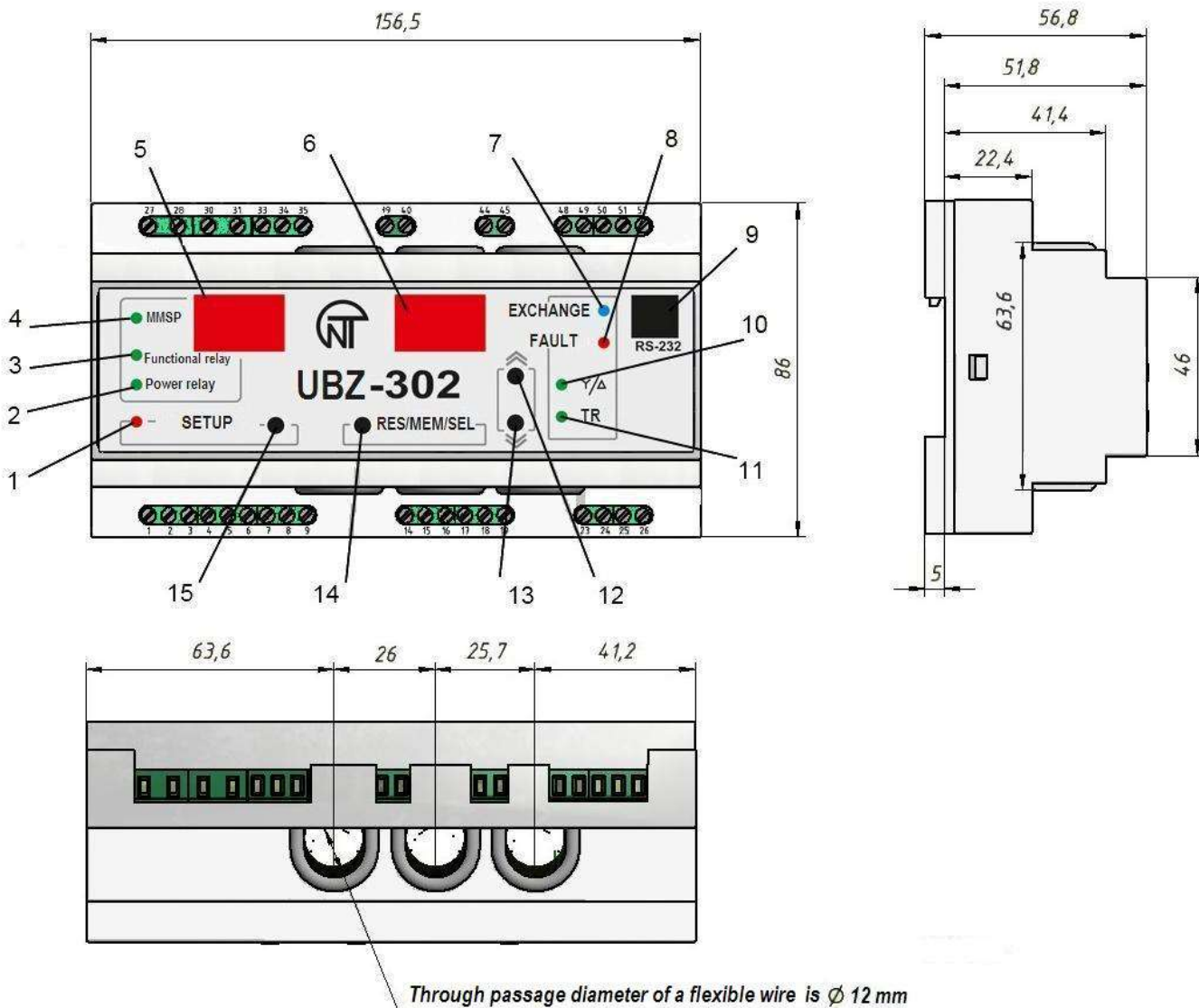
Set and read parameters	Mnemonics	Min.	Max.	Factory setting	Operation	Address
tion tripping delay, seconds						
Minimum voltage protection permission	$U_{\pm r}$	0	2	2	0-protection forbidden 1- protection allowed, no ARC after tripping 2- protection allowed, ARC after tripping allowed	179
Maximum line voltage, V	$U^{\pm 5}$	330	475	415		180
Maximum line voltage protection tripping delay, seconds	$U^{\pm t}$	1	10	2		181
Maximum line voltage protection permission	$U^{\pm r}$	0	1	2	0-protection forbidden 1- protection allowed, no ARC after tripping 2- protection allowed, ARC after tripping allowed	182
Line voltage imbalance, V	$U^{\pm 5}$	15	120	35	Negative sequence	183
Line voltage imbalance protection tripping delay, seconds	$U^{\pm t}$	1	30	5		184
Line voltage imbalance protection permission	$U^{\pm r}$	0	2	2	0-protection forbidden 1- protection allowed, no ARC after tripping 2- protection allowed, ARC after tripping allowed	185
Phase sequence order protection permission	$U^{\pm r}$	0	2	1	0-protection forbidden 1- protection allowed, no ARC after tripping 2- protection allowed, ARC after tripping allowed	186
Motor operation and automatic reclosing (ARC)						
ARC time after undercurrent protection tripping, seconds	ARC_n	0	900	600		187
ARC time, seconds	ARC_t	0	900	5		188
ARC prohibition for all faults (except voltage faults)	ARC_r	0	1	1	0-ARC forbidden 1-ARC allowed The value of ARC_r applies to all fault types except voltage faults. To forbid ARC after voltage faults, use the parameters $U^{\pm r}$, $U_{\pm r}$, $U^{\square r}$	189
Motor operation permission after UBZ power-on	AP_d	0	2	1	0 – manual motor start using the UBZ front panel 1- motor start after ARC time 2- motor start after 2 seconds	190
Motor control via UBZ front panel	AC_d	0	3	0	0 - forbidden 1 – motor start allowed 2 – emergency motor stop allowed 3 – motor start and stop allowed (see p. n. 2.4.7)	191
Temperature control						
Temperature sensor 1 type and temperature control permission	CT_r	0	2	0	0 – off 1- integrated in motor (protection tripping happens at sensor resistance over 1.7 kOhm) 2 – PTC (1 kOhm at 25°C)	192
Motor de-energizing temperature	CT_{15}	0	100	80		193

Set and read parameters	Mnemonics	Min.	Max.	Factory setting	Operation	Address
Sensor 1 temperature correction	[<i>lc</i>	-9	9	0		194
Temperature sensor 2 type and temperature control permission	[<i>2r</i>	0	3	0	0 – off 1 – type Pt100 2- type Ni100 3- type Ni120	195
Motor de-energizing temperature	[<i>25</i>	0	220	180		196
Warning temperature	[<i>2A</i>	0	220	170		197
Sensor 2 temperature correction	[<i>2c</i>	-9	9	0		198
ARC after protection tripping	[<i>PA</i>	1	2	2	1- ARC after protection tripping forbidden 2- ARC after protection tripping allowed	199
Reaction to temperature sensor failure	[<i>cr</i>	0	1	0	0- warning and continued operation; 1- warning and motor stop;	200
Motor insulation resistance						
Minimum motor insulation resistance protection	<i>r id</i>	0	20	5	0-off 5-motor does not start at insulation resistance under 500 kOhm, ARC allowed 10- motor does not start at insulation resistance under 1,000 kOhm, ARC allowed 15- motor does not start at insulation resistance under 500 kOhm, ARC forbidden 20- motor does not start at insulation resistance under 1,000 kOhm, ARC forbidden	201
Miscellaneous						
Minimal number of set parameters mode	<i>5 in</i>	0	1	1	0-mode activated 1-mode deactivated The mode can only be changed in engineer access mode.	202
Indication on UBZ display before motor power-on	<i>5 iP</i>	0	2	1	0- linear voltage Uab 1-insulation resistance rid 2-ARC countdown	203
Parameter indication mode	<i>5 iL</i>	0	1	1	0-parameter value displayed continuously 1-parameter value displayed during 15 seconds	204
Functional relay operation mode	<i>rr5</i>	0	2	0	0-relay used as signaling relay 1- relay used as time relay (closed after a time specified in rrt after the load relay closes) 2-relay used for star-delta motor switching (after time specified in rrt (address 206), the load relay is open, and after time specified in rrt (address 206) + Ftt (address 218), the functional relay is closed).	205
Timer, seconds	<i>rrt</i>	0	300	30	see p. 2 and p.3 in parameter <i>rr5</i>	206
Equipment uptime, days	<i>tbu</i>	0	999	0	*uptime transferred in hours if using the MODBUS/RS-232 interface	207
Motor uptime, days	<i>tcd</i>	0	999	0	*uptime transferred in hours if using the MODBUS/RS-232 interface	208




Set and read parameters	Mnemonics	Min.	Max.	Factory setting	Operation	Address
User access code	<i>LDC</i>	0	9	0	0 – keypad unlocked 1-9 – user password	209
Engineer access code	<i>PRS</i>	000	999	123	000 – engineer access granted 000-999 – engineer password	210
Reset to factory settings	<i>PPP</i>	0	1	0	After entering 1 and exiting the parameter setting mode, factory settings are restored	211
Serial interface parameters (RS-485/ RS-232)						
UBZ communication address	<i>r5A</i>	1	247	1		212
Transfer rate	<i>r5S</i>	0	1	0	0: 9,600 baud; 1: 19,200 baud; The transfer rate only changes after the device is powered off and on again.	213
Adapter reaction to loss of link	<i>r5P</i>	0	3	0	0- continued operation, no warning 1- warning, continued operation 2- warning, motor stop, ARC allowed after link restored 3- warning, motor stop, ARC forbidden after link restored	214
Response timeout detection, seconds	<i>r5D</i>	0	120	0	0-forbidden	215
UBZ communication via serial channel	<i>rPP</i>	0	2	0	0- communication forbidden 1- communication via RS-232 2- communication via MODBUS	216
Device version	<i>rEL</i>			20		217
Functional relay mode parameters Star-delta mode.						
Switching, seconds	<i>FtE</i>	0,1	2,0	0,4	Time between load relay opening and functional relay closing	218
Motor phase (phases) loss, with current control						
Phase loss protection tripping delay, seconds	<i>ibt</i>	0,3	10	0,5		219
Protection permission	<i>ibr</i>	0	2	1	0-protection forbidden 1- protection allowed, no ARC after tripping 2- protection allowed, ARC after tripping allowed	220
Remote motor start and stop using the RS-232/RS485 interfaces	<i>dUd</i>	0	2	0	0-remote control forbidden 1-remote control allowed, motor start after UBZ power-on allowed 2- remote control allowed, motor start after UBZ power-on forbidden until remote start command	221
0-20 mA analog input operation						
Upper threshold, mA	<i>R iE</i>	0	20,0	10,0		222
Lower threshold, mA	<i>R iB</i>	0	20,0	1,0		223
Control algorithm	<i>R iR</i>	0	2	0	0 – control off 1 – motor stops when current exceeds upper threshold and starts when current falls below lower threshold 2 – motor starts when current exceeds upper threshold and stops when current falls below lower threshold	224
Fault logging	<i>R iE</i>	0	1	0	0 – motor stop considered a fault, but not logged 1 – motor stop considered a fault and logged	225

Set and read parameters	Mnemonics	Min.	Max.	Factory setting	Operation	Address
0-20 V analog input operation						
Upper threshold, mA	<i>RUL</i>	0	10,0	5,0		226
Lower threshold, mA	<i>RULb</i>	0	10,0	1,0		227
Control algorithm	<i>RUA</i>	0	2	0	0 – control off 1 – motor stops when voltage exceeds upper threshold and starts when voltage falls below lower threshold 2 – motor starts when voltage exceeds upper threshold and stops when voltage falls below lower threshold	228
Fault logging	<i>RUE</i>	0	1	0	0 – motor stop considered a fault, but not logged 1 – motor stop considered a fault and logged	229

1.2.4 UBZ controls and dimensions are shown in Figure 1.1.



- 1 – SETUP - red LED, lit when UBZ in the parameter setting mode
- 2 – Power relay – green LED, lit when the load relay is closed
- 3 – Functional relay – green LED, lit when the functional relay is closed;
- 4 - MMSP – green LED – lit when the UBZ is working in the MMSP mode
- 5 – three-digit parameter mnemonic indicator:
 - point in the lowest digit is lit when the UBZ is in the engineer setting mode;

- point in the middle digit is lit when the setting parameter value is protected with the engineer password;
- point in the highest digit is lit when the setting parameter is not included in the MMSP list.
- 6 – three-digit parameter value indicator
- 7 – EXCHANGE – blue LED – lit during data exchange with PC
- 8 – FAULT – red LED:
 - when load relay is open, the LED is lit when UBZ is in a state of fault (blinking if ARC is allowed after fault);
 - when load relay is closed, the LED blinks when the motor is in a state of overcurrent or temperature overload, but the load relay opening time has not come yet
- 9 – outlet for connecting the UBZ to PC via RS-232
- 10 -  – green LED – lit when the UBZ functional relay is in the star-triangle mode (p. 2.4.3)
- 11 - TR – green LED – lit when the UBZ functional relay is in the time relay mode
- 12 -  button UP – scroll through displayed parameters in parameter read mode, and scroll through the menu in parameter setting mode
- 13 -  button DOWN - scroll through indicated parameters in parameter read mode, and scroll through the menu in parameter setting mode
- 14 - RES/MEM/SEL – write parameters in setting mode, switch between groups of displayed parameters in parameter read mode, reset
- 15 - button SETUP – enter parameter setting mode

NOTE -  - referred to as (S/D, star-delta)

Figure 1.1 – UBZ controls and dimensions

1.2.5 Protection Functions

1.2.5.1 Protection Types

UBZ provides the following types of electric motor protection:

- overcurrent phase protection;
- ground fault protection (zero sequence current);
- negative sequence current protection
- excess value of current negative sequence ratio divided by voltage negative sequence ratio protection;
- thermal overload protection;
- undercurrent phase protection;
- delayed start (rotor blocking) protection;
- coil overheating protection;
- overvoltage line protection;
- undervoltage line protection;
- line voltage imbalance (voltage negative sequence) protection;
- phase sequence protection;
- motor insulation minimum resistance protection.

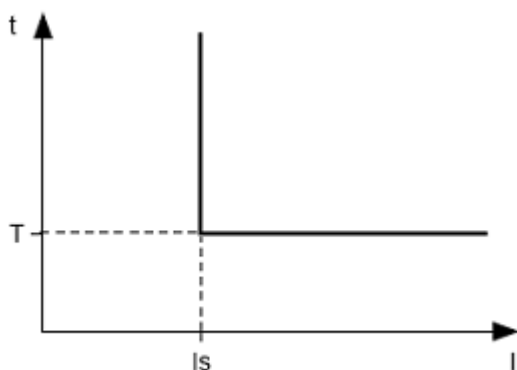
1.2.5.2 Overcurrent Protection

Overcurrent phase protection is of three-phase type. It is activated when one, two, or three current values reach the tripping threshold.

The maximum phase current protection is of three-phase type. It is engaged when one, two, or three current values reach the tripping threshold.

The protection has a time delay setting. The delay can be independent (constant), or dependent (**SIT** - reverse dependent; **VIT** or **LTI** – very reverse dependent; **EIT** - extremely reverse dependent; **UIT** – ultra reverse dependent; **RI** – delay type). The tripping curves are provided in Appendix 1.

When independent time delay protection is activated, the motor is de-energized if the current in one of the phases exceeds the threshold value within the **T** value of time (parameter “ i^2t ”).



$I_s = “i^2S”$ (tripping ratio) * “ i_{nd} ” (motor rated current) , and **T** – protection tripping delay time

Example. When $i^2S = 4.0$, $i_{nd} = 10$, and $i^2t = 10.0$, the motor will be de-energized 10 seconds after one of the phase currents exceeds 40A.

Figure 1.2 – Operation principle of the independent time delay protection

Dependent time delay protection operates according to the IEC 60255-3 and BS 142 standards.

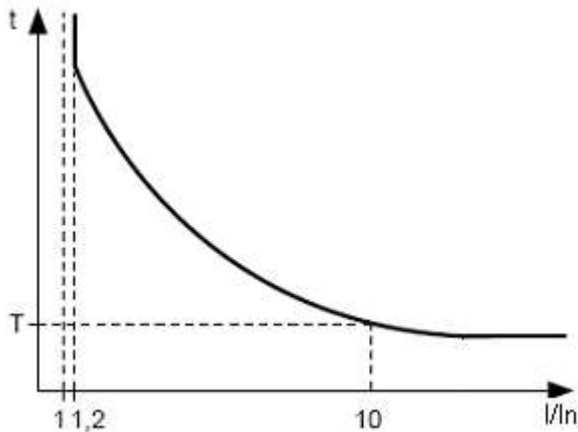


Figure 1.3 – Operation principle of the dependent time delay protection

In corresponds to the “ind” setting (motor rated current);
 T (“i₂L” – protection tripping time) – corresponds to the protection delay time for 10 In.
 For very high current values, protection has an independent time delay feature:

Annex 1 contains diagrams for the protection tripping constant equal to 1 second (the “i₂L” parameter). When a different value of the time constant is set, the protection tripping time changes proportionally to the time constant (for example, at “i₂L”=10 seconds, the tripping time will increase 10-fold, if the ratio of the currents is the same).

1.2.5.3 Ground Fault Protection:

- (“i₂S”);parameter);
- (“i₂t” parameter).
- activated when the ground fault current reaches the tripping threshold (the “i₂S” parameter);
- the motor is de-energized if the ground fault current exceeds the tripping threshold within the time value of T (the “i₂L” parameter).

1.2.5.4 Negative Sequence Current (phase imbalance) Protection is activated when the negative sequence component exceeds the threshold setting (the “i₂S” parameter), the motor is de-energized when this value is exceeded during a time exceeding the specified set value (the “i₂L” parameter).

If the tripping cause analysis is on (i₂r=1), and negative sequence current protection is activated for reasons other than line voltage imbalance (in this case, the cause is likely a malfunction in the motor), automatic reclosing will not occur after tripping (irrespective of the value of “i₂r”).

The voltage (current) negative sequence factor is a characteristic of the three-phase voltage (current) asymmetry. The approximate value of the voltage negative sequence factor can be calculated using the formula:

$$K_{2U_i} = \frac{U_{2(1)i}}{U_{1(1)i}} \cdot 100,$$

where $U_{2(1)i}$ is the negative sequence voltage RMS value of the three-phase voltage system base frequency, at the i-th instance of observation, V;

$U_{1(1)i}$ is the base frequency positive sequence voltage RMS value at the i-th instance of observation, V.

$U_{2(1)i}$ is calculated using the approximation formula: $U_{2(1)i} = 0,62 \cdot (U_{H\delta(1)i} - U_{HM(1)i})$,

where $U_{H\delta(1)i}$ and $U_{HM(1)i}$ are the highest and lowest RMS values of the three phase-to-phase base frequency voltages in the i-th instance of observation, V.

K_{2I_i} , the current negative sequence factor is calculated similarly.

If the current imbalance has not been caused by a voltage imbalance, the motor malfunction must be determined. To determine the cause of imbalance, calculate the value of the current negative sequence ratio divided by the voltage negative sequence ratio (K_{2I_i} / K_{2U_i}). If this value rate exceeds the “i₂S” parameter value, the motor is malfunctioning.

1.2.5.5 Undercurrent Phase Protection:

- activated when all three phase current values fall below the threshold (the “i₃S” parameter); the motor is de-energized when the values remain under the threshold during a time exceeding the set value (the “i₃L” parameter);
- inactive when the load current is under 10%*In (when the decrease in the current value is caused by the de-energizing of the motor, and not by the decreased load);
- has an independent ARC delay setting (the “i₃t” parameter).

1.2.5.6 Delayed Start and Rotor Blocking.

The operation principle of delayed start and rotor blocking protection is shown in Figure 1.4.

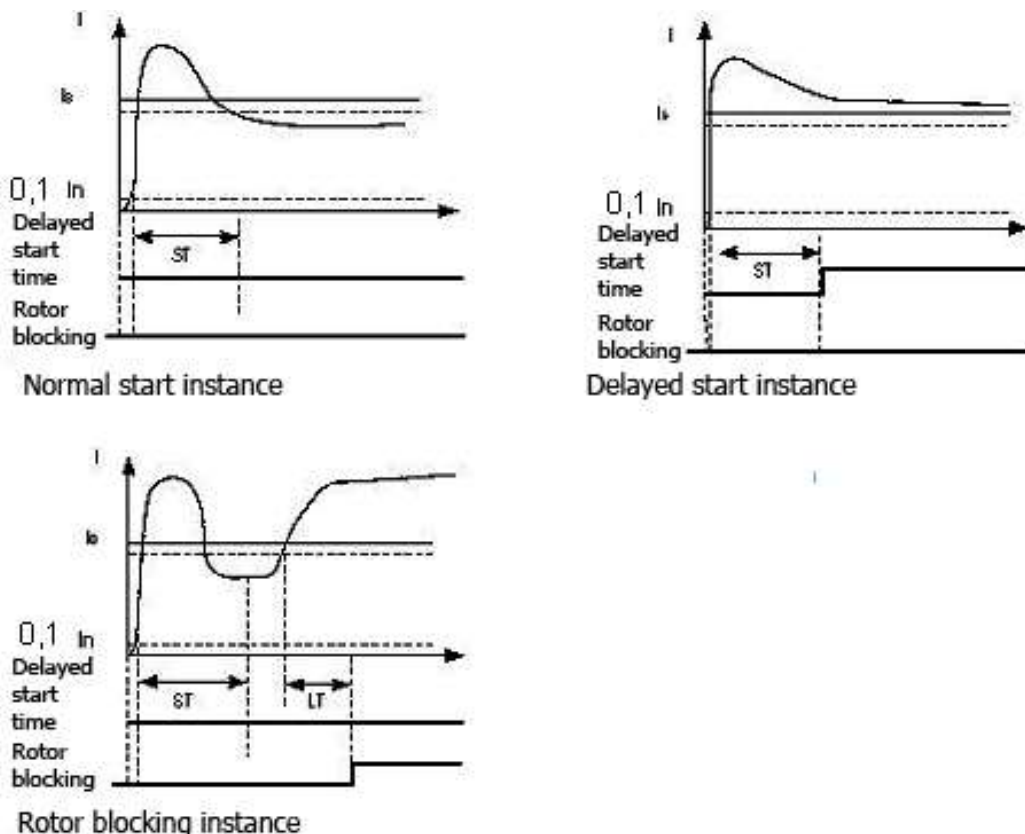


Figure 1.4 – Delayed start and rotor blocking

Delayed start.

During the motor start, protection is activated when the values of all phase currents exceed the I_s threshold setting (the “PP5” parameter) during a time longer than the ST time delay value (the “PPL’ parameter).

Rotor blocking

After the motor start is complete (the starting current is less than 120% of the rated current), UBZ switches to monitoring of possible rotor blocking. Protection is activated when the values of all phase currents exceed the threshold setting during a time longer than the LT time delay value (the “PbL” parameter).

1.2.5.7 Thermal Overload Protection

Thermal overload protection is designed based on the electromotor thermal balance equation, with the following assumptions:

- the motor is cold before the first start;
- during operation, the motor releases heat, in the amount proportional to the current value squared;
- after the motor is stopped, it cools down exponentially.

To enable protection, set up the double overload tripping time T2 (the “dtT” parameter).

Figure 1.5 shows the current-to-time curve for different T2 values.

The current-time dependence for the standard recommended T2 value (60 sec for double overload) is shown in Table 1.6.

Table 1.6

I/Inom	1.1	1.2	1.4	1.7	2	2.7	3
Tsec	365	247	148	88,6	60	36.4	24.6
I/Inom	4	5	6	7	8	10	15
Tsec	13.5	8.5	5.9	4,3	3.3	2.1	0.9

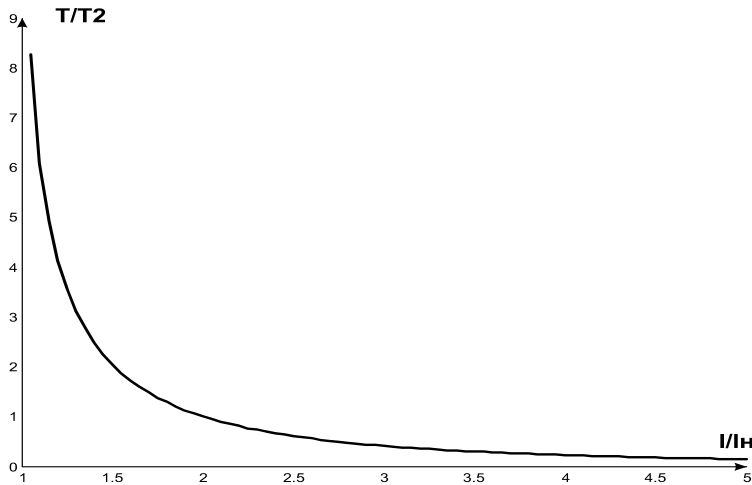
For rotary machines, cooling is more effective during operation than during the motor stall, which is why the dtP parameter is introduced – the cooling constant increase during motor stall.

After the load relay is open due to thermal overload, with automatic reclosing allowed, the relay will re-close after the bigger of the time values:

- duration of heat hysteresis (the motor should lose 33% of the accumulated heat);

- ARC time.

Through selection of suitable ARC times with regard to thermal hysteresis, the number of starts per time unit can be limited, because the device records the amount of heat released at the motor start when working in the intermittent cycle.



I/IH – current value divided by rated current;
 T/T2 – actual tripping time divided by T2 (double load tripping time).

Figure 1.5 – Current-time curve

1.2.5.8 Coil Overheating Protection

Depending on the threshold settings selected, protection can use the first input with the following temperature sensors:

- 1) integrated temperature sensors ($\epsilon I_r=1$). In this case, the C1S setting is not involved, and neither short circuit nor sensor breakout is monitored. Protection is activated when the sensor resistance exceeds 1700 Ohm.
- 2) PTC type sensors (1 kOhm at 25 °C) (this sensor should not be used to measure temperatures over 100 °C). At the second input, protection uses temperature sensors type Pt100 (platinum, 100 Ohm at 0 °C) or Ni100 (Ni120) (nickel, 100 Ohm (120 Ohm) at 0 °C) corresponding to IEC 60751 and DIN 43760 standards.

Protection at the second input:

- is activated when the monitored temperature exceeds the threshold setting;
- has two independent threshold setting: the alarm setting and the de-energize setting.

Protection detects the breakout and short circuit of temperature sensors:

- breakout at temperature over 220 °C;
- short circuit at temperature below minus 45 °C.

1.2.5.9 Voltage Protection

In the scope of voltage protection, before the motor is energized, UBZ checks whether the voltage parameters correspond to the user's settings and, depending on the results, allows or forbids to energize the load. After the load is energized, UBZ continues monitoring the voltage parameters, but any de-energizing decisions are made based on current values.

Voltage protection includes:

- undervoltage line protection (activated when at least one line voltage value remains below the threshold setting (the " $U_{-} S$ " parameter) during the time value in " $U_{-} t$ ");
- overvoltage line protection (activated when at least one line voltage value remains above the threshold setting (the " $U_{+} S$ " parameter) during the time value in " $U_{+} t$ ");
- line voltage imbalance protection (activated when the difference between the **RMS line voltage values** exceeds the threshold setting (the " $U_{\Delta} S$ " parameter) during the time value in " $U_{\Delta} t$ ").

1.2.5.10 **Phase Sequence Protection** is activated when the phase sequence order is broken; the motor is de-energized, and its subsequent operation blocked.

1.2.5.11 Motor Coil Insulation Minimal Resistance

After the device receives voltage, but before the output relay closes, UBZ checks the level of stator coil insulation relative to the body. This value is also checked when the load relay is closed, but the motor currents are less than 10% of the rated current (in this case, the motor is considered to be off).

At $r_{id}=5$ (15), the load is not energized if the coil insulation is below 500 ± 20 kOhm; at $r_{id}=10$ (20), if the coil insulation is below 1000 ± 50 kOhm. At $r_{id}=5$ and $r_{id}=10$, the load will be energized after the coil insulation is restored and the ARC time delay has passed. At $r_{id}=15$ and $r_{id}=20$, no ARC takes place.

1.2.5.12 **Phase Loss Protection** is activated if the current at one of the motor's phases exceeds 10% of the rated current (" i_{nd} "), while in any of the other phases, the current is under 7% of the rated current.

1.3 PACKAGING CONTENTS

The list of contents supplied is provided in Table 1.7.

Table 1.7 - Product Contents

Item	Abbreviation
UBZ-302 device	UBZ-302
Differential transformer (zero sequence transformer)	
PC connection cable for RS-232*	KC-01
Temperature sensor (types Pt100, Ni100 and Ni120) *	Pt100, Ni100, Ni120
*Supplied as agreed with consumer	

1.4 FEATURES AND OPERATION

UBZ is a microprocessor-based digital device that provides a high degree of reliability and accuracy. It requires no additional power supply, as the voltage it monitors is also used to power it.

UBZ has three integrated CTs, through which the power phase cables are led.

2 INTENDED USAGE

2.1 SAFETY

For any connections, the device must be powered off.

2.2 DEVICE CONTROLS

2.2.1 UBZ has five control modes:

- keypad lock;
- mode with minimal number of setting parameters (MMSP);
- user level;
- engineer level;
- remote control.

All work modes allow:

- viewing the measures and displayed parameters (table 1.4). To scroll through parameters, use DOWN and UP buttons;
- viewing the fault log (p.2.4.6).

2.2.2 When the keypad is locked, viewing and editing programmable parameters is not possible.

When the keypad is locked, pressing the SETUP buttons will display the “LOC” message. To unlock the keypad, press SETUP again. The SETUP LED will be lit, and the indicator will show a flashing “0”. Use the UP and DOWN buttons, enter the user password (consisting of numbers 1 to 9) and press the RES/MEM/SEL button. If the password is correct, the keypad will be unlocked. If no button is pressed within 15 seconds of unblocking the keyboard, and the lock setting is not changed by the user, the keypad will be locked again.

NOTE – If any temperature sensor is disabled via software, the indicator will show “*not*” instead of the temperature (resistance) value.

2.2.3 When the keypad is unlocked, it is possible to:

- work in MMSP mode;
- view and edit user-level parameters;
- view engineer-level parameters.

2.2.3.1 The MMSP mode is meant to simplify the use of UBZ for service personnel.

To switch the UBZ into the MMSP mode, set the value of 5 $n=1$ or reset to factory settings (p.2.2.4). When UBZ works in this mode, the green MMSP LED is on.

In the MMSP mode, the following parameters are sufficient for the normal operation of UBZ:

- CT type (integrated or external);
- rated CT current (if using external CT);
- rated (operating) motor current.

The difference between MMSP mode and user mode is that the parameters not included in the MMSP list are set to default factory settings.

WARNING: IF ANY PROGRAMMABLE PARAMETERS WERE EDITED BY THE USER OR THE ENGINEER, BUT NOT INCLUDED IN THE MMSP LIST, THEY WILL DEFAULT TO FACTORY SETTINGS WHEN MMSP MODE IS ACTIVATED.

Parameters not included in the list in this more are not viewed and not edited. Operations with the parameters included in the MMSP list is the same as in the user-level mode.

Adding parameters to the MMSP list and deactivating the MMSP list is only possible at the engineer level.

When the MMSP mode is deactivated (setting value of 5 $m=0$), the MMSP LED switches off. In the user mode, the entire parameter list is viewed. To edit a parameter:

- use the DOWN and UP buttons to select the parameter to be added;
- press the DOWN and UP buttons simultaneously (the point in the higher digit of the mnemonic indicator should disappear).

2.2.3.2 Editing and Viewing User-Level Parameters

To view and edit user-level parameters, press SETUP – the SETUP LED will be illuminated. Scroll through the parameters using the DOWN and UP buttons; press SETUP to enter parameter editing mode (the parameter value will start flashing); edit the parameter value using the DOWN and UP buttons; press RES/MEM/SEL to save the parameter value, SETUP to return to the menu without saving, and RES/MEM/SEL to leave the menu. If no button is pressed during 30 seconds, UBZ returns to the initial state.

2.2.3.3 Editing and Viewing Engineer-Level Parameters

Entering engineer mode

Press the SETUP button and keep pressed for 5 seconds. If engineer mode is password-protected, the indicator will display the “PAS” message. The SETUP LED will be illuminated, and the parameter value indicator will flash “000”. Use UP and DOWN to enter the engineer’s password (three digits from 1 to 9), pressing RES/MEM/SEL after each digit. If the password is wrong, the “PAS” message will be displayed, flashing in the higher digit; 15 seconds later, UBZ will return to the initial state. If the password is correct, the first engineer menu parameter will be displayed.

To scroll through the parameters, use DOWN and UP; press SETUP to enter parameter editing mode (the parameter value will start flashing); edit the parameter value using the DOWN and UP buttons; press RES/MEM/SEL to save the parameter value, SETUP to return to the menu without saving, and RES/MEM/SEL to leave the menu. If no button is pressed during 30 seconds, UBZ returns to the initial state.

When UBZ is used in engineer mode, the decimal point is displayed in the lower digit of the mnemonic indicator.

At the engineer level, access to any user-level parameter can be granted or denied by pressing SETUP and DOWN simultaneously. Denied access is indicated by the decimal point displayed in the middle digit of the mnemonic indicator.

At the engineer level, any parameter can be added to the MMSP parameter list. To do that:

- use DOWN and UP to select the parameter to be added;
- press DOWN and UP simultaneously (the decimal point in the higher digit of the mnemonic indicator should disappear).

To remove a parameter from the MMSP parameter list:

- use DOWN and UP to select the parameter to be removed;
- press DOWN and UP simultaneously.

If the parameter is excluded from the MMSP list, the decimal point will be displayed in the higher digit of the mnemonic indicator

2.2.4 Reset to Factory Settings

There are two ways of resetting UBZ to default factory settings.

Method one. Set the value of $PPP=1$. After leaving the parameter setting mode, all factory settings will be reset (except for the engineer password).

Method two. When UBZ is being powered on, press the buttons SETUP and RES/MEM/SEL and keep them pressed for two seconds. All factory settings will be reset, including the engineer password (**engineer password set to 123**).

After resetting to the default factory parameters, UBZ will work in the MMSP mode, with the following list of parameters:

- CT type (external or integrated), LPt ;
- rated CT current (for external CT), Lnt ;
- rated motor current, ind .

2.3 PREPARING UBZ FOR OPERATION

WARNING: TO IMPROVE THE OPERATING QUALITY OF UBZ, IT IS RECOMMENDED TO INSTALL FUSES (THERMAL OR EQUIVALENT) IN THE FOLLOWING CIRCUITS (LISTED IN THE ORDER OF IMPORTANCE, WITH RECOMMENDED FUSE RATING):

- 1) UBZ power supply circuit (27,28, 30, 31 - L1,L2,L3, N) - 1 A;
- 2) motor insulation resistance measuring circuit (25,26 - R-iz, R-iz_N) - 0,5 A;
- 3) temperature, current, voltage measuring circuits (48,49,50,51,52; 44,45; 39,40) – 0,5 A;
- 4) RS-485 (33,34,35) – 0,5 A;

5) relay outputs (fuse rating selected according to the circuits connected, but not exceeding 15A for outputs 1,2,3 and 5A for outputs 4-9).

2.3.1 For electric motors of 2.5 kW to 30 kW capacity, integrated current transformers can be used. The wires to the motor should be led through the openings in the UBZ housing (each phase wire through a separate opening).

For motors of other capacity, connect current transformers with 5A rated output current, as shown in Figure 2.1.

2.3.2 Conduct all three phase wires through the differential current transformer (zero sequence transformer) and connect it to the UBZ.

2.3.3 To monitor and measure the motor insulation, connect the insulation monitoring terminal **25** to one of the MS (magnetic starter) outputs. If the motor housing is not grounded, a circuit with isolated neutral is in use, or no neutral wire is connected to the UBZ terminal – connect the motor housing to terminal **26** electrically.

2.3.4 Connect UBZ to the electric circuit as shown in Figure 2.1. If using a motor with star-delta coil switching, connect as described in Appendix 2.

2.3.5 To operate UBZ via a personal computer using the UBZ-302 Control Panel software:

- install the UBZ Control Panel software on the PC by running `setup_cplubz302(Standart)(x.x).exe`, where x.x. is the software version;

- connect the RS-232 socket on the UZB front panel to the RS-232 socket of the PC using the KC-01 cable;

- set the value of " $rPP=1$ ".

NOTE:

1 The file `setup_cplubz302(Standart)(x.x).exe` can be downloaded from the website of NOVATEK-ELECTRO (http://www.novatek-electro.com/programmnoe_obespechenie.html).

2 The KC-01 cable is supplied to order. It can also be made by the user as shown in Figure 2.2.

3 User-developed software can also be used to operate UBZ.

2.3.6 If using the MODBUS protocol, connect the communication lines to the UBZ terminals **33 (GND)**, **34 (RS-485 B line)**, **35 (RS-485 A line)**. Set the value of " $rPP=2$ ".

2.3.7 Power UBZ on.

The procedure for the load relay closing is determined by the values of APd and APd (p. 2.4.1.).

WARNING: UBZ IS SUPPLIED WITH THE MOTOR RATED CURRENT SET TO ZERO. IN THIS CASE, THE UBZ LOAD RELAY WILL NOT BE ON BEFORE THE MOTOR RATED CURRENT VALUE IS SET. THE MOTOR RATED CURRENT MUST BE AT LEAST 5A.

2.3.8 Set the necessary parameter values in the menu.

2.3.9 Power UBZ off.

2.3.10 Connect the magnetic starter (MS) as shown in Figure 2.1.

NOTE: when the load relay is on, contacts **5-6** and **8-9** are closed, when it is off, the contacts **4-5** and **7-8** are closed.

2.4 INTENDED USAGE

NOTE – Descriptions of the UBZ operation assume that the appropriate protection types are activated and all necessary sensors are connected.

2.4.1 UBZ Operation Before Load Relay Activation

2.4.1.1 UBZ Operation After Power On (First Use)

After the device is powered on, the mnemonic indicator displays "**5EA**" for 1-2 seconds. Then, before activating the load relay, UBZ checks:

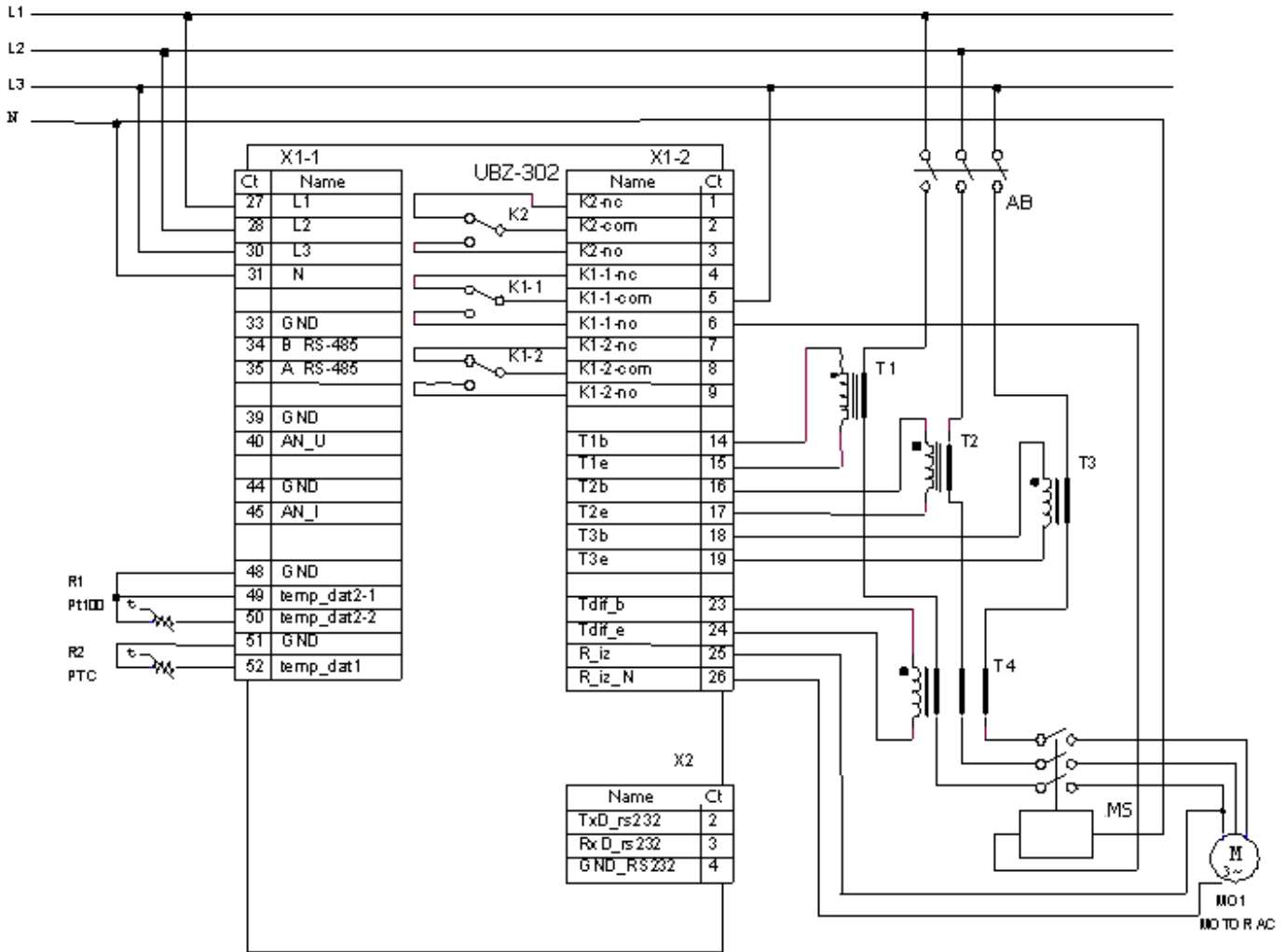
- the level of stator coil insulation relative to the body (if the insulation resistance is under 500 ± 20 kOhm at $r_{id}=5$ ($1,000 \pm 50$ kOhm at $r_{id}=10$), the load is not energized);
- quality of voltage: phase completion, symmetry, RMS line voltage value;
- correct phase order, lack of phase coincidence.

In case any prohibiting factor is present, the load relay is not activated, the mnemonic indicator displays the appropriate fault code, and the FAULT LED is illuminated.

Depending on the value of $5iP$, the indicator displays:

- linear voltage Uab at $5iP=0$;
- insulation resistance (rid) at $5iP=1$;
- ARC countdown in seconds (Att) at $5iP=2$.

If no forbidding factors are present, activation of the load relay is determined by the value of APd (UBZ operation after power-on).



Relay K1 – load relay
 Relay K2 – functional relay

Figure 2.1 – UBZ wiring chart

- 1) At $APd=0$, the load relay will not be activated. At this setting, press UP and DOWN simultaneously to activate the load relay.
- 2) At $APd=1$, the load relay will be activated after ARC delay time.
- 3) At $APd=2$, the load relay will be activated 2 seconds after power-on.

At the same time as the load relay is activated, the green LOAD LED is illuminated. After the relay activation and before the motor start (the motor start is determined as the load current exceeding 120% of rated current), the voltage quality continues to be monitored, with appropriate decision-making. If any forbidding factors arose during the dead time, the load relay will be deactivated.

P. 2.4.4.8 describes UBZ operation when remote motor control is allowed via the RS-232/RS-485 ($dUd=1$, $dUd=2$) interface.

2.4.1.2 UBZ Operation After De-Energizing After Fault

In this case, UBZ operates as during first power-on, but activation of the load relay does not depend on the value of APd .

If ACR after fault is not allowed ($Ar_r = 0$), the motor cannot be energized before UBZ is powered off. The value of Ar_r applies to all types of faults, except voltage faults. To forbid ARC after voltage faults, use the parameters U^F_r , U^r_r , U^o_r .

2.4.2 UBZ Operation After Load Relay Activation and Motor Energizing (currents of over 10% of the motor rated current).

UBZ carries out voltage and current control. The load relay is deactivated when any protection type mentioned in Table 2.8 is tripped, except:

- voltage protection;
- overcurrent protection at $i^2 t_n = 1$ (in this case, overcurrent is indicated, but the load relay is not deactivated).

The indicator can display the motor phase A current or the value of the user-selected parameter. The value of the user-selected parameter can be displayed constantly ($S_{iL}=0$) or during 15 seconds, after which the indicator resumes displaying the motor phase A current ($S_{iL}=1$).

2.4.3 Functional Relay Operation

The functions carried out by the functional relay are determined by the value of $rr5$.

At $rr5=0$, the relay is used as a signaling relay (the S/D and TR LEDs are not illuminated). The relay contacts are closed in case of any of the faults listed in Table 2.8.

At $rr5=1$, the relay is used as a time relay (the S/D and TR LEDs are illuminated). The relay is activated after a time specified in " rrt ", after the load relay is activated.

At $rr5=2$, the relay is used to switch the motor coils from star to triangle (the 3/T (S/D) LED is illuminated). In this mode, the load relay is activated the same as at $rr5=0$, but after the time specified in " rrt ", it is deactivated. Then, after a time specified in " Flt " passes after the deactivation of the load relay, the functional relay is activated.

NOTE – When the functional relay is activated, the contacts 1-2 are open, and the contacts 2-3 are closed.

2.4.4 Using the RS-232/RS-485 Interface with the MODBUS Protocol, RTU Mode

UBZ allows exchanging data with an external device using the serial interface and the MODBUS protocol. During data exchange via RS-485 or RS-232, the blue EXCHANGE LED is illuminated.

2.4.4.1 Communication Parameters:

- device address: 1-247 (parameter $r5A$);
- data transfer rate: 9,600 baud, 19,200 baud (parameter $r55$);
- reaction to loss of link: warning with continued operation; warning with motor stopping; continued operation with no warning (parameter $r5P$);
- timeout detection: 1 –120 seconds (parameter $r5D$);
- word format – 8 bit, no parity check, two stop bits.

2.4.4.2 UBZ Operation via PC

A PC is connected to the UBZ via a serial interface. The connection scheme is shown in Figure 2.2. Each UBZ has a unique communication address that is used by the PC to distinguish between different UBZs. UBZ can work in Modbus networks using the RTU mode.

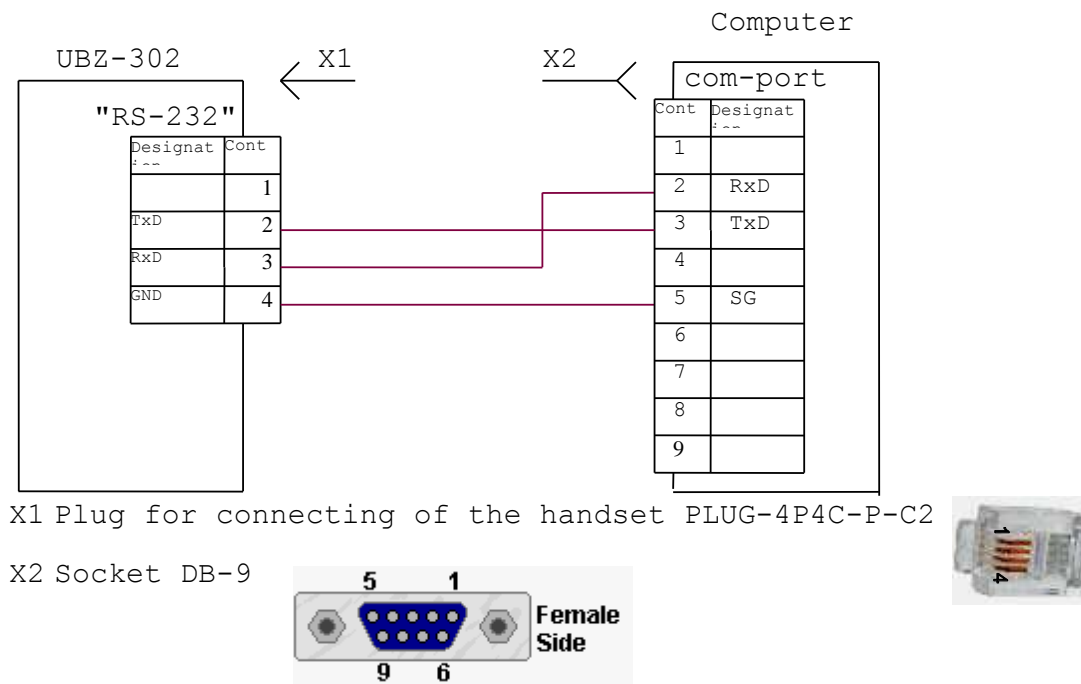


Figure 2.2 – Connecting UBZ to a PC

2.4.4.3 Communication Protocol

Data exchange between a PC and the UBZ is done in packets. The data packet format is described in Table 2.1.

Table 2.1

START	silence interval – over 4 ms at 9,600, or over 2 ms at 19,200 baud
ADR	UBZ communication address (8 bits)
CMD	Command code (8 bits)
DATA 0	Data contents: N*8 data bits (n<=24)
....	
DATA (n-1)	
CRC CHK low	CRC checksum 16 bits
CRC CHK high	
END	silence interval – over 4 ms at 9,600 baud, or over 2 ms at 19,200 baud

2.4.4.4 CMD (Command Code) and DATA (Data Characters)

The format of data character depends on command codes.

Command code 0x03, reading n words.

For example, reading 2 words continuously starting from the address 64H in the UBZ with communication address 01H (Table 2.2).

Command code 0x06, writing one word

Using this command is not recommended, because writing incorrect data may result in UBZ failure.

Data can only be written using the addresses of programmable parameters (see Table 1.5), except the parameters listed in Table 2.3.

Table 2.2

Command Message		Feedback Message	
ADR	0x01	ADR	0x01
CMD	0x03	CMD	0x03
Data start address	0x00 0x64	Data amount, bytes	0x04
Data amount, words	0x00 0x02	Data contents at address	0x17 0x70
CRC CHK low	0x85	Data contents at address	0x00 0x00
CRC CHK high	0xD4	CRC CHK low	0xFE
		CRC CHK high	0x5C

Table 2.3

Set and Read Parameters	Code Parameters	Address
Total device uptime, days	<i>t b U</i>	207
Motor uptime, days	<i>t C O</i>	208
User access code	<i>L O C</i>	209
Engineer access code	<i>P R S</i>	210
Reset to factory parameters	<i>P P P</i>	211
Device version	<i>r E L</i>	217

The parameter is written regardless of any engineer protection set (writing via the communication line has a higher priority).

When a new value is written into a MMSP-protected cell, the parameter is automatically excluded from the MMSP mode.

The parameters being written must be a multiple of the interval specified in Table 1.5.

For example, Table 2.4 shows the procedure of writing the entry 1000 (0x03E8) into the register at the address 0x00A0, in the UBZ with the communication address 01H.

Table 2.4

Command Message		Feedback Message	
ADR	0x01	ADR	0x01
CMD	0x06	CMD	0x06
Data start address	0x00 0xA0	Data start address	0x00 0xA0
Data	0x03 0xE8	Data	0x03 0xE8
CRC CHK low	0x89	CRC CHK low	0x89
CRC CHK high	0x56	CRC CHK high	0x56

Command code 08h – diagnostics.

The 08h function provides for a number of tests used to check the communication between the PC and the UBZ, and to check the UBZ operational state. The function uses the sub-function field to elaborate the action (test).

Sub-function 00h – return query data.

The data sent in the data field of the query must be returned in the data field of the response.

Figure 2.3 shows an example of a query and a response.

Query

Address	Function	HB sub-function	LB sub-function	HB data	LB data	CRC LB	CRC HB
01h	08h	00h	00h	A0h	3Ch	98h	1Ah

Response

Address	Function	HB sub-function	LB sub-function	HB data	LB data	CRC LB	CRC HB
01h	08h	00h	00h	A0h	3Ch	98h	1Ah

Figure 2.3 – Example of query and response of the sub-function 00h – return query data

Sub-function 01h – restart communication options.

The peripheral UBZ port must be initialized and restarted.

Figure 2.4 shows an example of query and response.

Query

Address	Function	HB sub-function	LB sub-function	HB data	LB data	CRC LB	CRC HB
01h	08h	00h	01h	00h	00h	B1h	CBh

No response

Figure 2.4 – Example of query and response of the sub-function 01h – restart communication options.

2.4.4.5 CRC – Cyclic Redundancy Check

The checksum (CRC16) is a cyclical checking code based on the A001h polynomial. The transmitter creates a checksum for all bytes of the transmitted message. The receiver creates the checksum for all bytes of the received message and compares it to the checksum received from the transmitted. If the created and received checksums are not the same, an error message is generated.

The checksum field occupies two bytes. In a message, the checksum is transmitted least significant byte first.

The following algorithm is used to create the checksum:

- 1) load CRC register (16 bite) with ones (FFFFh);
- 2) XOR gate with the first 8 bits of the message byte and the contents of the CRC register;
- 3) shift result one bit to the right;
- 4) if the shifted bit = 1, XOR gate with the register contents with value of A001h;
- 5) if the shifted bit = 0, repeat step 3;
- 6) repeat steps 3, 4, 5, until 8 shifts are carried out;
- 7) XOR gate with the next 8 bits of the message byte and the contents of the CRC register;
- 8) repeat steps 3-7 until all bytes of the message are processed;
- 9) the final contents of the register will contain the checksum.

An example of CRC generating code on C. The function receives two arguments:

- Unsigned char* data <- indicator to message buffer;
- Unsigned char length <- number of bytes in the buffer.

The function returns the CRC value as (unsigned int).

```

Unsigned int crc_chk(unsigned char* data, unsigned char length)
{int j;
 unsigned int reg_crc=0xFFFF;
 while(length--)
 { reg_crc ^= *data++;
  for(j=0;j<8;j++)
  { if(reg_crc & 0x01) reg_crc=(reg_crc>>1) ^ 0xA001; // LSB(b0)=1
    else reg_crc=reg_crc>>1; } }
 return reg_crc;
}
    
```

2.4.4.6 Register Addresses

Table 1.4 shows the register addresses of measured and calculated UBZ parameters. Table 1.5 shows the register addresses of programmable parameters.

Table 2.5 shows additional registers and their purpose.

Table 2.5

Name	Address	Purpose	Note
register 240	Bit 0	0-no fault 1-fault (fault code in register 241)	
	Bit 1	0 – load relay open 1 – load relay closed	
	Bit 2	0– functional relay open 1 – functional relay closed	
	Bit 3	0 – no restart 1 – ARC expected	
	Bit 5-4	Functional relay operating mode 00 – signaling relay 01 – time relay 10 – star / delta	
	Bit 6	0 – MSM mode off 1 – MSM mode on	
	Bit 7	0 – regular operating mode 1 – UBZ in hysteresis area when working with analog outputs	
Fault register 1	241	bit mapping according to Table 2.8	0-no fault 1-fault
Fault register 2	242	bit mapping according to Table 2.8	
Fault log			
fault code 1	243	fault code according to Table 2.8	
parameter value 1	244	parameter value according to Table 2.8	
fault time 1	245	two upper bytes	
	246	two lower bytes	
fault code 2	247	fault code according to Table 2.8	
parameter value 2	248	parameter value according to Table 2.8	
fault time 2	249	two upper bytes	
	250	two lower bytes	
fault code 3	251	fault code according to Table 2.8	
parameter value 3	252	parameter value according to Table 2.8	
fault time 3	253	two upper bytes	
	254	two lower bytes	
fault code 4	255	fault code according to Table 2.8	
parameter value 4	256	parameter value according to Table 2.8	
fault time 4	257	two upper bytes	
	258	two lower bytes	
fault code 5	259	fault code according to Table 2.8	
parameter value 5	260	parameter value according to Table 2.8	
fault time 5	261	two upper bytes	
	262	two lower bytes	
<p>NOTE:</p> <p>1 Fault time is time that passed between powering the UBZ off and the fault. Measured in minutes.</p> <p>2 After delivery or after resetting to factory settings (p. 2.2.4), the fault log contains error code 40 and parameter value 10,000.</p> <p>3 When UBZ is energized, the value 5000000 is written to all fault time registers.</p>			

2.4.4.7 Communication Error Processing

In case of an error during frame reception (parity error, frame error, checksum error), UBZ returns no response.

In case of an error in format or value of transmitted data (unsupported function code, etc.), UBZ accepts the query frame and creates a response containing the error indication code. The error indication is the 1 in the higher bit of the function field. A separate field is reserved for the error code in the response. Figure 2.5 shows an example of a response.

Table 2.6 provides error codes.

Query - function 30h not supported

Address	Function	Data	CRC LB	CRC HB
01h	30h		XXh	XXh

Response

Address	Function	Error code	CRC LB	CRC HB
01h	B0h	01h	94h	00h

Figure 2.5 – Example of a response after error

Table 2.6

Error code	Name	Description
01h	ILLEGAL FUNCTION	The UBZ cannot process the accepted function code
02h	ILLEGAL DATA ADDRESS	The data address in the query is not accessible by this slave device
03h	ILLEGAL DATA VALUE	The value in the query data field is not acceptable for the UBZ
04h	SLAVE DEVICE FAILURE	An unrecoverable error occurred when UBZ tried to carry out the requested action
05h	ACKNOWLEDGE	The UBZ accepted the query, but processing it requires a long time. This response prevents the master device from generating a timeout error
06h	SLAVE DEVICE BUSY	The UBZ is busy processing the command. The master device should resent the message later, when the slave device is free
07h	NEGATIVE ACKNOWLEDGE	The UBZ cannot carry out the program function contained in the query

2.4.4.8 Remote Motor Control Using the RS-232/RS-485 Interface

Remote control of the UBZ is determined by the value of *dUd*.

At *dUd*=0, remote control of the motor is forbidden.

At *dUd*=1, the UBZ operation after energizing is the same as with remote control off (regular operation), but writing into the R_COMMAND command register is allowed.

At *dUd*=2, the UBZ will energize the motor only after a respective command is received via the RS-232/RS-485 interface.

The value of R_COMMAND is taken into consideration by the UBZ operation algorithm at *dUd*=1 and *dUd*=2. If *dUd*=0, and the user sets *dUd*=1 or *dUd*=2, "0" will be written to R_COMMAND.

Table 2.7 shows a list of the possible settings of the command register.

At *dUd*=1, "1" will be written into the command register after power on (regular operation). At *dUd*=2, "0" will be written into the command register after power on (the motor is switched off until the energize command is given).

After emergency de-energizing of the motor by simultaneous pressing of UP and DOWN (at *ACd*=2 or *ACd*=3), the command register will be reset to 0.

Table 2.7

Command register R_COMMAND Address = 237	Actions
0	De-energize motor. If the motor is off, it will not be energized until a remote energize command is given. If the motor is on, it will be de-energized.
1	Regular device operation. If the motor was de-energized by a remote command, or by simultaneous pressing of BBEPX / UP and BHI3 / DOWN (at <i>ACd</i> =3), or by a fault with permitted subsequent ARC, then after 1 is written into R_COMMAND, the motor will be energized after the ARC time delay.
2	Early motor de-energizing. Writing 2 into R_COMMAND results in the motor energizing before the end of the ARC time delay. After the motor is on, R_COMMAND = 1.

2.4.5 Fault Status System

In case of a fault status:

- the mnemonic indicator displays a fault code as per Table 2.8;
- the value indicator displays the value of the parameter to which the fault is related (if the fault status has no numerical value, the indicator displays “---”);
- the red FAULT LED is illuminated (steady glow if no ARC is allowed, or blinding if ARC is expected);
- the load relay opens;
- the functional relay closes (at $r_{r5}=0$).

If UBZ detects several types of faults simultaneously, fault codes and their parameter values are displayed sequentially.

If ARC is allowed, the indicator displays fault codes and the time to ARC (if the time delay for thermal overload exceeds the ARC delay time, the former is displayed).

Table 2.8 - Fault Codes

Fault name	Fault mnemonic	Parameter value	Parameter value register address	Fault code	N bit register address
phase overcurrent	$A_{i \neq}$	maximum phase voltage	300	0	241:0
thermal overload	A_{dt}		301	1	241:1
ground fault (zero sequence current)	$A_{i _}$	zero sequence current	302	2	241:2
exceeded value of negative sequence current ratio divided by negative sequence voltage ratio	$A_{i \square}$	negative sequence current ratio * 100	303	3	241:3
negative sequence current	$A_{i \square}$	negative sequence current	304	4	241:4
phase undercurrent	$A_{i _}$		305	5	241:5
delayed start	APp	current	306	6	241:6
rotor blocking	APb	current	307	7	241:7
temperature threshold at sensor 1	A_{t1}	temperature, degrees	308	8	241:8
temperature threshold at sensor 2	A_{t2}	temperature, degrees	309	9	241:9
phase sequence	A_{U4}		310	10	241:10
currents present with open load relay (contactor fault)	A_{Co}	current	311	11	241:11
line undervoltage	$A_{U _}$	voltage	312	12	241:12
line overvoltage	$A_{U \neq}$	voltage	313	13	241:13
phase imbalance	$A_{U \square}$	imbalance	314	14	241:14
motor coil insulation resistance	$A_{r _}$	insulation resistance	315	15	241:15
remote control channel fault	A_{dU}			16	242:0
emergency motor stop without ARC	EAd			17	242:1
emergency motor stop with ARC, by simultaneous pressing of BBEPX / UP and BHI3 /DOWN	EAd			18	242:2
short circuit of temperature sensor 1	$ES1$			19	242:3
breakout of temperature sensor 1	$EO1$			20	242:4
short circuit of temperature sensor 2	$ES2$			21	242:5
breakout of temperature sensor 2	$EO2$			22	242:6
phase loss	E_{iU}			23	242:7
EEPROM destruction	EEP			24	242:8
0-20 mA analog input	$AA_{i _}$		325	25	242:9
0-10 V analog input	AAU		326	26	242:10

WARNING: The "EEP" fault (EEPROM destruction) means that the programmable parameter data (see Table 1.5) are damaged. To continue operation, power down UBZ and reset to factory settings (see p. 2.2.2 – method two).

2.4.6 Fault Status Log

When the load relay is deactivated in case of a fault, the UBZ stores the fault code, the value of the parameter that caused the fault, and the time of the fault (the time passed between the UBZ power on and the fault).

The maximum number of fault codes stored simultaneously is five. After subsequent faults, information about the fault is overwrites the oldest entry.

To view the log, press RES/MEM/SEL.

The SETUP LED will be illuminated (flashing), and the UBZ indicators will display the first row from Table 2.9. To scroll through the log, use UP and DOWN.

Table 2.9

Displayed on mnemonic indicator	Displayed on value indicator
"Adi"	number of log entry (1 is the newest)
XXX – fault mnemonic according to Table 2.8	YYY – parameter value as per Table 2.8 (if no parameter value, indicator displays "---")
XXX – hours since fault	YY – minutes since fault

To leave the log, press RES/MEM/SEL. Otherwise, the log will be closed automatically, 30 seconds after any button was pressed.

Information about the fault is displayed on the UBZ indicators in the format shown in Table 2.9.

When UBZ is powered on, 5000000 is written into the registers used to store fault time. In this case, the mnemonic indicator and the value indicator display "---" and "-", respectively.

2.4.7 Controlling the Motor Using the UBZ Front Panel

Depending on the value of *ARd*, the UBZ load relay can be controlled using the buttons UP and DOWN (unless the keypad is locked):

ARd=0 – no reaction;

ARd=1 (motor start allowed) – the load relay will close unless the ARC time has expired;

ARd=2 (emergency motor stop) – the load relay will open, with fault code "*ARd*". Motor restart is only possible after powering the UBZ off and on again;

ARd=3 (motor start and stop permitted) – the load relay opens, with fault code "*ARd*". To energize, press the buttons UP and DOWN.

NOTE – When the values are set to "*ARd*=0" (manual motor start from the UBZ front panel after power on) and "*ARd*=0" (manual motor control forbidden), the load relay will not be activated.

WARNING: IF REMOTE CONTROL IS ALLOWED ("*dUd*=1"), MOTOR START FROM THE FRONT PANEL IS FORBIDDEN.

2.4.8 Controlling the Motor Using the Analog Inputs

Algorithms for controlling the motor using the analog inputs 0-20 mA and 0-10 V are provided in Table 1.5.

After motor de-energizing through a fault value, ARC countdown will only start after the parameter value leaves the fault range.

If, after motor de-energizing through a fault value, the value remains between the motor energizing and de-energizing levels (the FAULT indicator is not illuminated, but the mnemonic indicator displays the fault code), early motor start is possible, using the front panel buttons or remote control.

3 TECHNICAL MAINTENANCE

3.1 SAFETY PRECAUTIONS



REPAIR, MAINTENANCE AND ASSEMBLY WITHOUT DISCONNECTING THE DEVICE FROM THE CIRCUIT IS FORBIDDEN.

NEVER ATTEMPT TO REMOVE AND REPAIR THE UNIT.

Some of the unit components may be live.

NEVER ATTEMPT TO OPEN AND REPAIR THE PROTECTED EQUIPMENT, IF SWITCHED TO THE UNIT SOCKET.

Do not use the unit in corrosive environments with the air containing acids, alkalis, oils, etc.

Do not operate the unit under conditions of high humidity.

Installation, adjustment and maintenance of the unit should only be provided by the qualified personnel, having reviewed this Operating manual

3.2 TECHNICAL MAINTENANCE PROCEDURE

Technical maintenance is recommended to make every 6 months

Technical maintenance entails a visual examination, including checking that the wires are properly connected to the UBZ terminals, and the housing is free of cracks and chips.

4. TRANSPORTATION AND STORAGE

UBZ-302 in the manufacturers package should be carefully stored in dry places with ambient temperature from -50 to +60 °C and relative air humidity not more than 80%. Air should not contain any chemically aggressive vapors. When transporting customer should provide suitable packing that would protect the UBZ-302 from any mechanical damages, serious drops and vibrations that may affect the device integrity.

5. TERMS OF SERVICE AND MANUFACTURER'S WARRANTY

The service life of UBZ-302 is 10 years. After the service life is over, one should contact the manufacturer.

Warranty period is 36 month upon the day of sale.

The manufacturer shall repair the unit, in the compliance with the operating manual by the user, within the warranty period.

UBZ-302 is not subject to the warranty service in the following cases: expiry of the warranty period;

availability of mechanical damages;

attempts to open and repair;

traces of moisture attack or in the presence of foreign items inside the unit:

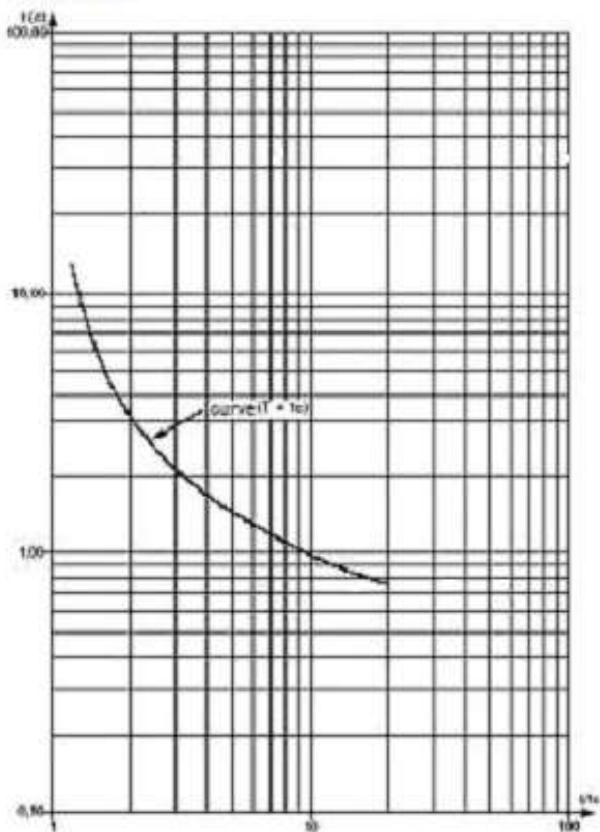
damage is caused by electric current or voltage in excess to the permissible values as indicated in the Operating manual

Warranty service is provided in the place of purchase Post-warranty service shall be provided by the manufacturer.

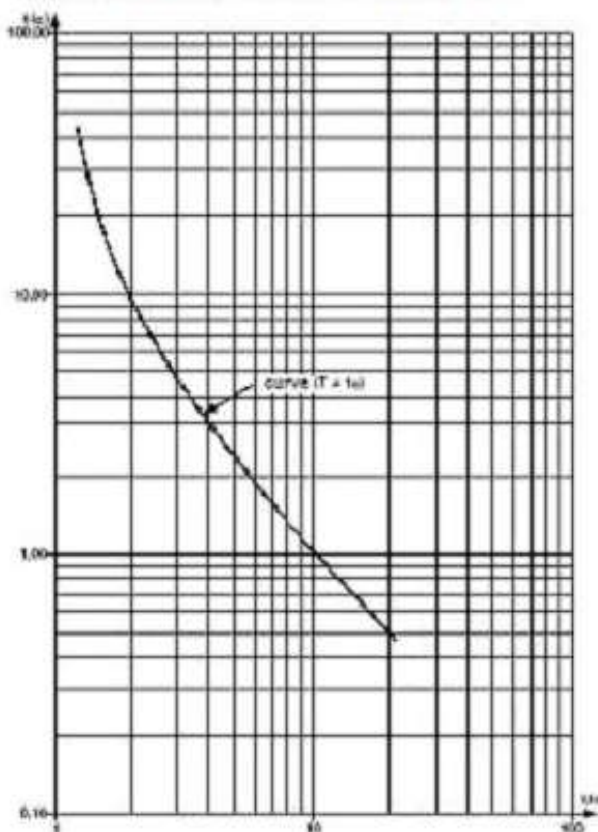
The manufacturer's warranty does not cover compensation for direct or indirect losses associated with the unit transportation to the place of purchase or manufacturer's plant.

APPENDIX 1. Current protections with different time-dependent delay

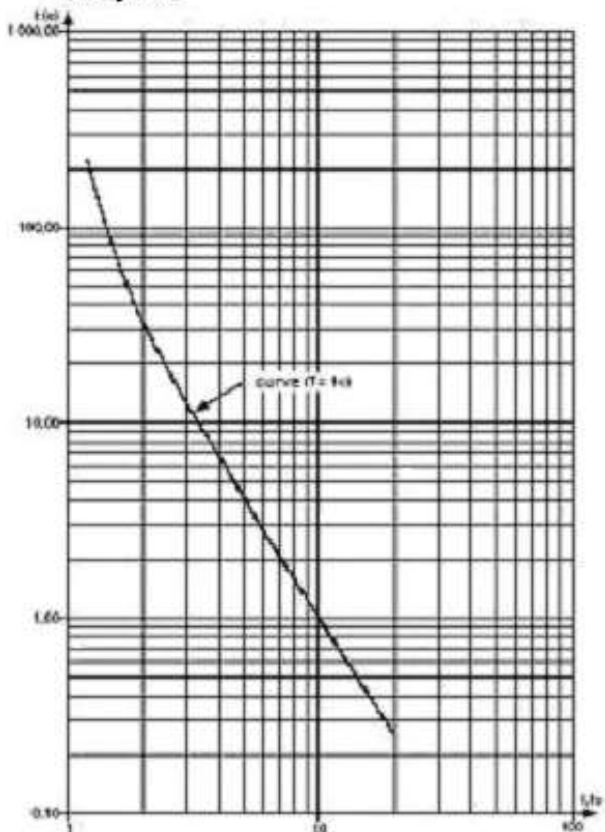
Curve of standard inverse relation of time delay SIT



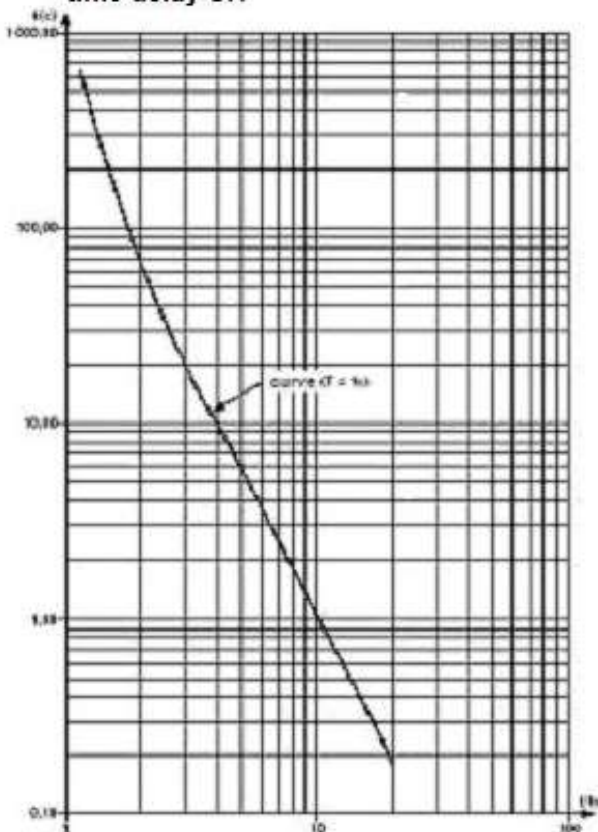
Curve of very inverse relation of time delay VIT or long inverse relation of time delay LTI



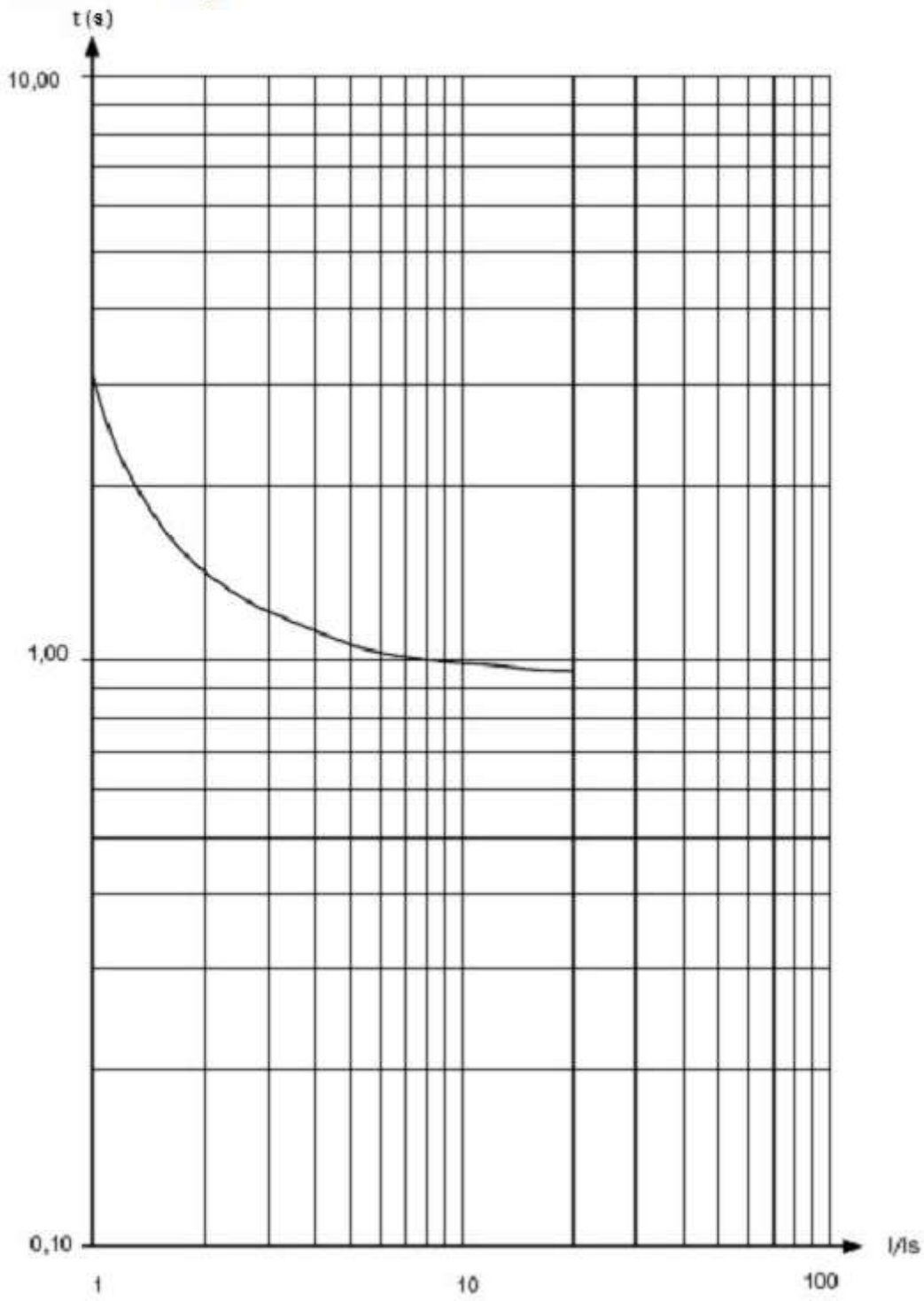
Curve of extreme inverse relation of time delay EIT



Curve of ultimate inverse relation of time delay UIT



Curve of time delay RI



APPENDIX 2 – UBZ-302 operation by the motor in the star/delta switching mode

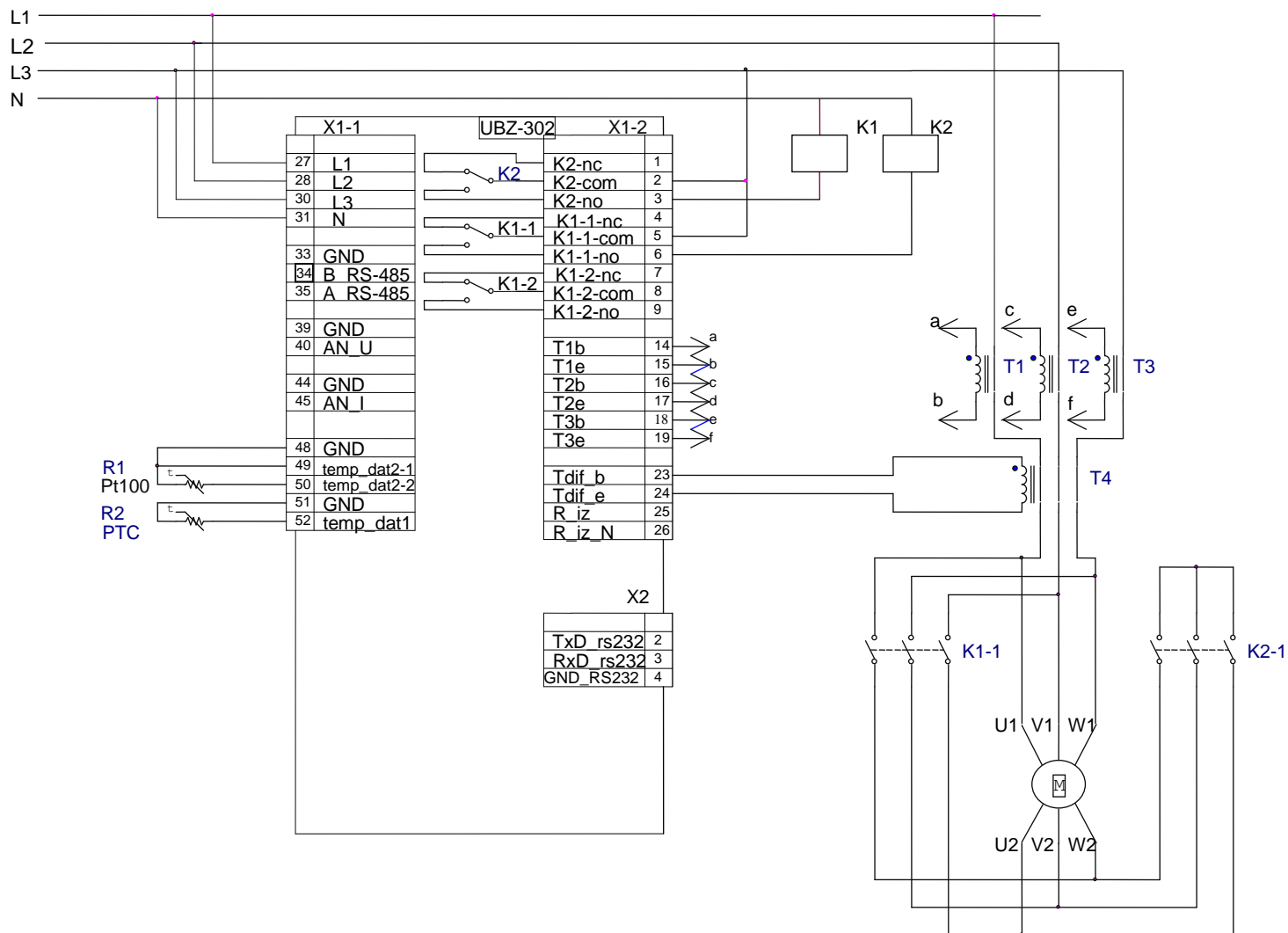
If before the start of the motor it is not necessary to test and check the insulation of the coils to the case of the motor then it's allowed to connect the UBZ-302 according to the simplified scheme shown on **Figure P1** below.

If before the start of the motor it's necessary to test the insulation level of the coils to the motor case then the connection must necessarily be done as shown on **Figure P2**.

When working in the delta/star switching mode the motor could be controlled in a several ways:

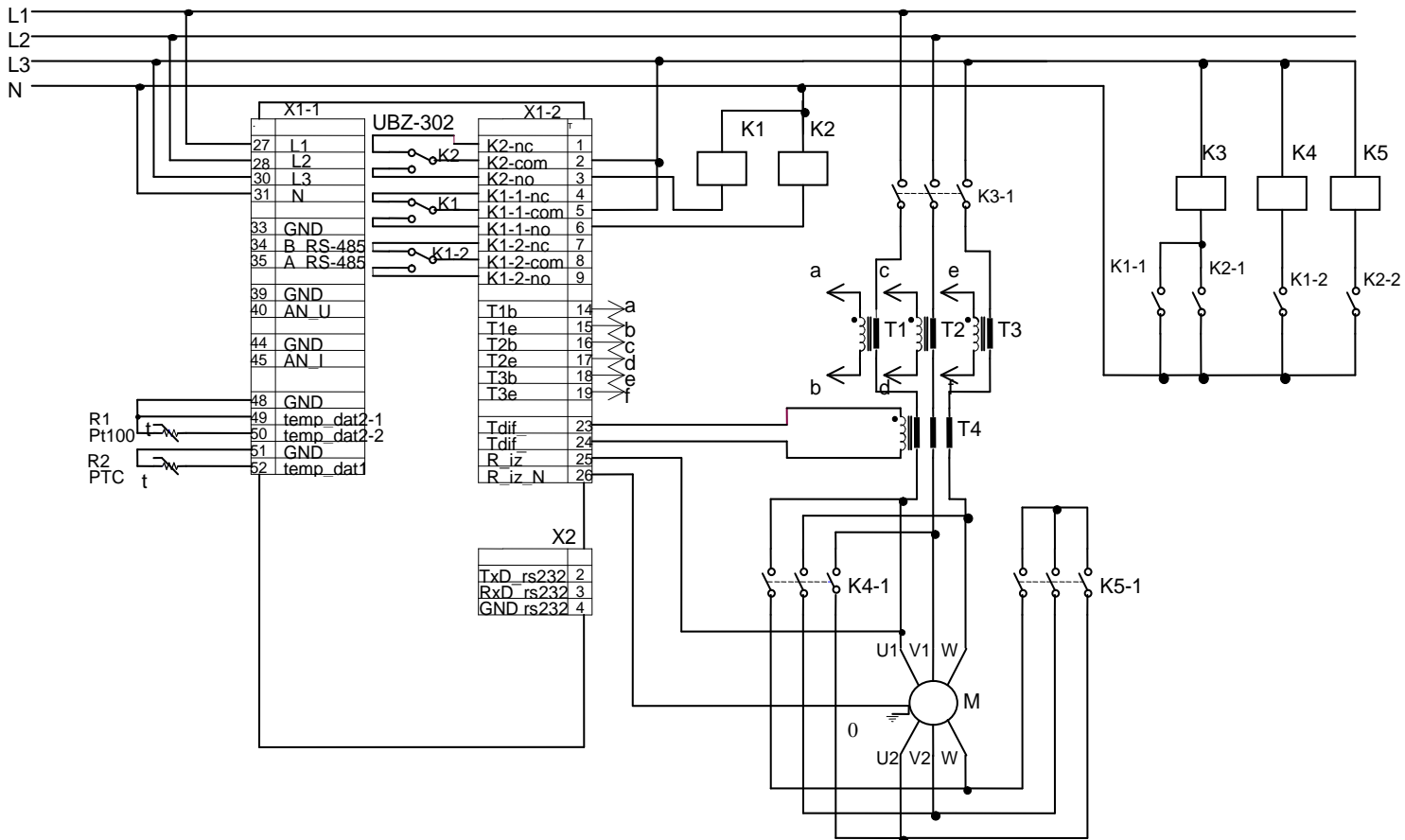
- Turn OFF/ON of the motor by external circuit breaker (contactor) with simultaneous power supply OFF/ON to the input terminals of the **UBZ-302**;
- Operation with the motor from the front panel of the **UBZ-302**;
- Operation with the motor using interface RS-232/RS-485.

ATTENTION!!! It is strictly prohibited to turn OFF the motor by external circuit breaker (contactor) without taking OFF the power supply from the input terminals of the **UBZ-302**. As a very exception it's possible to disconnect first the motor by external breaker (contactor) and then additionally turn the motor OFF from the front panel of the UBZ-302 or alternatively by giving the corresponding remote control command by interface RS-232/RS-485 to avoid the direct start on Delta.



K1 – contactor to turn ON the coils for Delta scheme
 K2- contactor to turn ON the coils for Star scheme

Figure P1 - Wiring diagram for the UBZ-302 for star/delta mode of operation without the control of the coils insulation



- K1- intermediate relay to turn the coils for Delta
- K2 – intermediate relay to turn the coils for Star
- K3- main contactor for starting the motor
- K4 – contactor to turn the coils for Delta
- K5 – contactor to turn the coils for Star

Figure P2 - UBZ-302 Wiring diagram for the Star-Delta operation mode and the control of the coils insulation level