SA 07.2 – SA 16.2

Electrical data multi-turn actuators for open-close duty with 3-phase AC motors

Short-time duty S2 - 15 min, 400 V/50 Hz

Multi-turn actuator			Motor									
Type	Output speed [rpm]	Max. torque [Nm]	Motor type	Nominal power[1] P_N [kW]	Speed [rpm]	Nominal current[2] I_N (A)	Max. current[3] I_{max} [A]	Starting current I_A [A]	cos φ	Overcurr. prot. device setting [A]	AUMA power class for switchgear	
											Contactor	Thyristor
SA 07.2	4	30	VD00063-4-0,02	0.02	1,400	0.4	0.4	1.0	0.40	0.4	A1	B1
	5.6					0.4	0.4	1.0	0.40	0.4	A1	B1
	8		VD00063-4-0,04	0.04	1,400	0.4	0.4	1.0	0.50	0.4	A1	B1
	11					0.4	0.5	1.0	0.50	0.5	A1	B1
	16		VD00063-2-0,06	0.06	2,800	0.6	0.6	1.9	0.42	0.6	A1	B1
	22					0.6	0.7	1.9	0.42	0.7	A1	B1
	32		AD00063-4-0,10	0.10	1,400	1.0	1.0	2.4	0.42	1.0	A1	B1
	45					1.0	1.0	2.4	0.42	1.0	A1	B1
	63		AD00063-2-0,20	0.20	2,800	0.8	1.2	4.4	0.60	1.2	A1	B1
	90					0.8	1.3	4.4	0.60	1.3	A1	B1
	125		AD00063-2-0,30	0.30	2,800	0.9	1.6	4.4	0.70	1.6	A1	B1
	180	25				0.9	1.7	4.4	0.70	1.7	A1	B1
SA 07.6	4	60	VD00063-4-0,03	0.03	1,400	0.4	0.5	1.0	0.43	0.5	A1	B1
	5.6					0.4	0.5	1.0	0.43	0.5	A1	B1
	8		VD00063-4-0,06	0.06	1,400	0.6	0.7	1.6	0.38	0.7	A1	B1
	11					0.6	0.7	1.6	0.38	0.7	A1	B1
	16		VD00063-2-0,12	0.12	2,800	0.7	0.9	3.0	0.52	0.9	A1	B1
	22					0.7	1.0	3.0	0.52	1.0	A1	B1
	32		AD00063-4-0,20	0.20	1,400	1.6	1.9	4.6	0.42	1.9	A1	B1
	45					1.6	2.0	4.6	0.42	2.0	A1	B1
	63		AD00063-2-0,40	0.40	2,800	1.8	2.3	9.0	0.53	2.3	A1	B1
	90					1.8	2.5	9.0	0.53	2.5	A1	B1
	125		AD00063-2-0,50	0.50	2,800	1.9	3.0	9.0	0.62	3.0	A1	B1
	180	50				1.9	3.2	9.0	0.62	3.2	A1	B1
SA 10.2	4	120	VD00071-4-0,06	0.06	1,400	0.5	0.6	2.0	0.40	0.6	A1	B1
	5.6					0.5	0.6	2.0	0.40	0.6	A1	B1
	8		VD00071-4-0,12	0.12	1,400	1.0	1.1	3.0	0.40	1.1	A1	B1
	11					1.0	1.2	3.0	0.40	1.2	A1	B1
	16		VD00071-2-0,25	0.25	2,800	1.3	1.5	4.5	0.52	1.5	A1	B1
	22					1.3	1.8	4.5	0.52	1.8	A1	B1
	32		AD00071-4-0,40	0.40	1,400	2.5	2.6	8.5	0.42	2.6	A1	B1
	45					2.5	3.0	8.5	0.42	3.0	A1	B1
	63		AD00071-2-0,70	0.70	2,800	3.0	4.0	16	0.54	4.0	A1	B1
	90					3.0	4.5	16	0.54	4.5	A1	B1
	125		AD00071-2-1,00	1.00	2,800	3.5	5.4	16	0.64	5.4	A1	B1
	180	100				3.5	6.0	16	0.64	6.0	A1	B1
SA 14.2	4	250	VD00090-4-0,12	0.12	1,400	0.5	0.8	2.8	0.60	0.8	A1	B1
	5.6					0.5	1.0	2.8	0.60	1.0	A1	B1
	8		VD00090-4-0,25	0.25	1,400	1.0	1.6	5.2	0.60	1.6	A1	B1
	11					1.0	1.7	5.2	0.60	1.7	A1	B1
	16		VD00090-2-0,45	0.45	2,800	1.5	3.0	9.0	0.64	3.0	A1	B1
	22					1.5	3.5	9.0	0.64	3.5	A1	B1
	32		AD00090-4-0,75	0.75	1,400	2.6	4.3	16	0.62	4.3	A1	B1
	45					2.6	5.0	16	0.62	5.0	A1	B1
	63		AD00090-2-1,40	1.40	2,800	4.7	7.6	38	0.60	7.6	A2	B2
	90					4.7	9.0	38	0.60	9.0	A2	B2
	125		AD00090-2-1,80	1.80	2,800	5.3	12	38	0.65	11	A2	B2
	180	200				5.3	12	38	0.65	11	A2	B2
SA 14.6	4	500	VD00090-4-0,20	0.20	1,400	0.9	1.5	5.2	0.54	1.5	A1	B1
	5.6					0.9	1.7	5.2	0.54	1.7	A1	B1
	8		VD00090-4-0,40	0.40	1,400	1.8	3.0	9.3	0.56	3.0	A1	B1
	11					1.8	3.5	9.3	0.56	3.5	A1	B1
	16		VD00090-2-0,80	0.80	2,800	3.6	5.0	18	0.51	5.0	A1	B1
	22					3.6	5.5	18	0.51	5.5	A1	B1
	32		AD00090-4-1,60	1.60	1,400	5.3	7.5	38	0.57	7.5	A2	B2
	45					5.3	9.0	38	0.57	9.0	A2	B2
	63		AD00090-2-3,00	3.00	2,800	9.0	14	68	0.60	14	A2	B3
	90					9.0	16	68	0.60	16	A2	B3
	125		AD00090-2-3,30	3.30	2,800	9.5	21	68	0.65	21	A2	B3
	180	400				9.5	22	68	0.65	22	A2	B3
SA 16.2	4	1,000	VD00112-4-0,40	0.40	1,400	1.4	2.7	10	0.65	2.7	A1	B1
	5.6					1.4	2.9	10	0.65	2.9	A1	B1
	8		VD00112-4-0,80	0.80	1,400	3.0	5.2	22	0.57	5.2	A1	B2
	11					3.0	5.5	22	0.57	5.5	A1	B2
	16		VD00112-2-1,50	1.50	2,800	5.6	9.0	40	0.60	9.0	A2	B2
	22					5.6	11	40	0.60	11	A2	B2
	32		AD00112-4-3,00	3.00	1,400	8.5	15	60	0.71	15	A2	B3
	45					8.5	17	60	0.71	17	A2	B3
	63		AD00112-2-5,00	5.00	2,800	12	25	114	0.80	25	A2	–
	90					12	30	114	0.80	25	A2	–
	125	800	AD00112-2-6,00	6.00	2,800	14	35	114	0.83	25	A2	–
	180					14	45	114	0.83	25	A2	–

1) – 3) Refer to Notes on Electrical data SA .2/SAR .2 multi-turn actuators with 3-phase AC motors

Installation and sizing

Motor data

Motor data is approximate. Due to usual manufacturing tolerances, there may be deviations from the values given.

Motor protection

To protect against overheating, thermoswitches or PTC thermistors are embedded in the motor windings.

Actuators without integral actuator controls (AUMA NORM):

Thermoswitches or PTC thermistors have to be considered within the external controls (refer to terminal plan).

Note: Failure to connect thermoswitches or PTC thermistors shall void the warranty for the motor.

Rating of the thermoswitches

AC current		DC current	
250 V, 50 – 60 Hz		60 V	1.0 A
cos φ = 1	2.5 A	42 V	1.2 A
cos φ = 0.6	1.6 A	24 V	1.5 A

Actuators with AM or AC integral actuator controls:

Thermal motor protection is already integrated.

Mains voltage, mains frequency

Permissible variation of mains voltage: ±10 %

Permissible variation of mains frequency: ±5 %

Switchgear sizing

For motor operation, reversing contactors (mechanically, electrically and electronically locked) or thyristors (electronically locked) can be used.

Actuators without integral actuator controls (AUMA NORM):

Switchgear are supplied by the customer. We recommend specification of switchgear suitable for their rated operating power/motor power in compliance with the assigned AUMA power class.

Switchgear assignment to AUMA power classes:

AUMA power class	Reversing contactor Rated operating power acc. to EN 60947-4-1 Utilization category AC-3	Reversing contactor Motor power according to UL/CSA at	
	400 V AC	480 V AC	600 V AC
A1	4.0 kW	5.0 hp	5.0 hp
A2	7.5 kW	10 hp	10 hp
A3	15 kW	20 hp	25 hp
A4	30 kW	60 hp	60 hp
A5	55 kW	75 hp	100 hp
A6	75 kW	100 hp	125 hp

AUMA power class	Thyristor Rated operating current acc. to EN 60947-4-2 Utilization category AC-53a
	400 V AC
B1	6 A
B2	8.5 A
B3	16 A

Actuators with AM or AC integral actuator controls:

Required switchgear in power classes A1 – A3 or B1 – B3 are already integrated in AM or AC actuator controls. For switchgear of power classes A4 – A6, a control box is additionally required.

For actuators with AM integral actuator controls and installed switchgear in AUMA power class A3, an optional thermal overcurrent protection device cannot be directly integrated within the AM. A control box is additionally required. However, AC actuator controls can be used instead of AM actuator controls. When opting for AC actuator controls, the additional control box can be omitted.

Notes on Electrical data SA .2/SAR .2 multi-turn actuators with 3-phase AC motors

1) Nominal power P_N

Mechanical power output at motor shaft at run torque of multi-turn actuator (corresponds to approx. 35 % of maximum torque).

The consumed electrical power can be calculated using the following formula:

$P = U \times I \times \cos \varphi \times \sqrt{3}$

2) Nominal current I_N

Current at run torque at approx. 35 % of maximum torque

3) Max. current I_{max}

Current at maximum torque